Deep Computer Vision

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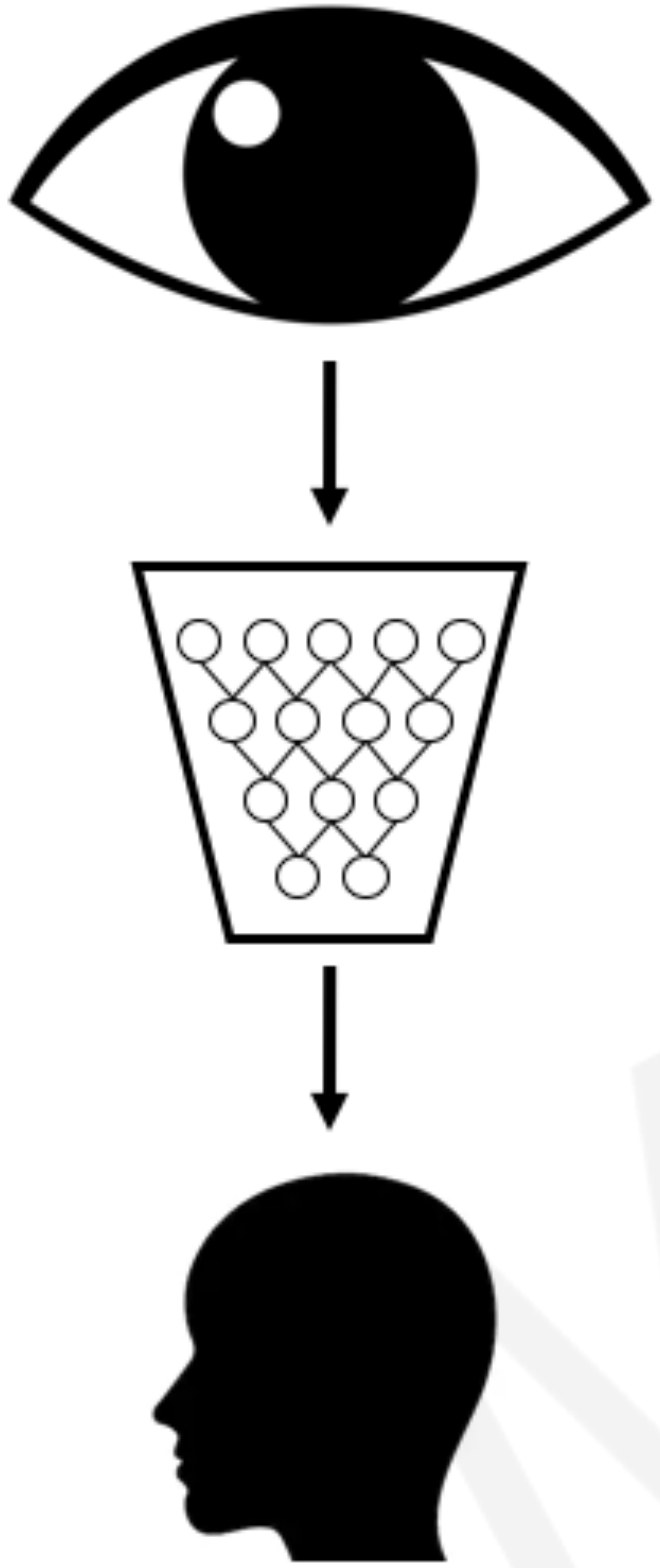
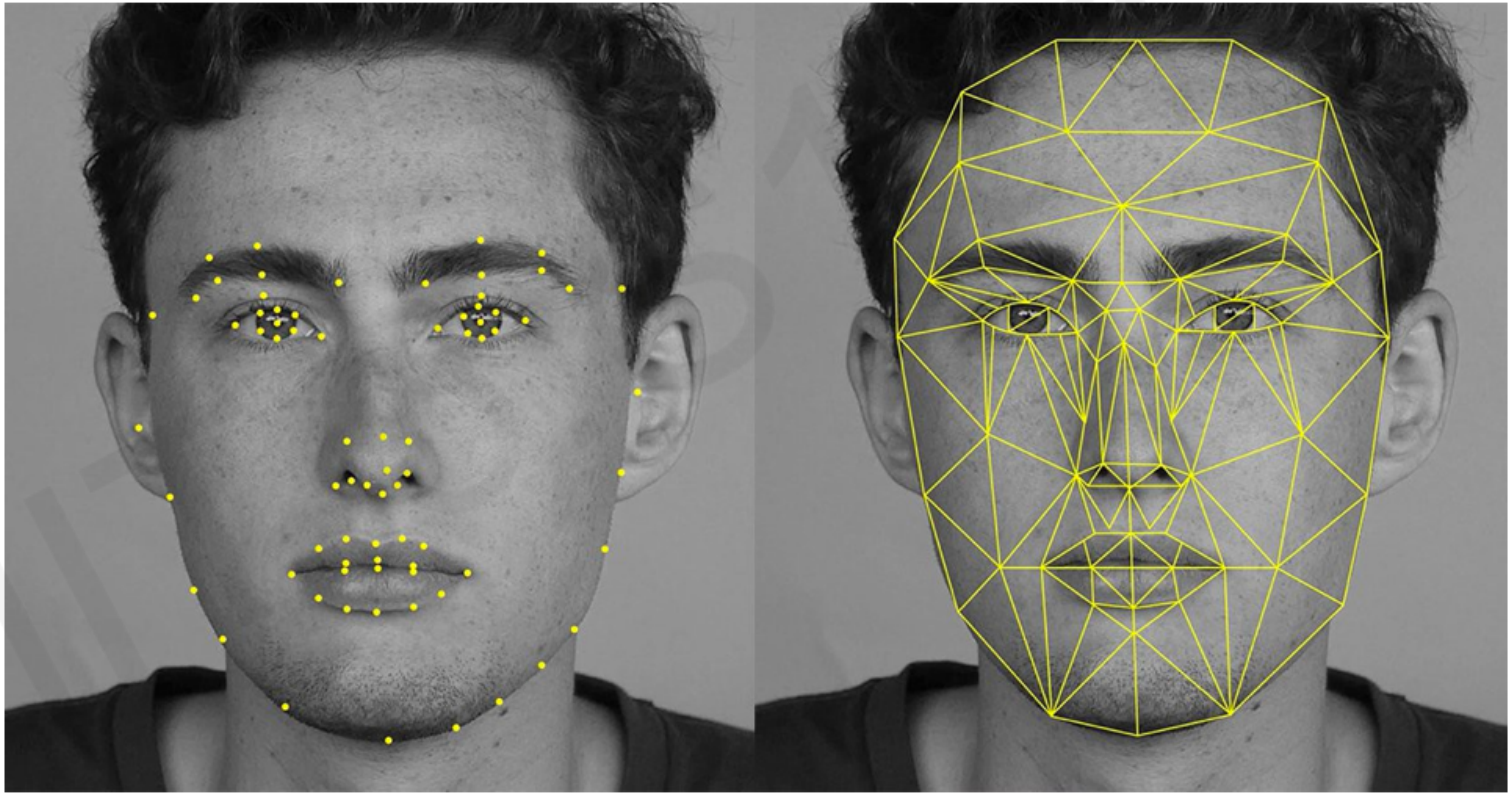
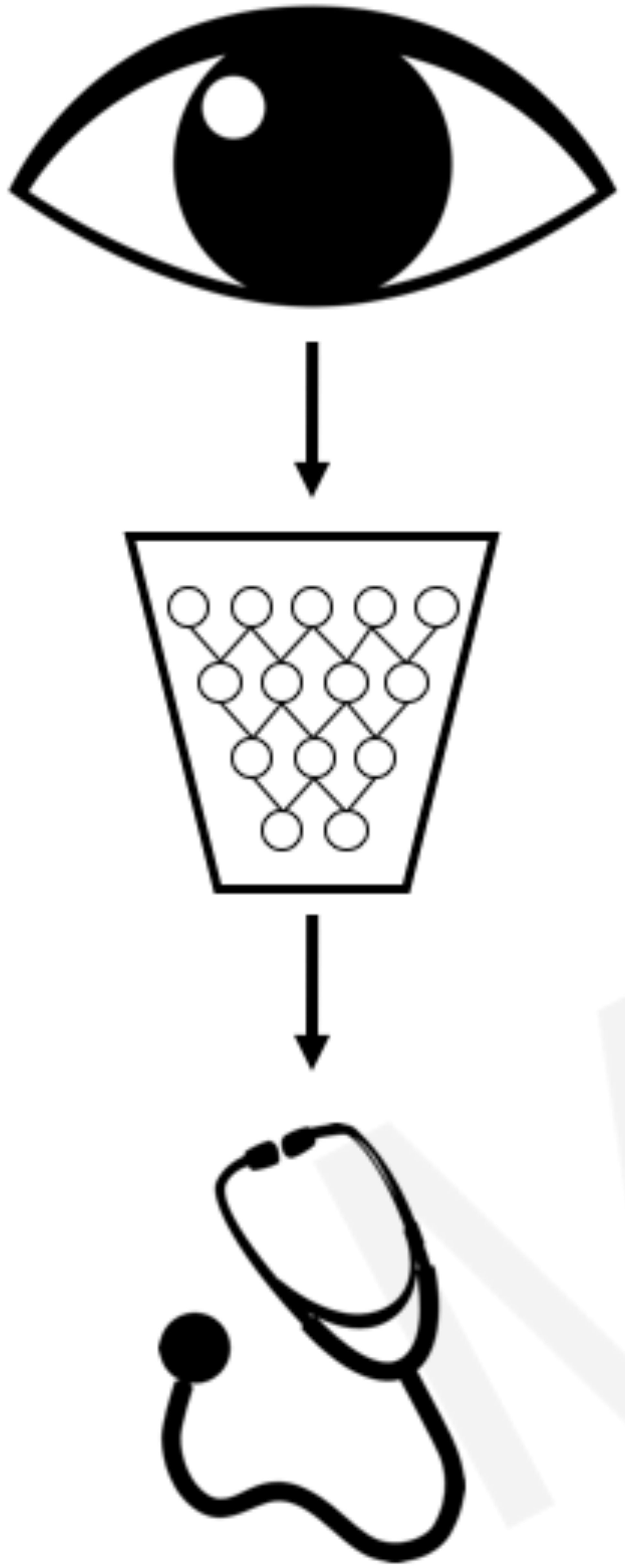
January 28, 2020

