Outline of this section

- Overview of Transfer Learning
- 2 Categorization
- Applications
- 4 Conclusion

What is Transfer Learning?[Pan and Yang, 2010]

Naive View (Transfer Learning)

Transfer Learning (i.e. Knowledge Transfer, Domain Adaption) aims at applying knowledge learned **previously** to solve **new** problems faster or with better solutions.

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- What to "Transfer"?
- How to "Transfer"?
- When to "Transfer"?

Transfer Learning

- Machine Learning Scheme.
- Relationship with other ML tech?

What is Transfer Learning? (Cont.)



Supervised Classification



Semi-supervised Learning



Transfer Learning

Figure: Supervised classification uses labeled examples of elephants and rhinos; semi-supervised learning uses additional unlabeled examples of elephants and rhinos; transfer learning uses additional labeled datasets[Raina et al., 2007].

Motivation

Why we need Transfer Learning[Tang et al., 2012]?

- Labeled data are expensive and limited.
- Related data are cheap and sufficient.

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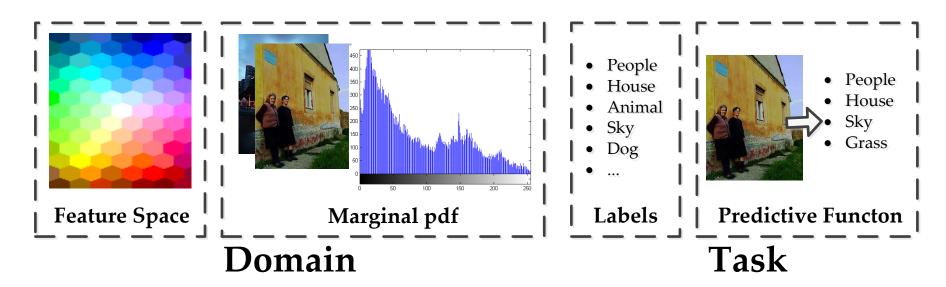
Figure: Object detector for static image is easy to obtain. However, the labeled data for video task are limited and expensive.

Terminologies

- **Domain**: A domain $\mathcal{D} = \{\mathcal{X}, P(X)\}$ consists of two components: a feature space \mathcal{X} and a marginal prob distribution $P(X), X \in \mathcal{X}$.
- **Task**: Given a spefic domain, a task $\mathcal{T} = \{\mathcal{Y}, f(\cdot)\}$ also consists of two components: a label space \mathcal{Y} and the predictive function $f(\cdot) = P(y|x)$. The predictive is unknown for us but can be learned from training data, which consists of data pair (x_i, y_i) .

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Terminologies (Cont.)

• Source/Target Domain Data: a set of labeled data D_S and D_T

$$D_S = \{(x_{S_1}, y_{S_1})...(x_{S_{n_S}}, y_{S_{n_S}})\}, D_T = \{(x_{T_1}, y_{T_1})...(x_{T_{n_T}}, y_{T_{n_T}})\}$$

In most cases, $0 \le n_T \ll n_S$.

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In most cases, $0 \le n_T \ll n_S$.

Definition (Transfer Learning)

Given a source domain \mathcal{D}_S and learning task \mathcal{T}_S , a target domain \mathcal{D}_T and learning task \mathcal{T}_T , **transfer learning** aims to help improve the learning of the target predictive function $f_T(\cdot)$ in \mathcal{D}_T using the knowledge in \mathcal{D}_S and \mathcal{T}_S , where $\mathcal{D}_S \neq \mathcal{D}_T$ or $\mathcal{T}_S \neq \mathcal{T}_T$.

Transfer of Learning

A psychological point of view

- The study of dependency of human conduct, learning or performance on prior experience.
 - [Thorndike and Woodworth, 1901] explored how individuals would transfer in one context to another context that share similar characteristics.
- \triangleright C++ \rightarrow Java
- ➤ Maths/Physics → Computer Science/Economics



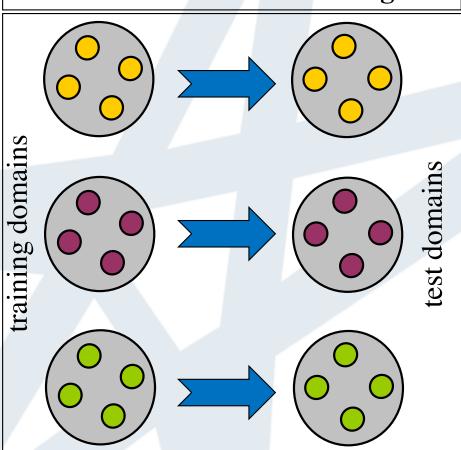
Transfer Learning

In the machine learning community

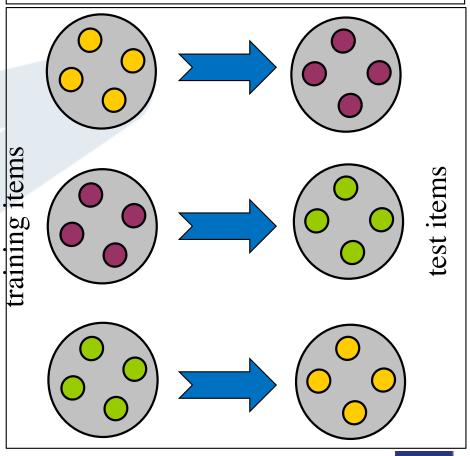
- The ability of a system to recognize and apply knowledge and skills learned in previous domains/tasks to novel tasks/domains, which share some commonality.
- Given a target domain/task, how to identify the commonality between the domain/task and previous domains/tasks, and transfer knowledge from the previous domains/tasks to the target one?

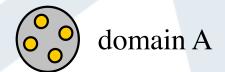
Transfer Learning

Traditional Machine Learning



Transfer Learning





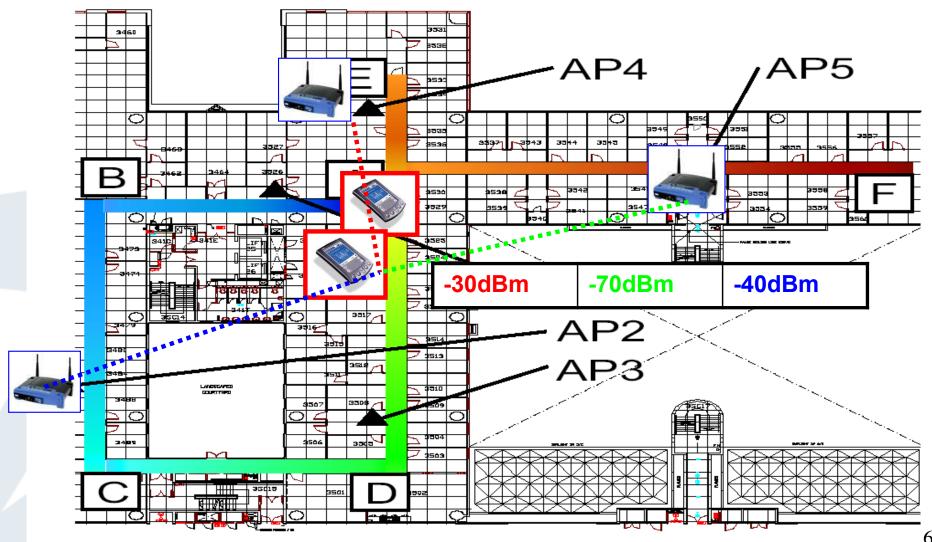






Motivating Example I:

Indoor WiFi localization



Indoor WiFi Localization (cont.)