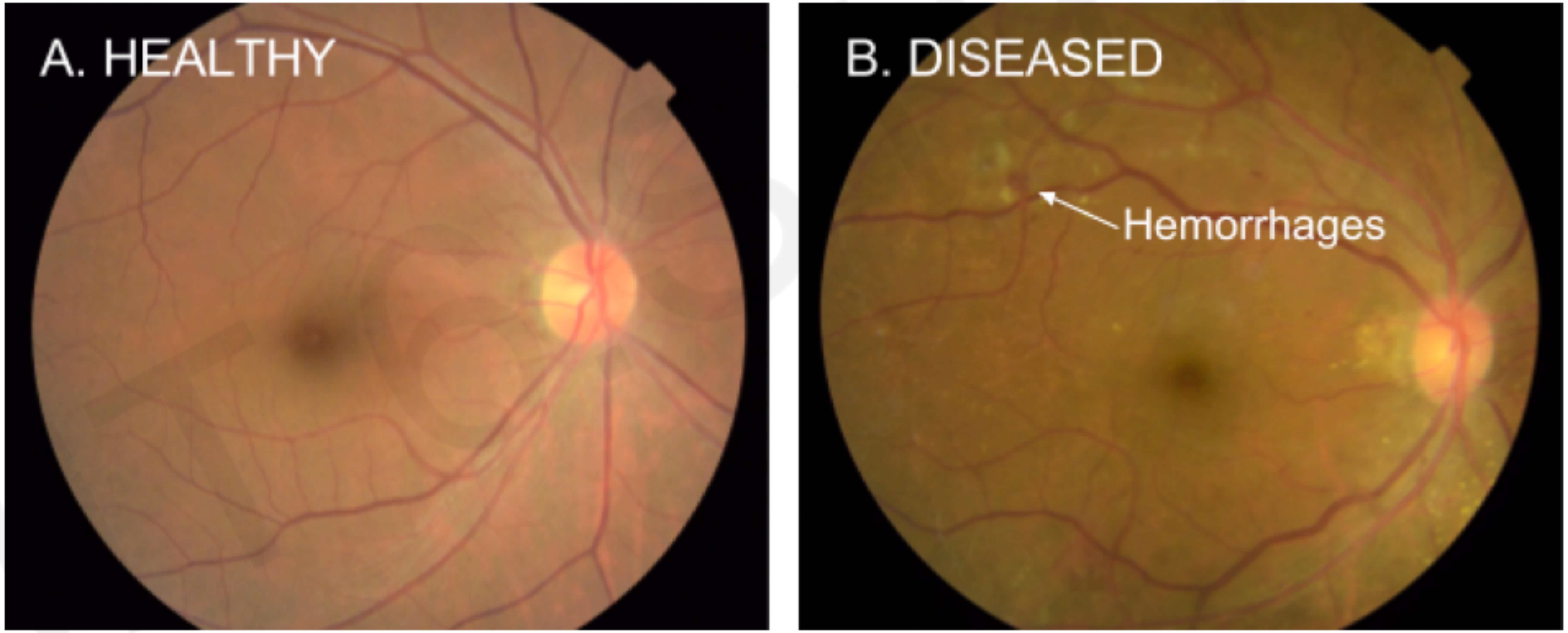
Impact: Facial Detection & Recognition



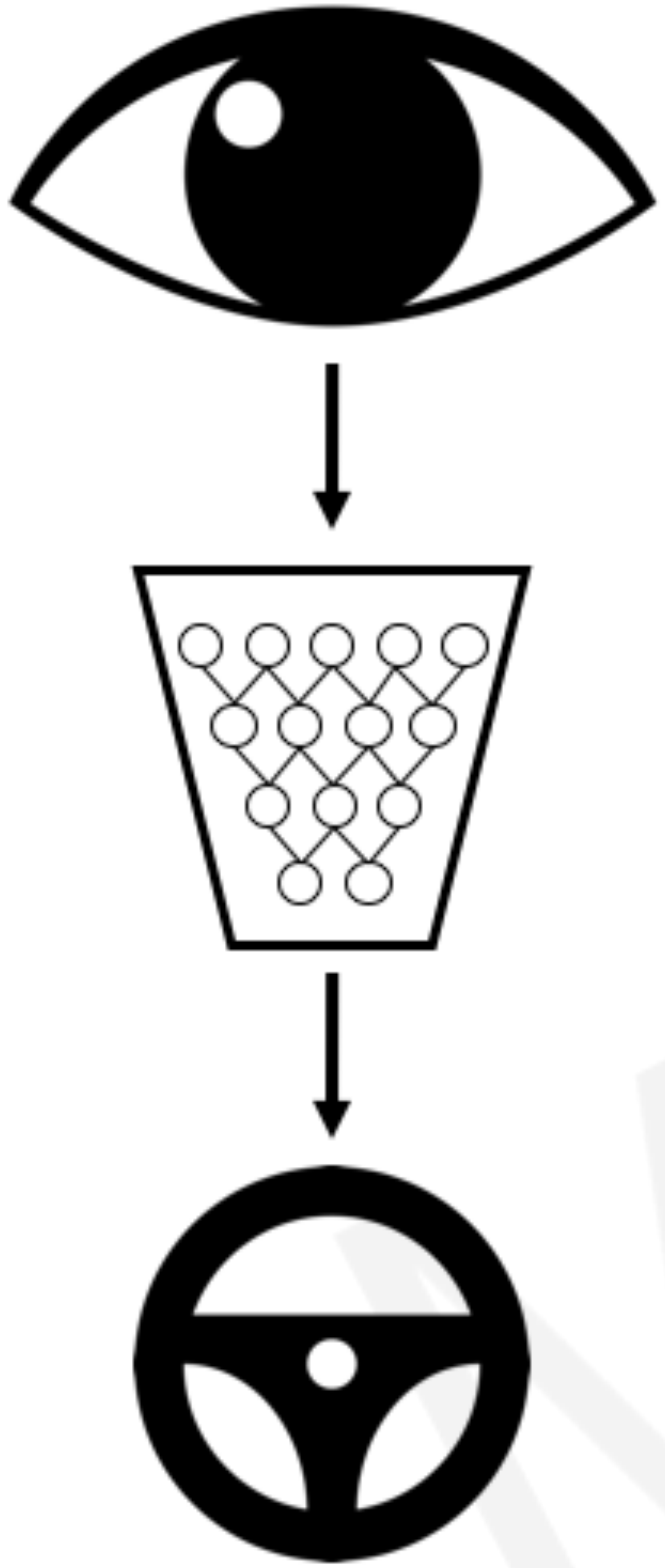


Impact: Medicine, Biology, Healthcare



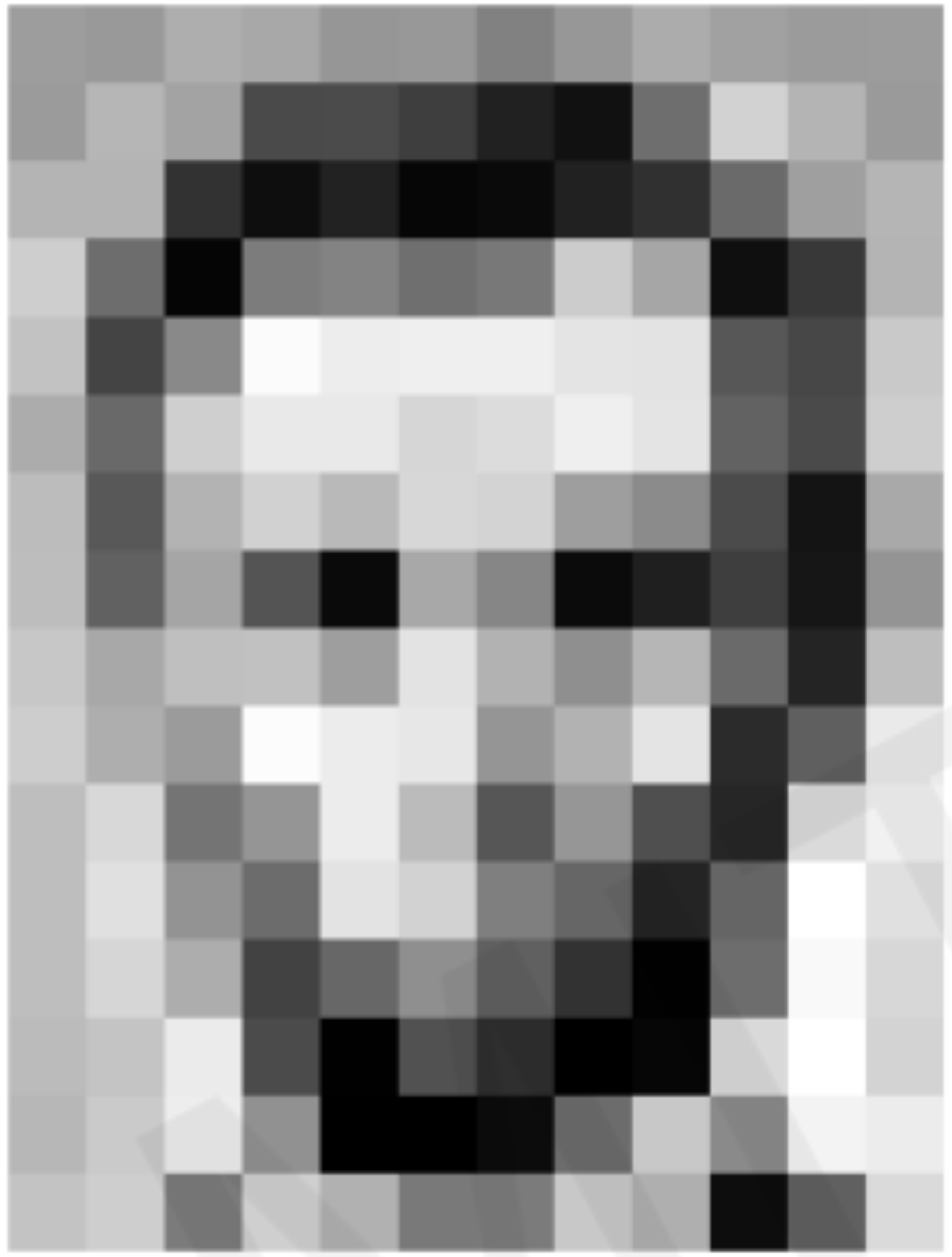


Impact: Self-Driving Cars

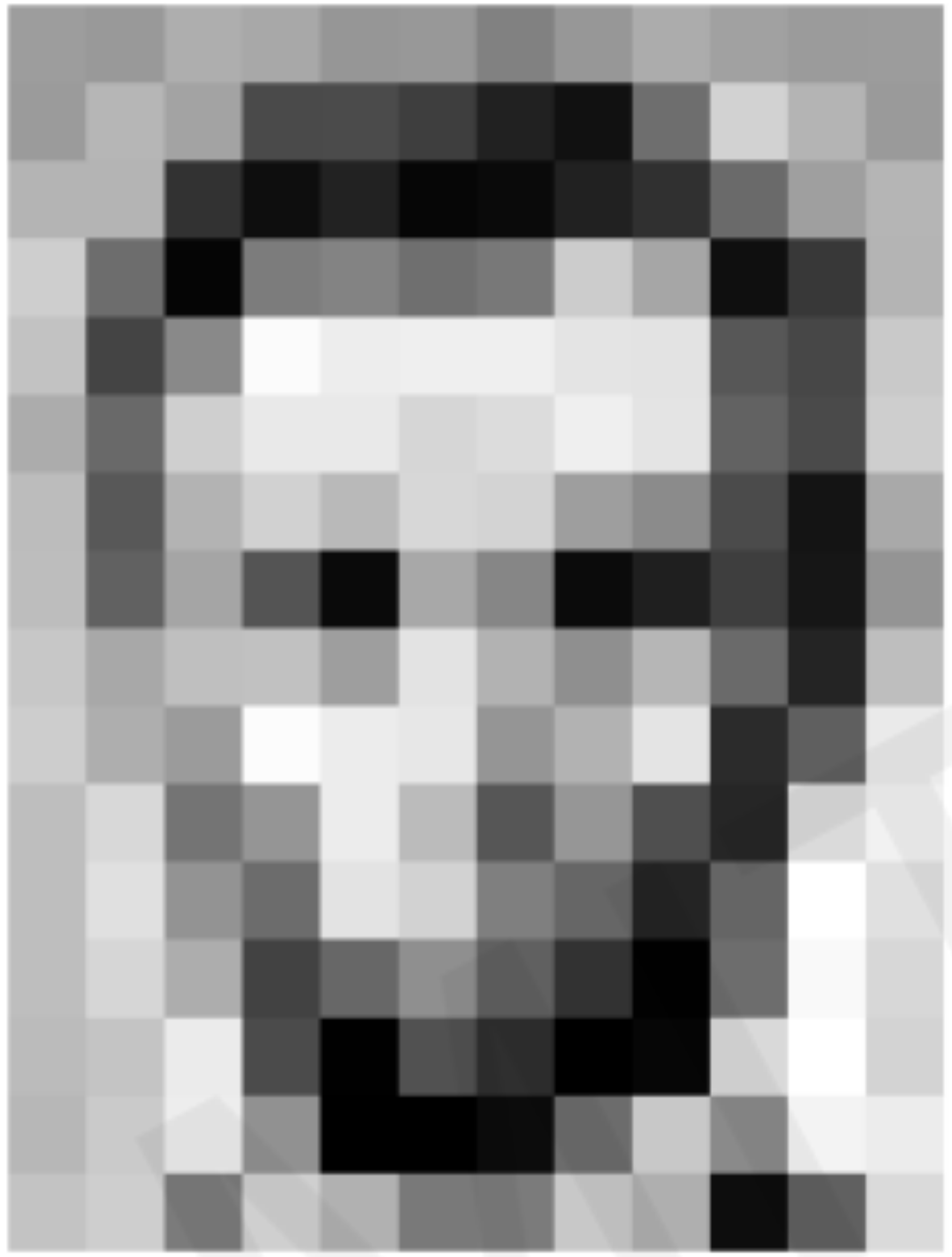


What Computers “See”