S=(-37dbm, .., -77dbm), L=(1, 3) S=(-41dbm, .., -83dbm), L=(1, 4)

S=(-49dbm, .., -34dbm), L=(9, 10) S=(-61dbm, ..., -28dbm), L=(15,22)



Localization model



Test

S=(-37dbm, .., -77dbm) S=(-41dbm, .., -83dbm)

S=(-49dbm, .., -34dbm) S=(-61dbm, ..., -28dbm)

Device A







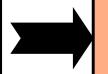
Training

S=(-33dbm, .., -82dbm), L=(1, 3)

S=(-57dbm, .., -63dbm), L=(10, 23)



Localization model



Test

S=(-37dbm, .., -77dbm)

S=(-41dbm, .., -83dbm)

S=(-49dbm, .., -34dbm)

S=(-61dbm, .., -28dbm)

~10 meters

Average Error

Distance

1.5 meters

Device B









Motivating Example II:

Sentiment classification

10 hours ago

Edward Priz * replied:



You know, this isn't the first time that "States Rights" has been used as a cover for racist policies. In fact, the whole "States Rights" thing has become a sort of code for heavy-handed racist policies, hasn't it? And it does provide a sort of contextual

10 hours ago

RICH HIRTH * replied:



The issue here is probable cause. A police officer can question if he has probable cause, and he can document it. This law can be abused if being Latino is probable cause. That is license to

harace for the notice. As long as the law is annied fairly there

2 hours ago

Julia Gomez replied:



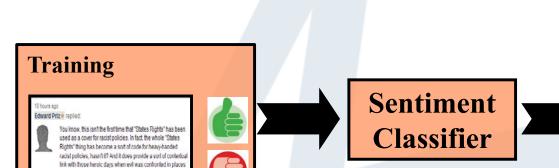
The Arizona law is so clearly unconstitutional that I do not think it will ever reach the point of being enforced. The article did not say so, but the Republican governor is afraid of a GOP primary electorate that is even more reactionary than usual. That is why she signed the bill, not because she thinks it is legally defensible.







Sentiment Classification (cont.)



Classification Accuracy

~ 84.6%



Electronics



Training

Electronics

10 hours ago RICH HIRTH # replied



The issue here is probable cause. A police officer can question if he has probable cause, and he can document. This law can be abused if being Lation is probable cause. That is included to harass for the police. As long as the law is applied faith, there should not be a problem. As far as documentation, Most states have laws that officers must carry and date (i), and no one cares. There is no reason the Executive branch needed to get involved in what the Court should decide.

like Selma and Little Rock, doesn't it? Thanks for making that





Sentiment Classifier





Test

10 hours ago

Edward Priz * replied:

10 hours ago

Edward Priz * replied:



You know, this isn't the first time that "States Rights" has been used as a cover for racist prolices in flat, the whole "States Rights" thing has become a sort of code for heavy-handed racist profices, hearn it? And it does provide a sort of contentual link with those heroic days when evil was confronted in places like Sehma and Little Rock, doesn't it? Thanks for making that link would.

You know, this isn't the first time that "States Rights" has been

racist policies, hasn't it? And it does provide a sort of contextual

link with those heroic days when evil was confronted in places

like Selma and Little Rock, doesn't it? Thanks for making that

used as a cover for racist policies. In fact, the whole "States

Rights" thing has become a sort of code for heavy-handed

~72.65%

DVD





Electronics





Difference between Domains

	Electronics	Video Games	
	(1) Compact; easy to operate;	(2) A very good game! It is	
	very good picture quality;	action packed and full of	
	looks sharp!	excitement. I am very much	
		hooked on this game.	
	(3) I purchased this unit from	(4) Very realistic shooting	
	Circuit City and I was very	action and good plots. We	
	excited about the quality of the	played this and were hooked .	
	picture. It is really nice and		
	sharp.		
	(5) It is also quite blurry in	(6) The game is so boring . I	
(3)	very dark settings. I will never	am extremely unhappy and will	
(a	buy HP again.	probably never buy UbiSoft	
		again.	

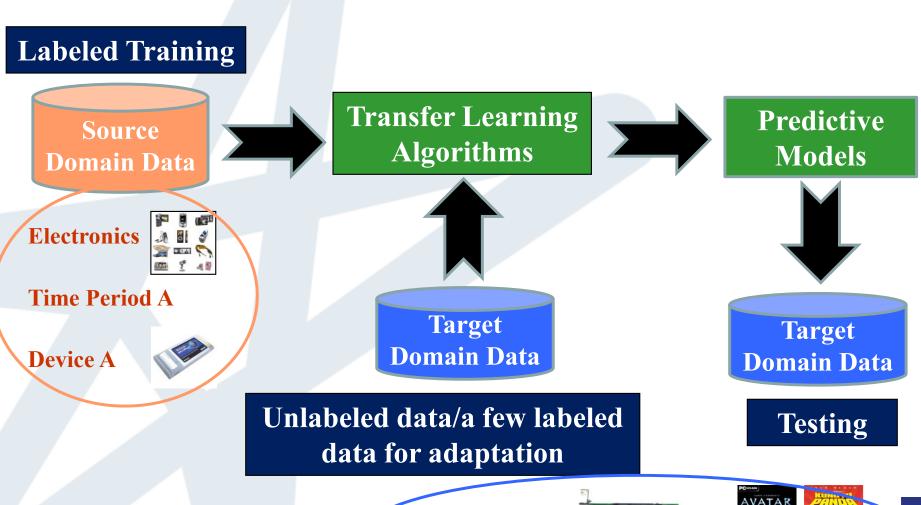
How to Build Systems on Each Domain of Interest

- ➤ Build every system from scratch?
 - ☐ Time consuming and expensive!

- ➤ Reuse common knowledge extracted from existing systems?
 - ☐ More practical!