Images are Numbers

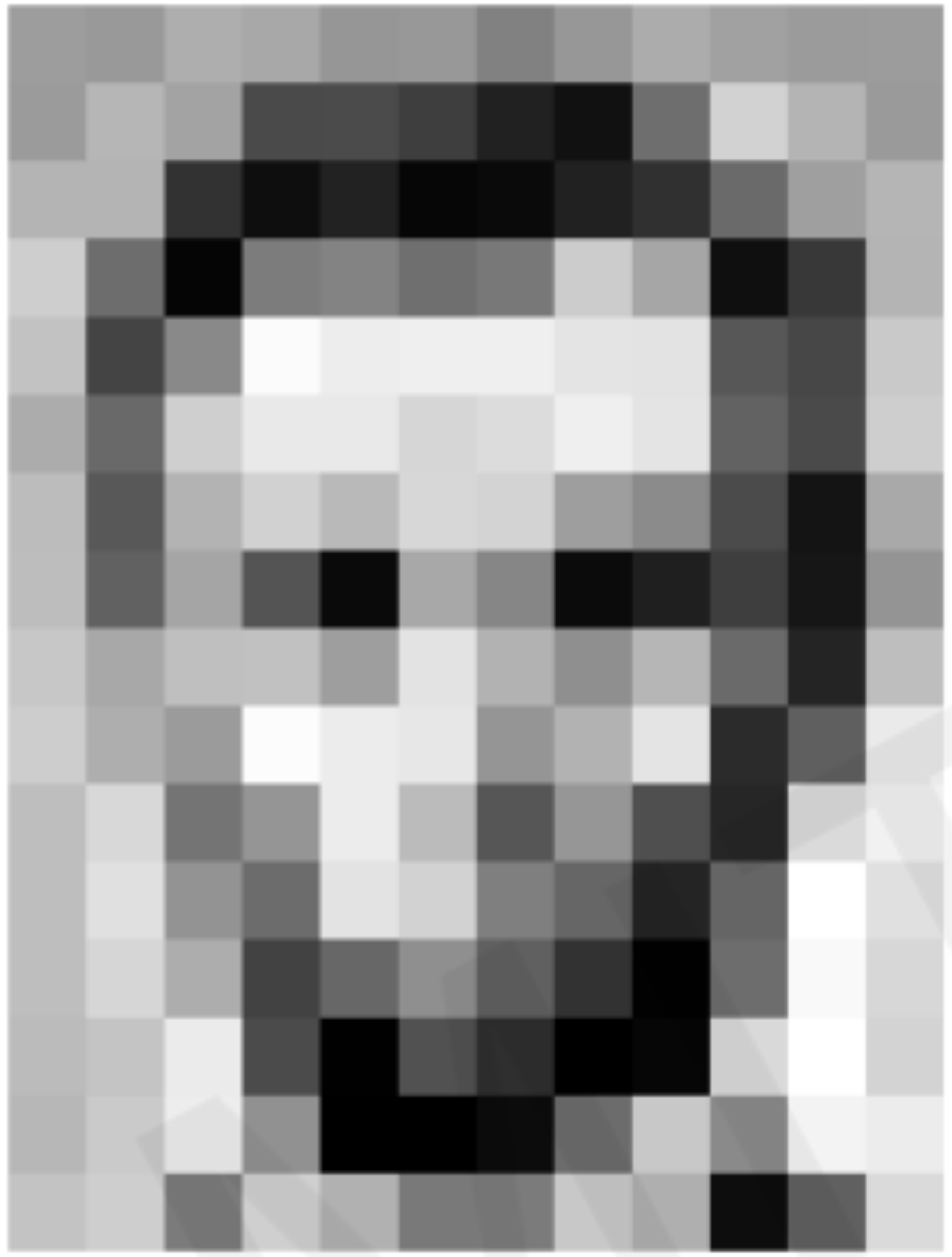


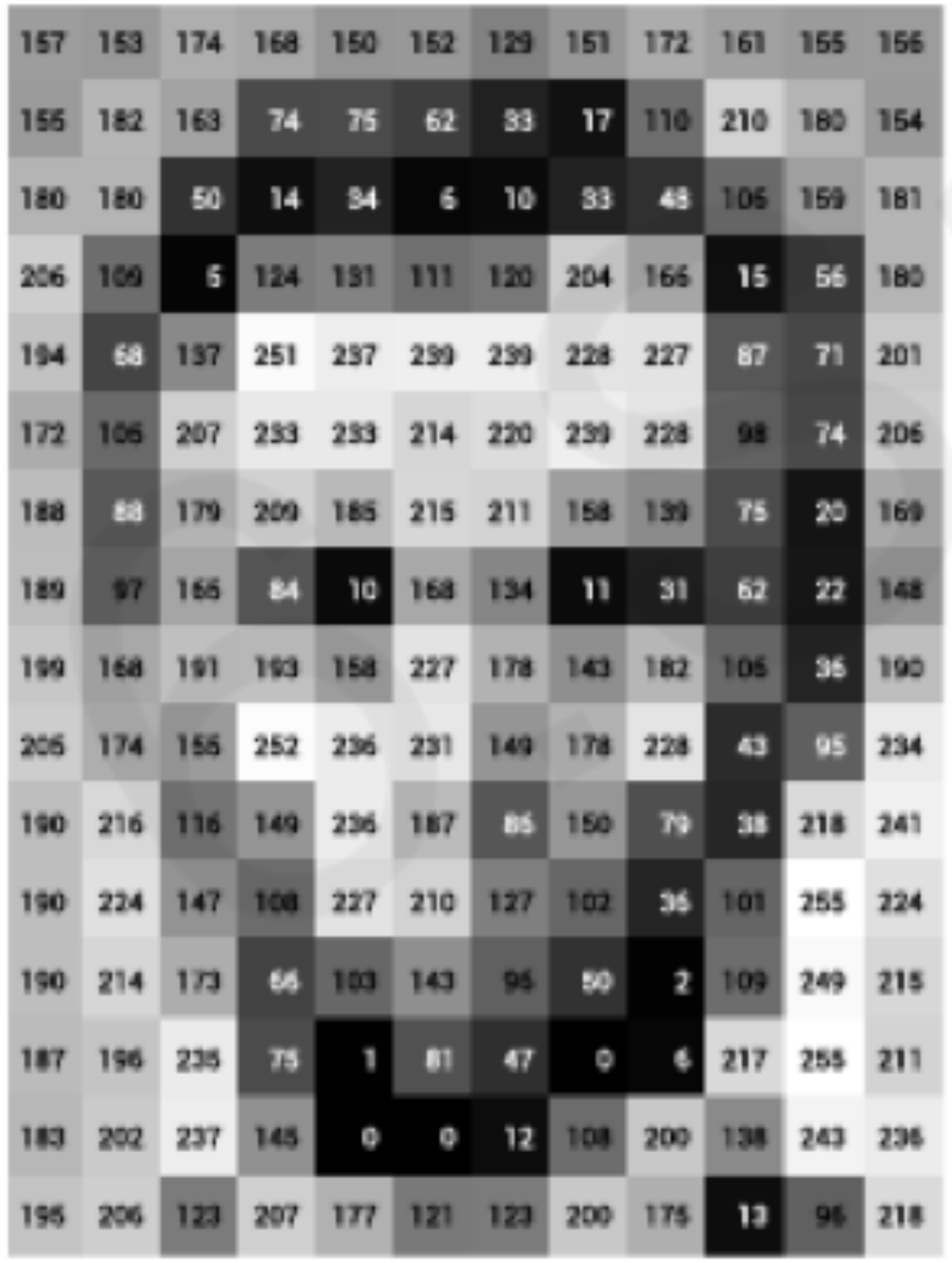
Images are Numbers



157	153	174	168	150	152	129	151	172	161	155	156
155	182	163	74	75	62	33	17	110	210	180	154
180	180	50	14	34	6	10	33	48	106	159	181
206	109	5	124	131	111	120	204	166	15	56	180
194	68	137	251	237	239	239	228	227	87	71	201
172	106	207	233	233	214	220	239	228	98	74	206
188	88	179	209	185	215	211	158	139	75	20	169
189	97	165	84	10	168	134	11	31	62	22	148
199	168	191	193	158	227	178	143	182	106	36	190
205	174	155	252	236	231	149	178	228	43	95	234
190	216	116	149	236	187	86	150	79	38	218	241
190	224	147	108	227	210	127	102	36	101	255	224
190	214	173	66	103	143	96	50	2	109	249	215
187	196	235	75	1	81	47	0	6	217	255	211
183	202	237	145	0	0	12	108	200	138	243	236
195	206	123	207	177	121	123	200	175	13	96	218

Images are Numbers





What the computer sees

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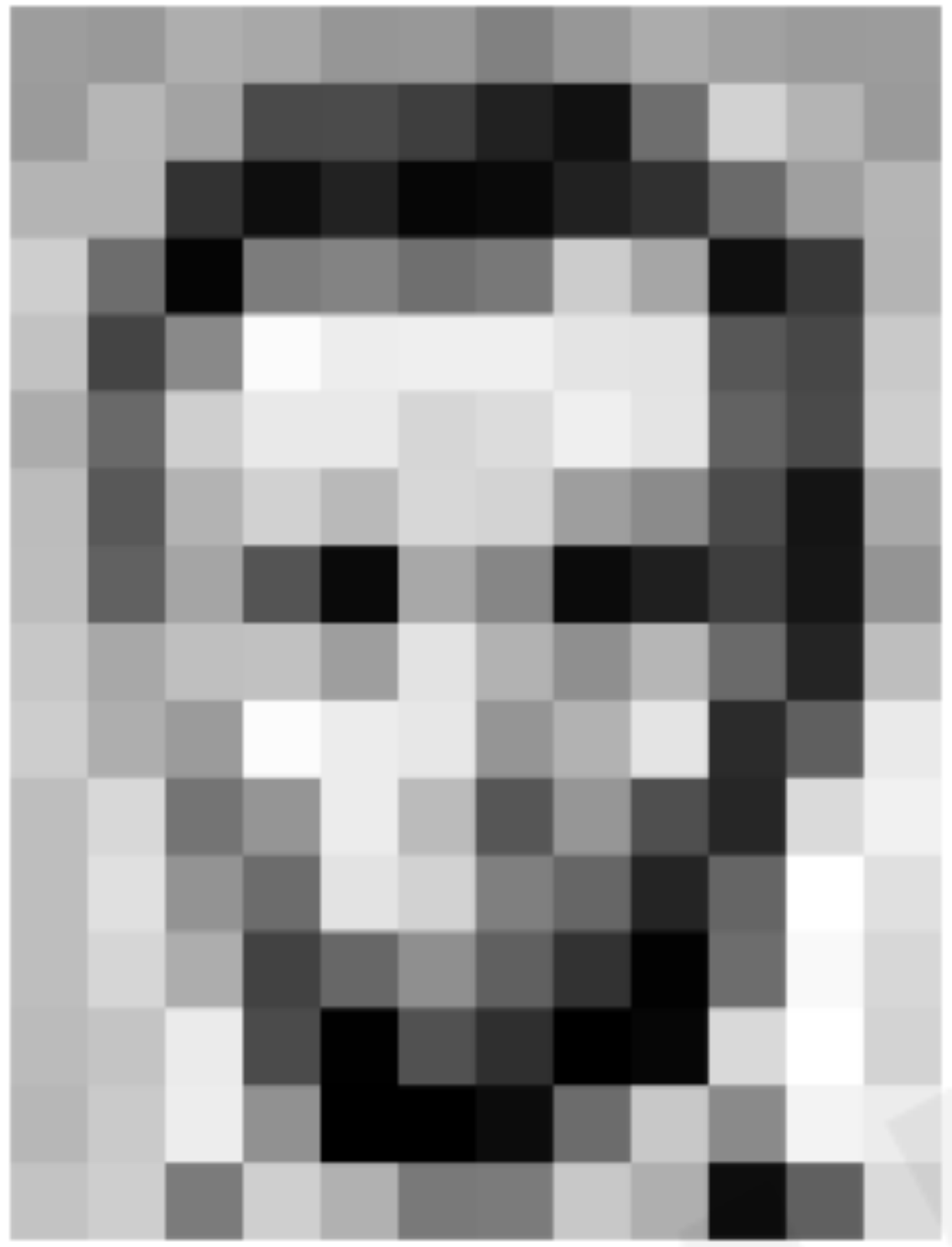
195	206	123	207	177	121	123	200	175	13	96	218

An image is just a matrix of numbers [0,255]!
i.e., 1080x1080x3 for an RGB image

Tasks in Computer Vision



Input Image

157	153	174	168	150	152	129	151	172	161	155	156
155	182	163	74	75	62	33	17	110	210	180	154
180	180	50	14	34	6	10	33	48	106	159	181
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183	202	237	145	0	0	12	108	200	138	243	236
195	206	123	207	177	121	123	200	175	13	96	218

Pixel Representation

$\xrightarrow{\text{classification}}$

$$\begin{array}{l} \text{Lincoln} \\ \text{Washington} \\ \text{Jefferson} \\ \text{Obama} \end{array} \begin{bmatrix} 0.8 \\ 0.1 \\ 0.05 \\ 0.05 \end{bmatrix}$$

- **Regression**: output variable takes continuous value
- **Classification**: output variable takes class label. Can produce probability of belonging to a particular class

High Level Feature Detection

Let's identify key features in each image category

Nose,
Eyes,
Mouth

Wheels,
License Plate,
Headlights

Door,
Windows,
Steps

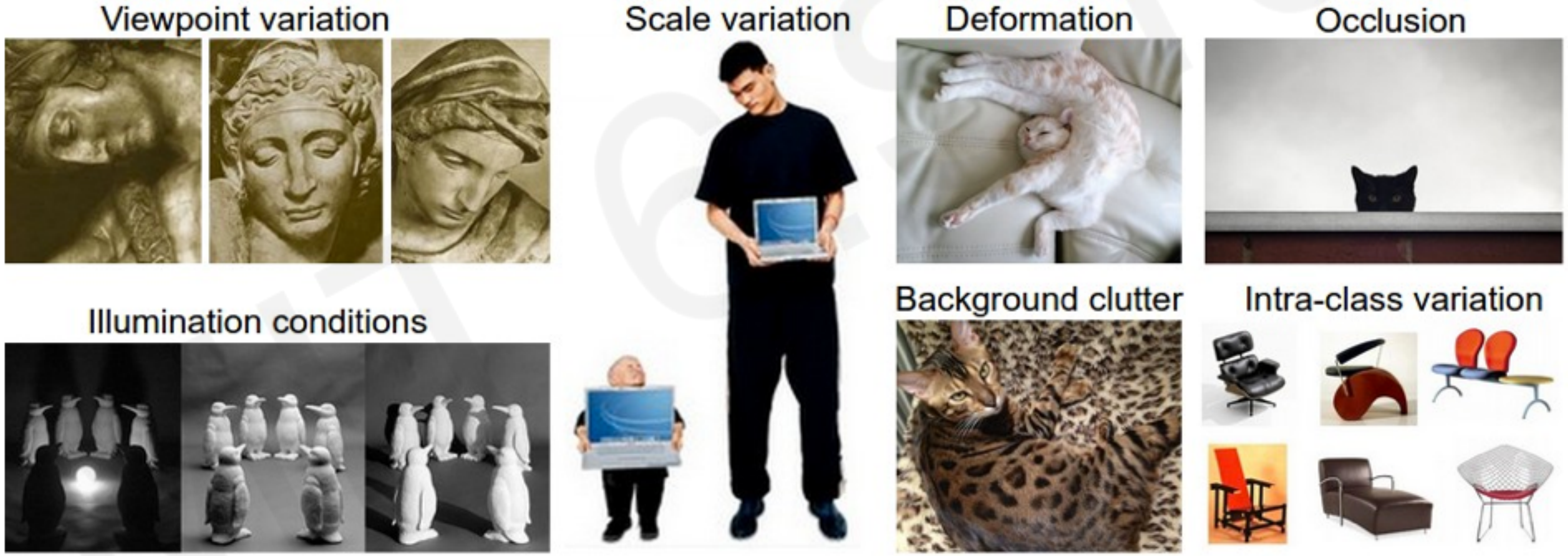
Manual Feature Extraction

Domain knowledge → Define features → Detect features to classify

Problems?