The Goal of Transfer Learning



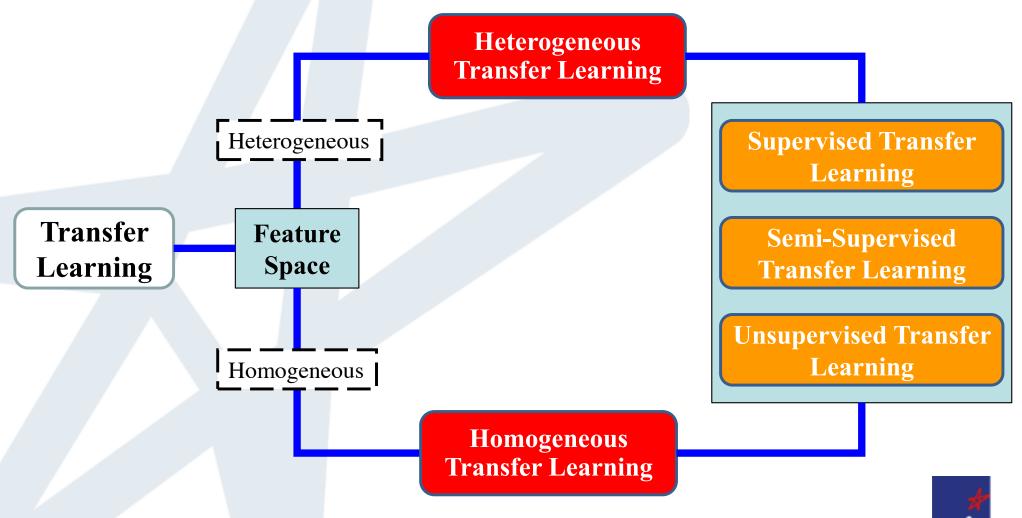
Time Period B







Transfer Learning Settings



Transfer Learning Approaches

Instance-based Approaches

Feature-based Approaches

Parameter-based Approaches

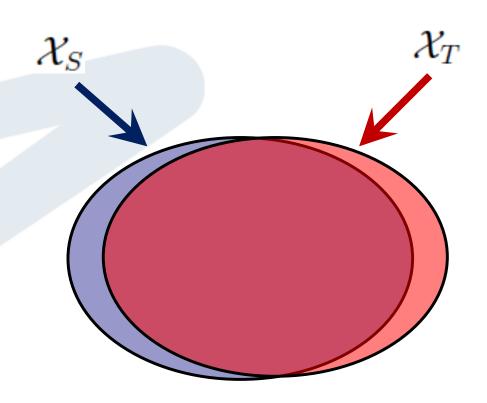
Relational Approaches



Instance-based Transfer Learning Approaches

General Assumption

Source and target domains have a lot of overlapping features (domains share the same/similar support)





Instance-based Transfer Learning Approaches

Case I

Problem Setting

Given $D_S = \{x_{S_i}, y_{S_i}\}_{i=1}^{n_S}, D_T = \{x_{T_i}\}_{i=1}^{n_T},$

Learn f_T , s.t. $\sum_i \epsilon(f_T(x_{T_i}), y_{T_i})$ is small,

where y_{T_i} is unknown.

Assumption

- $\mathcal{Y}_S = \mathcal{Y}_T$, and $P(Y_S|X_S) = P(Y_T|X_T)$,
- $\mathcal{X}_S \approx \mathcal{X}_T$,
- $P(X_S) \neq P(X_T)$.

Case II

Problem Setting

Given $D_S = \{x_{S_i}, y_{S_i}\}_{i=1}^{n_S}$,

 $\mathbf{D}_T = \{x_{T_i}, y_{T_i}\}_{i=1}^{n_T}, \ n_T \ll n_S,$

Learn f_T , s.t. $\epsilon(f_T(x_{T_i}), y_{T_i})$ is small, and

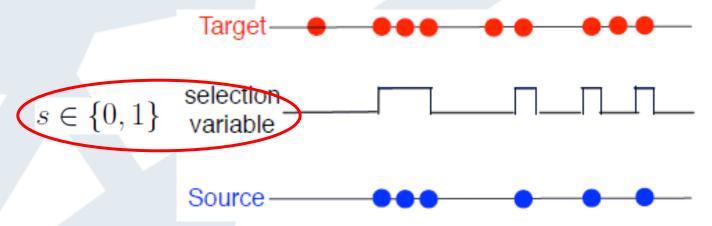
 f_T has good generalization on unseen x_T^* .

Assumption

• $\mathcal{Y}_S = \mathcal{Y}_T$, but $f_S \neq f_T \ (P_S(y|x) \neq P_T(y|x))$.

Correcting sample selection bias

• Imagine a *rejection* sampling process, and view the source domain as samples from the target domain



Assumption: sample selection bias is caused by the data generation process 26



Correcting sample selection bias (cont.)

• The distribution of the selector variable maps the target onto the source distribution

$$P_S(x) \propto P_T(x)P(s=1|x)$$

$$\beta(x) = \frac{P_T(x)}{P_S(x)} \propto \frac{1}{P(s=1|x)}$$

[Zadrozny, ICML-04]

- ➤ Labeled instances from the source domain with label 1
- > Unlabeled instances from the target domain with label 0
- > Train a binary classifier



correcting sample selection bias(cont.)

• Use $\beta(x)$ to train a binary classifier. The classifier is regarded as the selection variable mentioned above.

• Put the labeled data in source domain and the unlabeled data in target domain together. Use the classifier to resample the data.