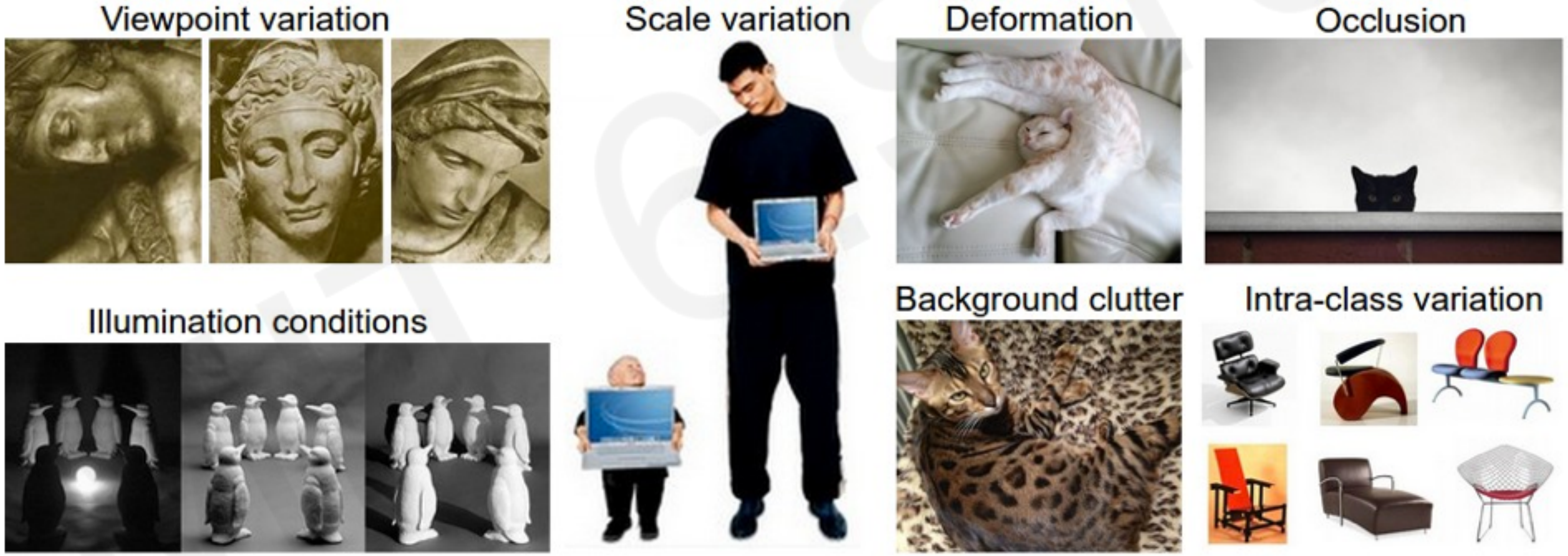
Manual Feature Extraction

Domain knowledge → Define features → Detect features to classify



Manual Feature Extraction

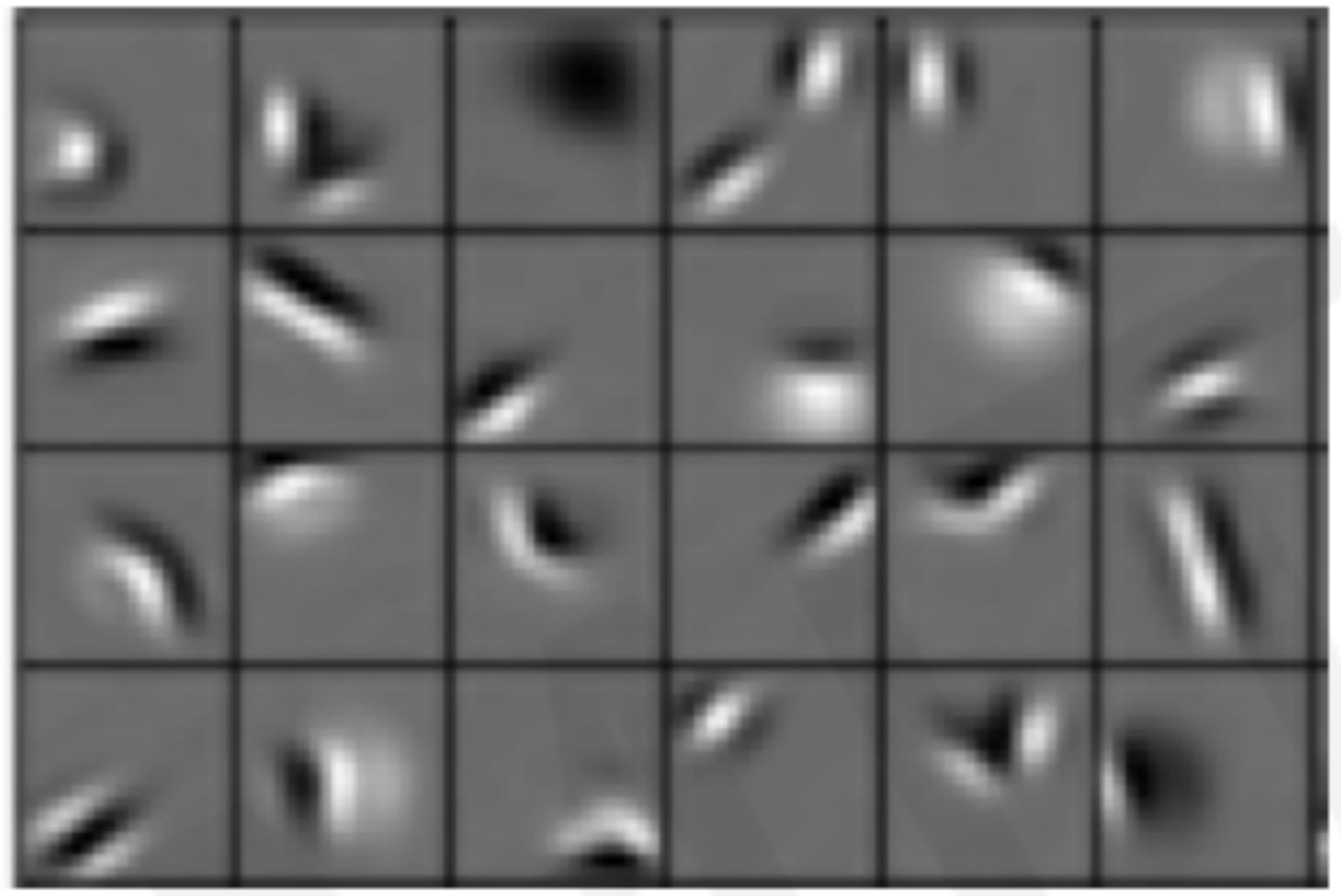
Domain knowledge → Define features → Detect features to classify



Learning Feature Representations

Can we learn a **hierarchy of features** directly from the data instead of hand engineering?

Low level features



Edges, dark spots

Mid level features

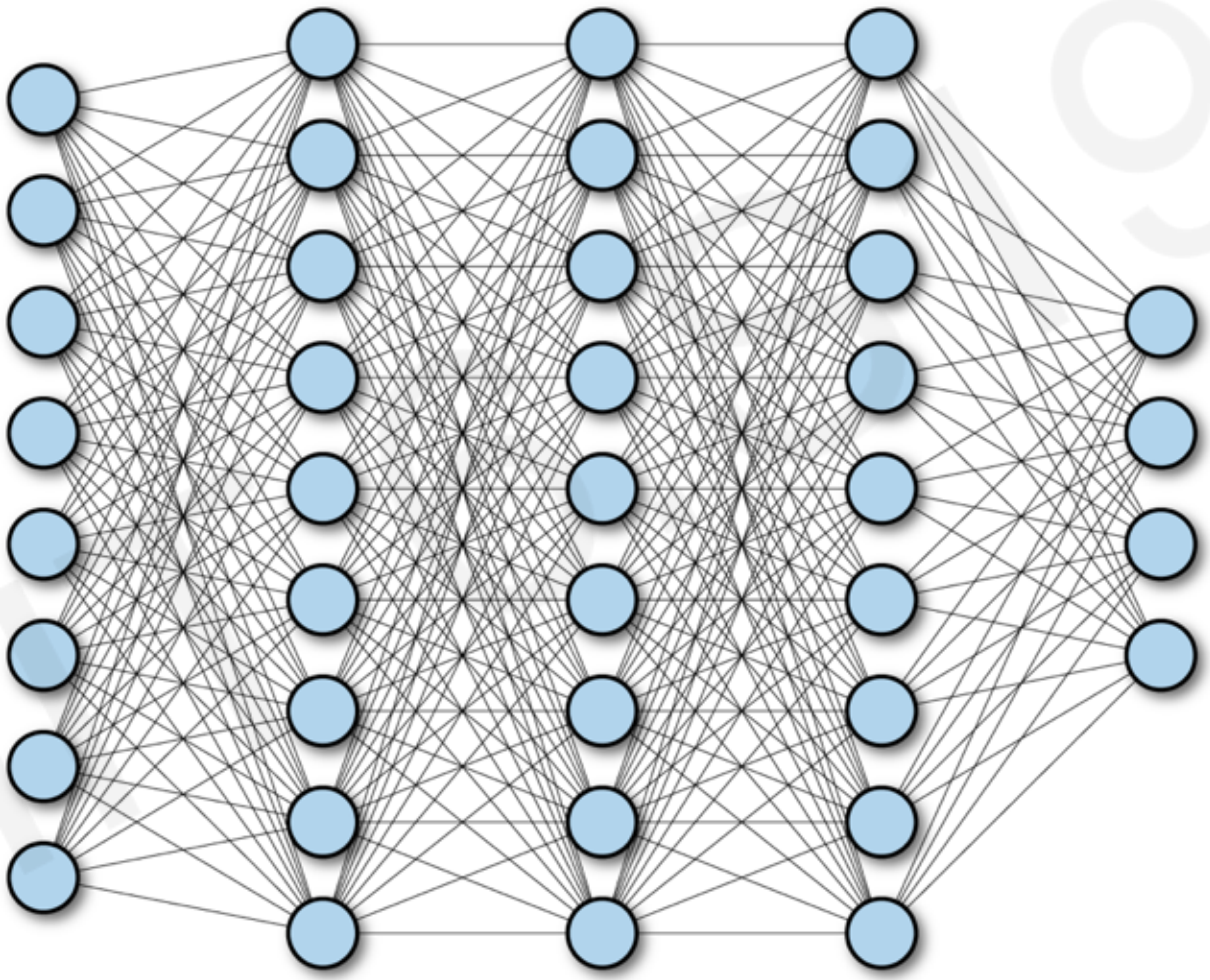
Eyes, ears, nose

High level features

Facial structure

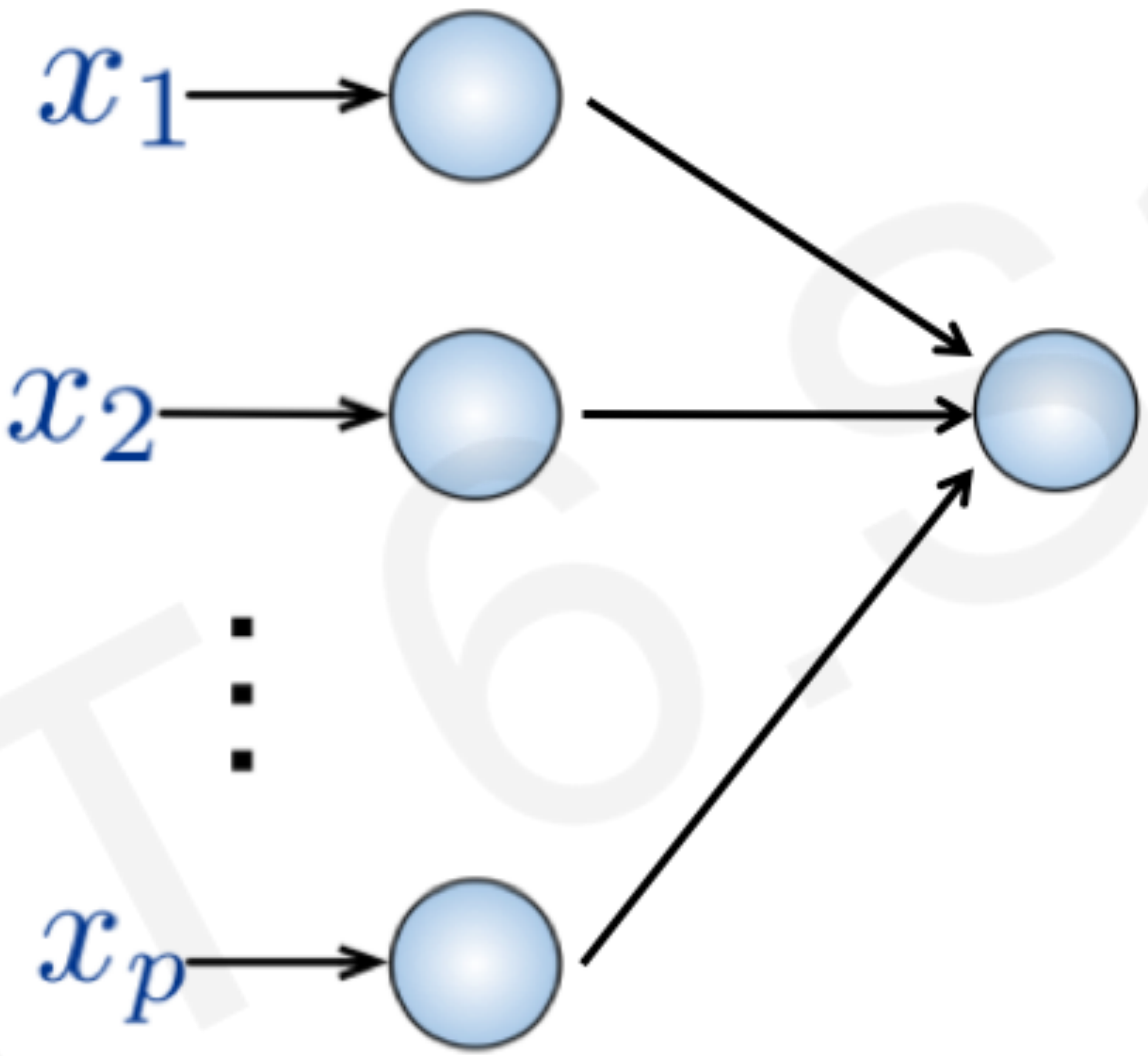
Learning Visual Features

Fully Connected Neural Network



Fully Connected Neural Network

Input:
- 2D image
- Vector of pixel values



Fully Connected:
- Connect neuron in hidden layer to all neurons in input layer
- No spatial information!
- And many, many parameters!

Fully Connected Neural Network

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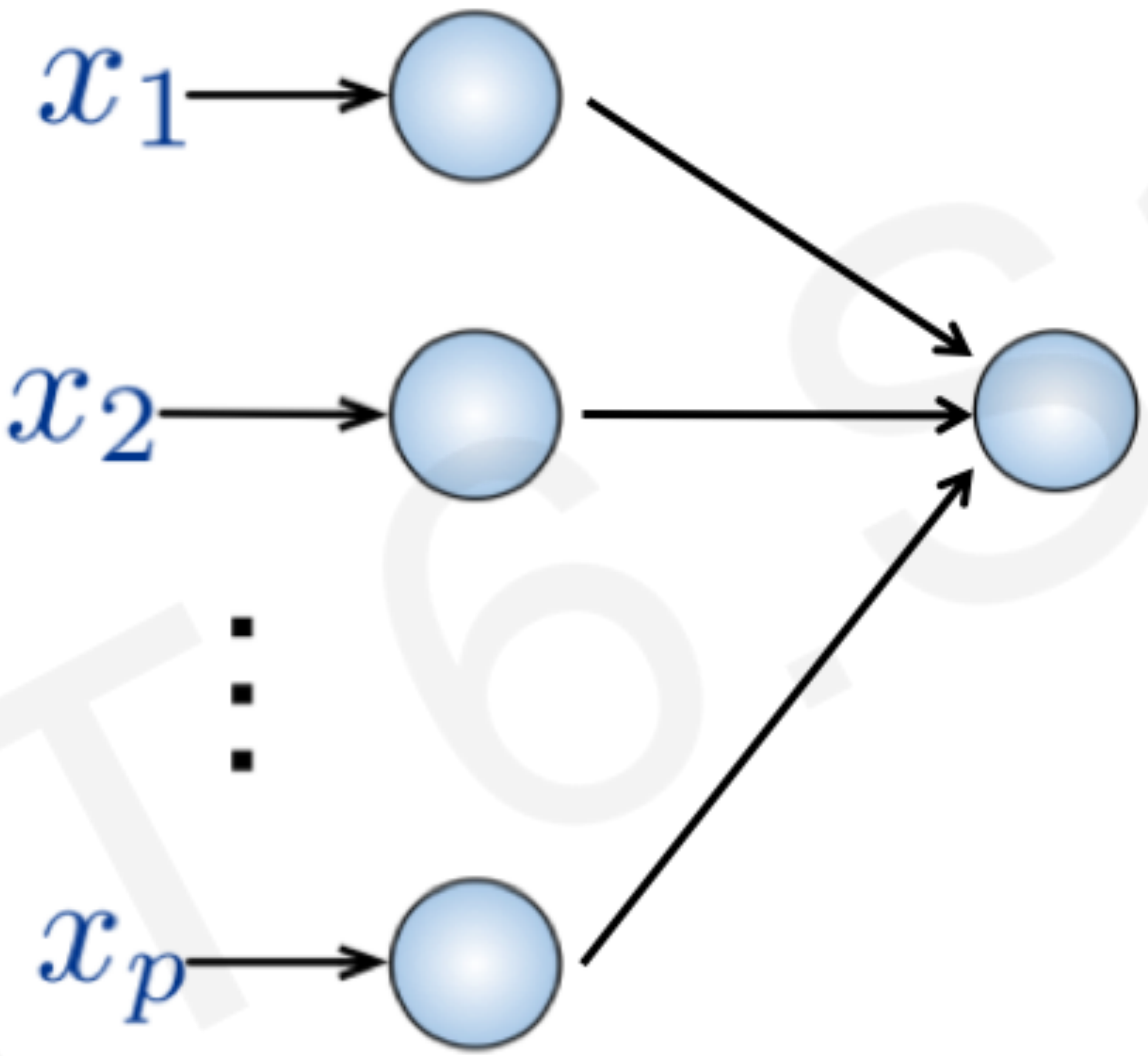
- 2D image
- Vector of pixel values