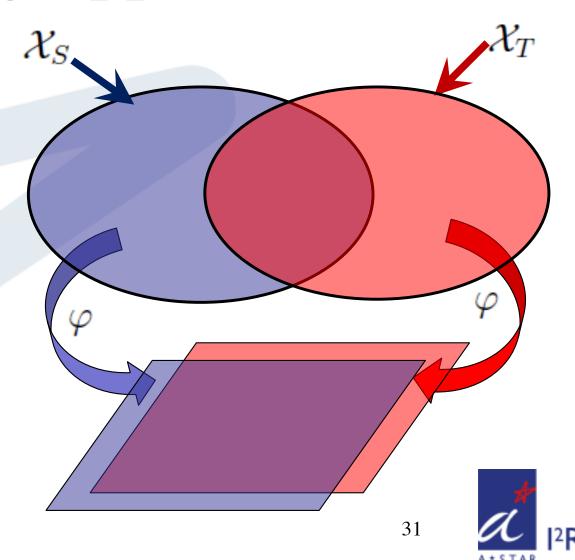
correcting sample selection bias(cont.)

 Now we get a new sample subset of source domain data. The sample selection bias has been corrected in the new subset. Data in the sample subset and the target domain follow the same distribution.

We can train our model on the sample subset of source domain data.
 Then directly use the model on target domain data.

Feature-based Transfer Learning Approaches

When source and target domains only have some overlapping features. (lots of features only have support in either the source or the target domain)



Encode application-specific knowledge

-			
	Electronics	Video Games	
	(1) Compact; easy to operate;	(2) A very good game! It is	
	very good picture quality;	action packed and full of	
	looks sharp!	excitement. I am very much	
		hooked on this game.	
	(3) I purchased this unit from	(4) Very realistic shooting	
	Circuit City and I was very	action and good plots. We	
	excited about the quality of the	played this and were hooked .	
	picture. It is really nice and		
	sharp.		
	(5) It is also quite blurry in	(6) The game is so boring . I	
	very dark settings. I will	am extremely unhappy and will	
(a)	never_buy HP again.	probably never_buy UbiSoft	
		again.	

Encode application-specific knowledge (cont.)

Electronics

compact	sharp	blurry	hooked	realistic	boring
1	1	0	0	0	0
0	1	0	0	0	0
0	0	1	0	0	0



Training

$$y = f(x) = \text{sgn}(w \cdot x^T), \quad w = [1, 1, -1, 0, 0, 0]$$



Video Game

	compact	sharp	blurry	hooked	realistic	boring
	0	0	0	1	0	0
	0	0	0	1	1	0
()	0	0	0	0	0	1



Encode application-specific knowledge (cont.)

	Electronics	Video Games
	(1) Compact; easy to operate;	(2) A very good game! It is
	very good picture quality;	action packed and full of
	looks sharp!	excitement. I am very much
		hooked on this game.
	(3) I purchased this unit from	(4) Very realistic shooting
	Circuit City and I was very	action and <i>good</i> plots. We
	excited about the quality of the	played this and were hooked .
	picture. It is really <i>nice</i> and	
	sharp.	
	(5) It is also quite blurry in	(6) The game is so boring . I
	very dark settings. I will	am extremely unhappy and
A	never buy HP again.	will probably never buy
		UbiSoft again.

Encode application-specific knowledge (cont.)

- > Three different types of features
 - Source domain (*Electronics*) specific features, e.g., compact, sharp, blurry
 - Target domain (*Video Game*) specific features, e.g., hooked, realistic, boring
 - Domain independent features (pivot features), e.g., good, excited, nice, never_buy



Spectral Feature Alignment (SFA)