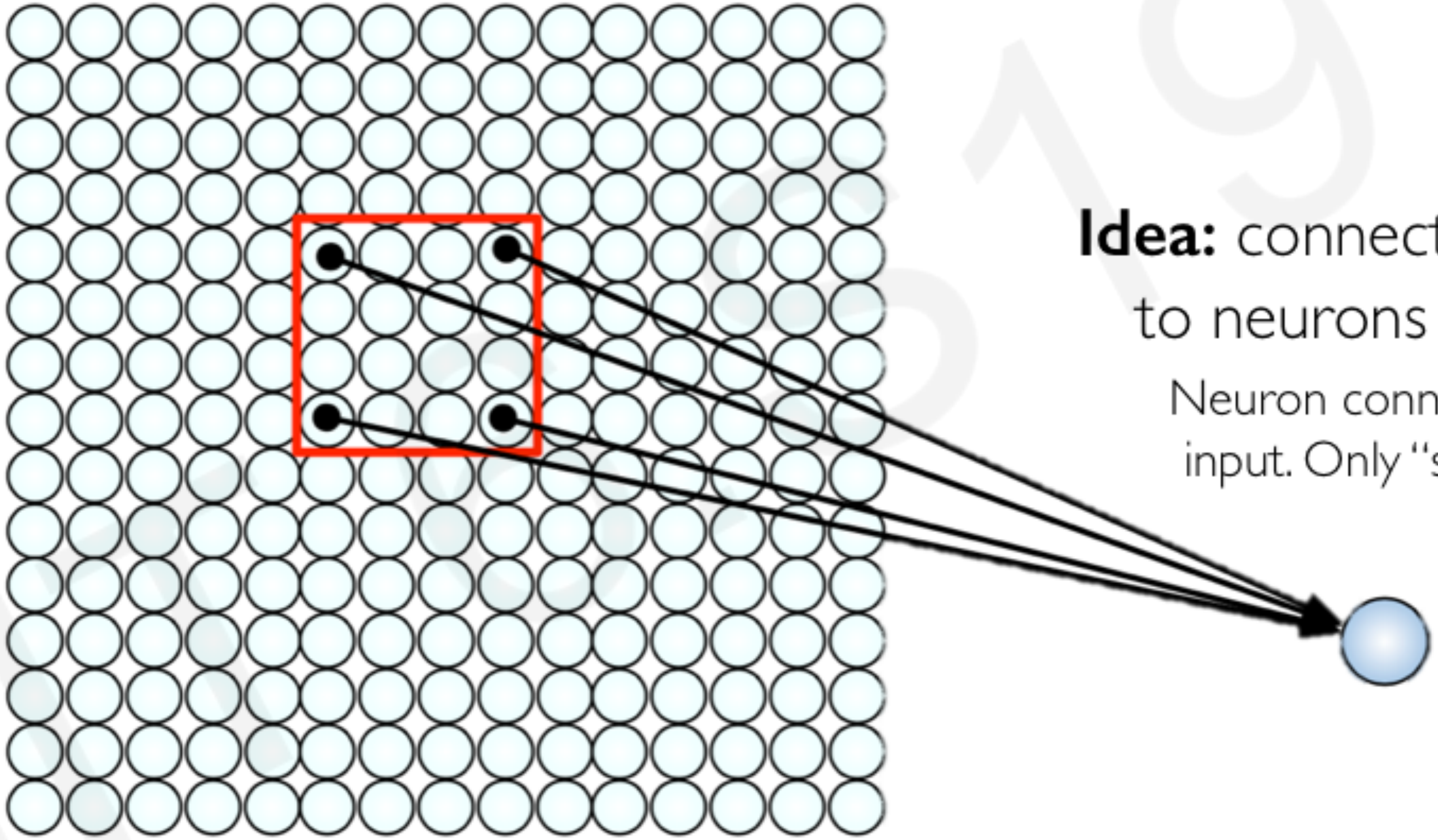


Fully Connected:
- Connect neuron in hidden layer to all neurons in input layer
- No spatial information!
- And many, many parameters!

How can we use **spatial structure** in the input to inform the architecture of the network?

Using Spatial Structure

Input: 2D image.
Array of pixel values



Idea: connect patches of input to neurons in hidden layer.

Neuron connected to region of input. Only "sees" these values.

Using Spatial Structure

Connect patch in input layer to a single neuron in subsequent layer.
Use a sliding window to define connections.
*How can we **weight** the patch to detect particular features?*

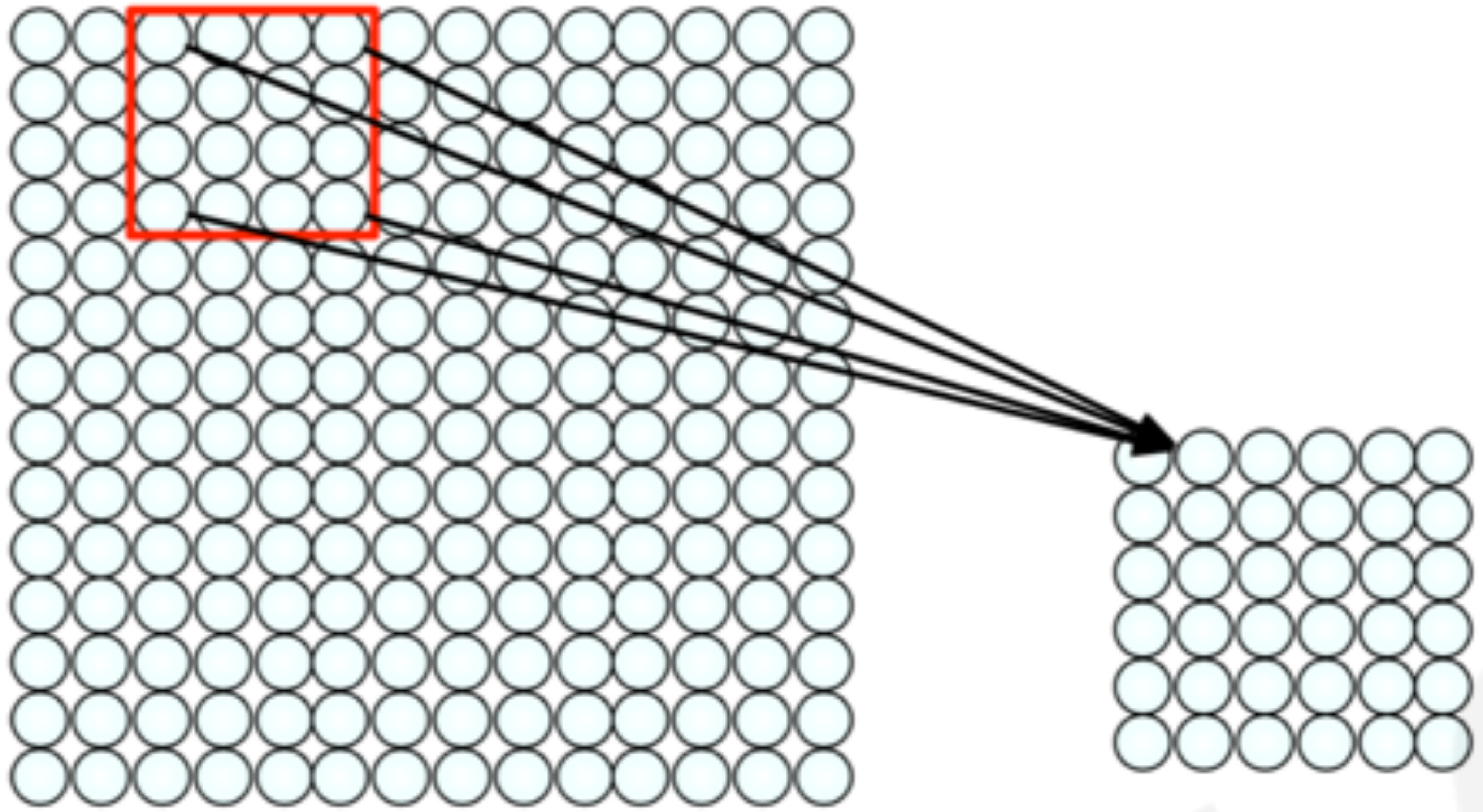
Applying Filters to Extract Features

1) Apply a set of weights – a filter – to extract **local features**

2) Use **multiple filters** to extract different features

3) Spatially **share** parameters of each filter
(features that matter in one part of the input should matter elsewhere)

Feature Extraction with Convolution



- Filter of size 4x4 : 16 different weights
- Apply this same filter to 4x4 patches in input
- Shift by 2 pixels for next patch

This "patchy" operation is **convolution**

1) Apply a set of weights – a filter – to extract **local features**

2) Use **multiple filters** to extract different features

3) **Spatially share** parameters of each filter

Feature Extraction and Convolution

A Case Study

X or X?