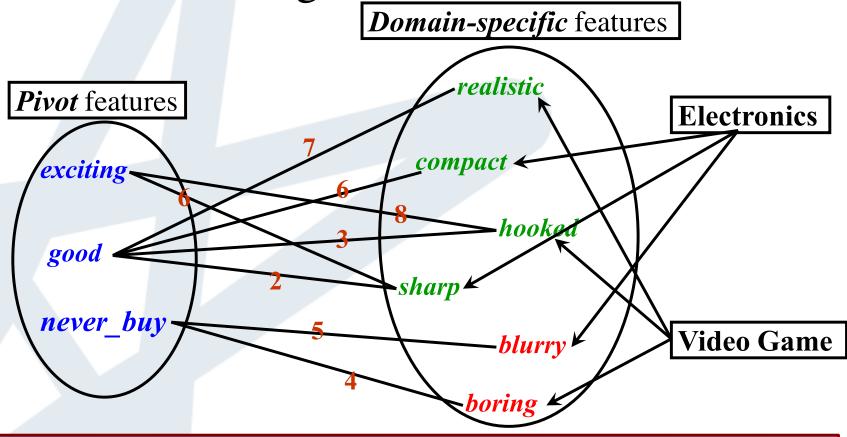
> Intuition

- ☐ Use a *bipartite* graph to model the correlations between *pivot* features and other features
- ☐ Discover new shared features by applying *spectral clustering* techniques on the graph

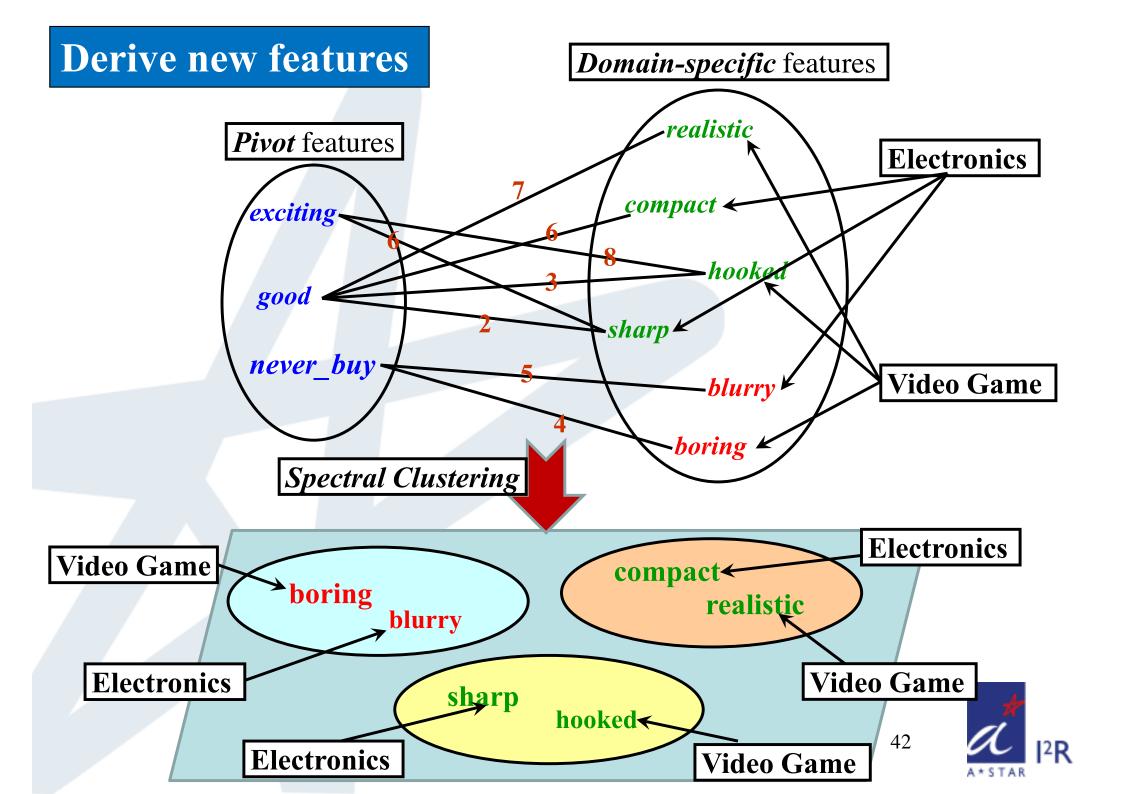


Spectral Feature Alignment (SFA)

High level idea



- ➤ If two *domain-specific* words have connections to more common *pivot* words in the graph, they tend to be aligned or clustered together with a higher probability.
- ➤ If two *pivot* words have connections to more common *domain-specific* words in the graph, they tend to be aligned together with a higher probability.



Spectral Feature Alignment (SFA)

Derive new features (cont.)

Electronics

sharp/hooked compact/realistic		blurry/boring	
1	1	0	
1	0	0	
0	0	1	



$$y = f(x) = \text{sgn}(w \cdot x^T), \quad w = [1, 1, -1]$$



Video Game

sharp/hooked	compact/realistic	blurry/boring
1	0	0
1	1	0
0	0	1

Spectral Feature Alignment (SFA) Algorithm

- ➤ Identify *P pivot* features
- Construct a *bipartite* graph between the pivot and remaining features.
- > Apply *spectral clustering* on the graph to derive new features
- Train classifiers on the source using *augmented* features (original features + new features)



Parameter-based Transfer Learning Approaches

Assume
$$f(x) = \langle \theta, x \rangle = \theta^{\top} x = \sum_{i=1}^{m} \theta_i x_i$$
, where $\theta, x \in \mathbb{R}^m$.

$$\theta_S^* = \arg\min \sum_{i=1}^{n_S} l(x_{S_i}, y_{S_i}, \theta_S) + \lambda \Omega(\theta_S),$$

$$\theta_T^* = \arg\min \sum_{i=1}^{n_T} l(x_{T_i}, y_{T_i}, \theta_T) + \lambda \Omega(\theta_T)$$

Tasks are learned independently

Motivation: A well-trained model θ_S^* has learned a lot of structure. If two tasks are related, this structure can be transferred to learn θ_T^* .

Parameter-based Approaches

Multi-task Parameter Learning

Assumption:

If tasks are related, they may share similar parameter vectors. For example, [Evgeniou and Pontil, KDD-04]

Common part

$$\theta_S = \theta_0 + v_S$$

$$\theta_T = \theta_0 + v_T$$

Specific part for individual task

$$\{\theta_S^*, \ \theta_T^*\} = \arg\min \sum_{t \in \{S,T\}} \sum_{i=1}^n l(x_{t_i}, y_{t_i}, \theta_t) + \lambda \Omega(\theta_0, v_S, v_T)$$

Relational Transfer Learning Approaches

➤ Motivation: If two relational domains (data is non-i.i.d) are related, they may share some similar relations among objects. These relations can be used for knowledge transfer across domains.

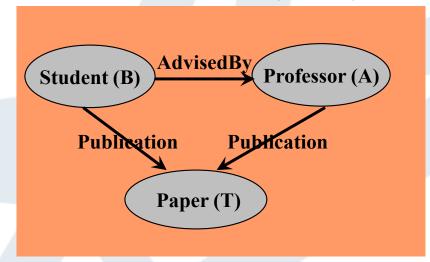


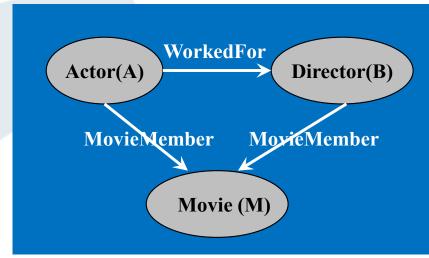
Relational Transfer Learning Approaches (cont.)

[Mihalkova etal., AAAI-07, Davis and Domingos, ICML-09]

Academic domain (source)

Movie domain (target)





AdvisedBy $(B, A) \land Publication (B, T)$ => Publication (A, T) WorkedFor (A, B) ∧ MovieMember (A, M) => MovieMember (B, M)





 $P1(x, y) \land P2(x, z) \implies P2(y, z)$



Summary

Heterogeneous Transfer Learning **Supervised Transfer** Learning Transfer **Semi-Supervised** Learning **Transfer Learning** Unsupervised **Transfer Learning** Homogeneous **Transfer Learning**

In data level **Instance-based Approaches Feature-based Approaches** Relational **Approaches** Parameter-based Approaches

71

In model level

Thank You