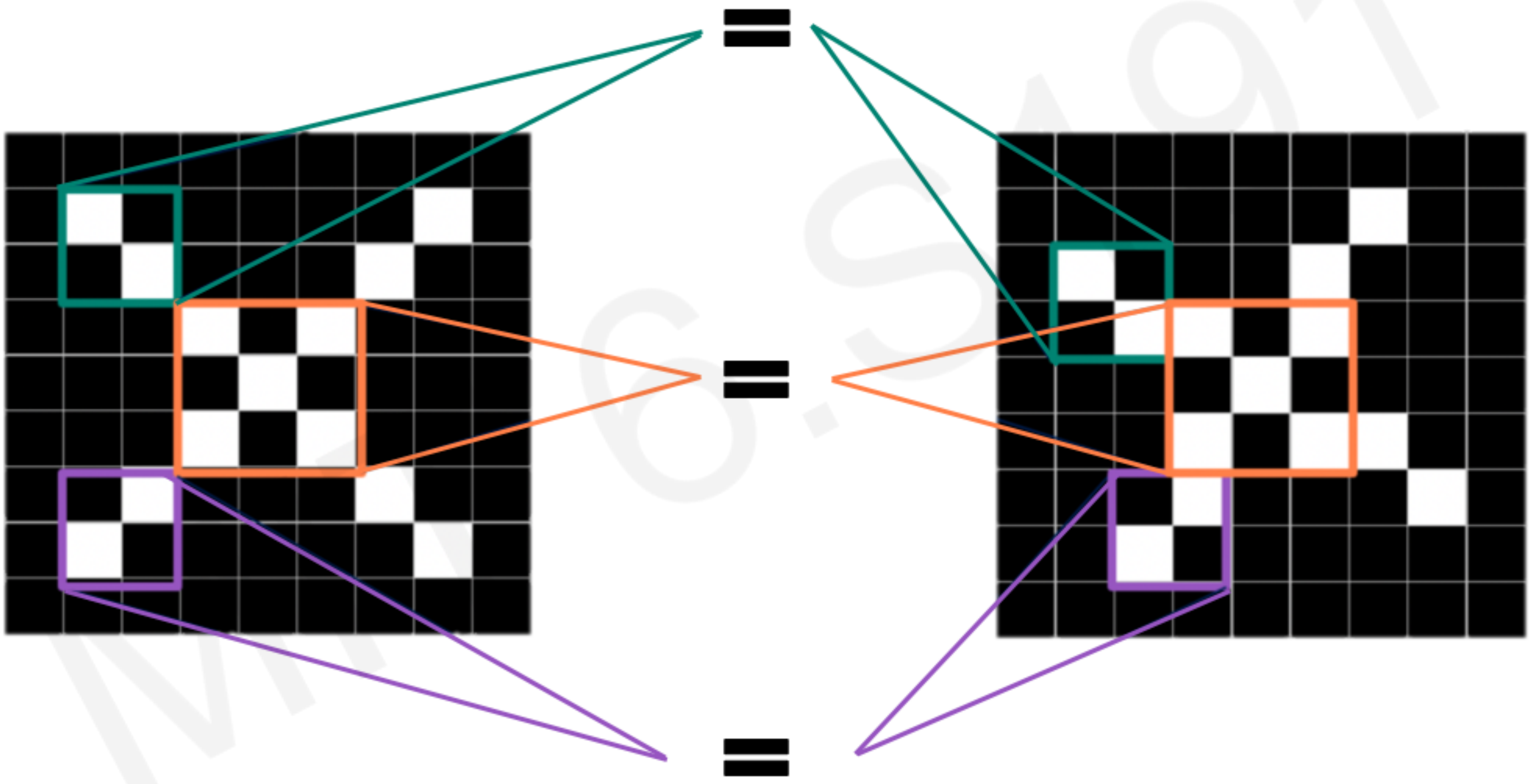
-1	-1	-1	-1	-1	-1	-1	-1	-1
-1	1	-1	-1	-1	-1	-1	1	-1
-1	-1	1	-1	-1	-1	1	-1	-1
-1	-1	-1	1	-1	1	-1	-1	-1
-1	-1	-1	-1	1	-1	-1	-1	-1
-1	-1	-1	1	-1	1	-1	-1	-1
-1	-1	1	-1	-1	-1	1	-1	-1
-1	1	-1	-1	-1	-1	-1	1	-1
-1	-1	-1	-1	-1	-1	-1	-1	-1

$\stackrel{?}{=}$

-1	-1	-1	-1	-1	-1	-1	-1	-1
-1	-1	-1	-1	-1	-1	1	-1	-1
-1	1	-1	-1	-1	1	-1	-1	-1
-1	-1	1	1	-1	1	-1	-1	-1
-1	-1	-1	-1	1	-1	-1	-1	-1
-1	-1	-1	1	-1	1	1	-1	-1
-1	-1	-1	1	-1	-1	-1	1	-1
-1	-1	1	-1	-1	-1	-1	-1	-1
-1	-1	-1	-1	-1	-1	-1	-1	-1

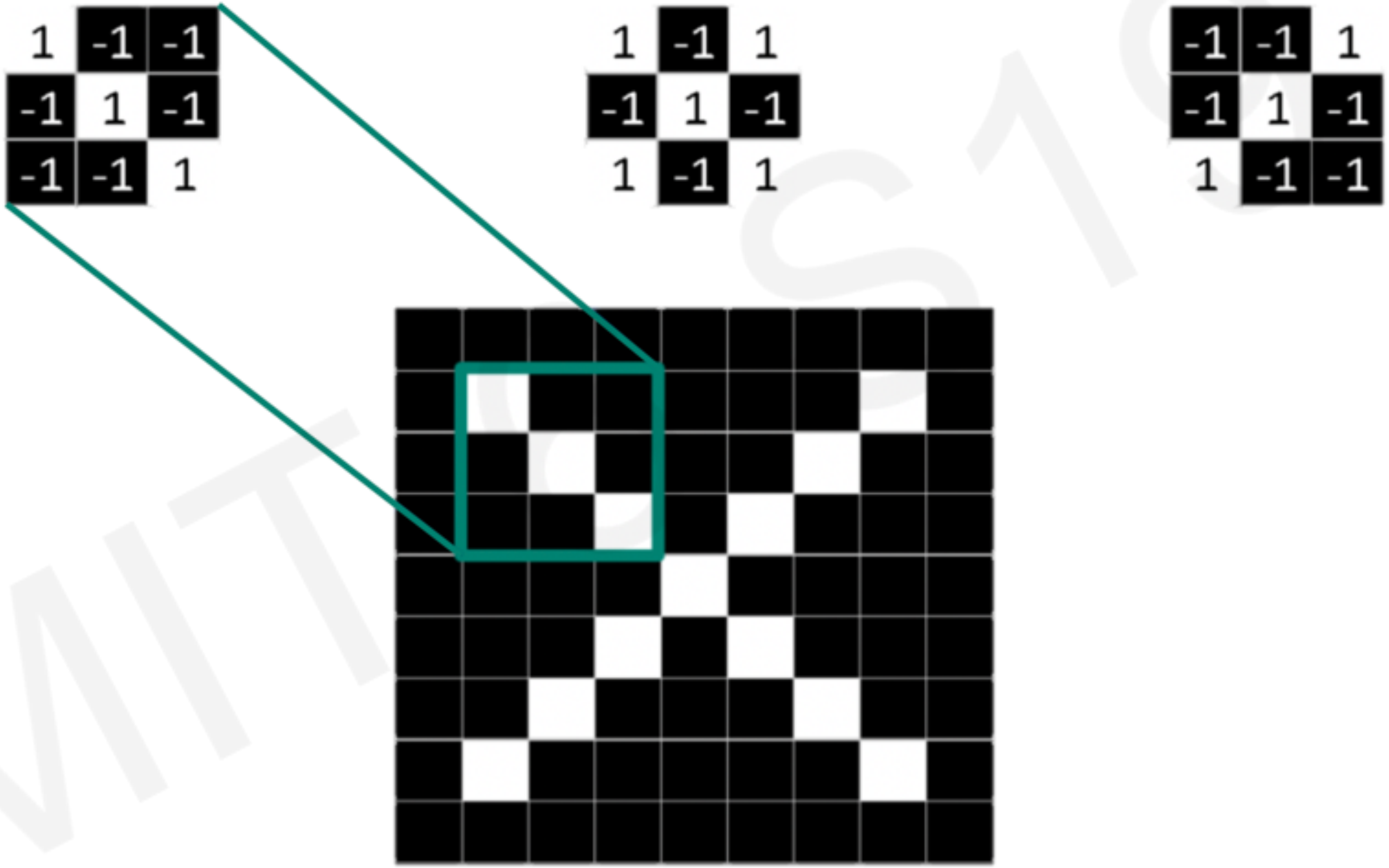
Image is represented as matrix of pixel values… and computers are literal!
We want to be able to classify an X as an X even if it's shifted, shrunk, rotated, deformed.

Features of X



Filters to Detect X Features

filters



The Convolution Operation

The Convolution Operation

Suppose we want to compute the convolution of a 5x5 image and a 3x3 filter:

1	1	1	0	0
0	1	1	1	0
0	0	1	1	1
0	0	1	1	0
0	1	1	0	0

image

$\otimes$

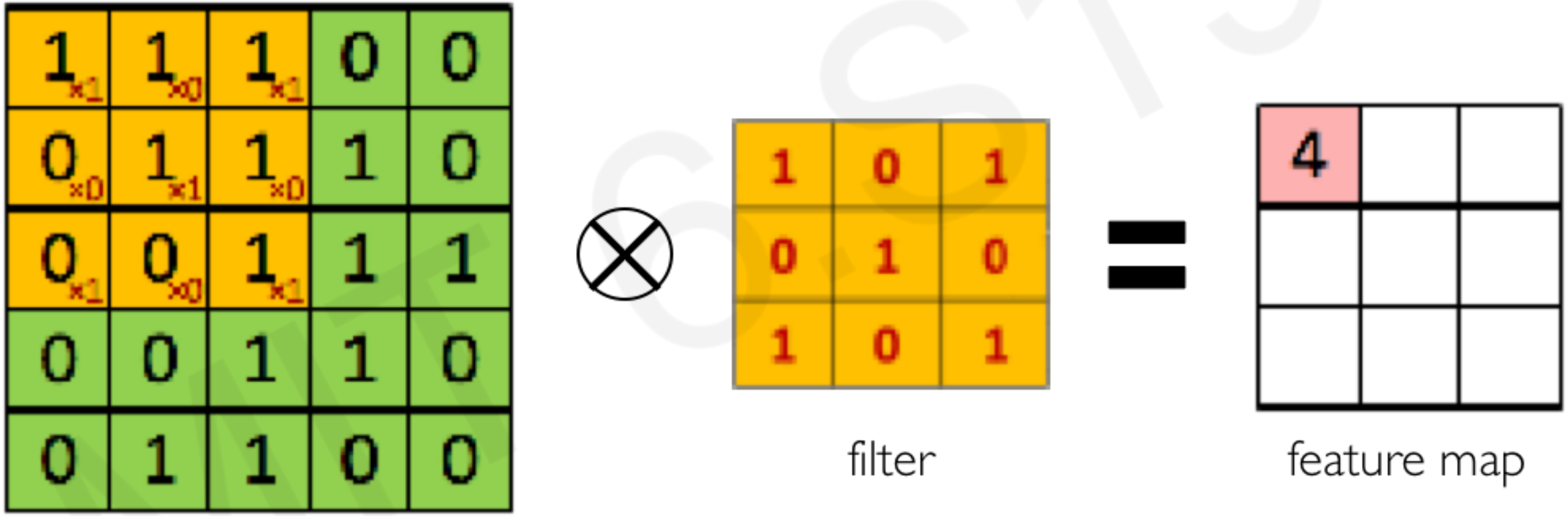
1	0	1
0	1	0
1	0	1

filter

We slide the 3x3 filter over the input image, element-wise multiply, and add the outputs…

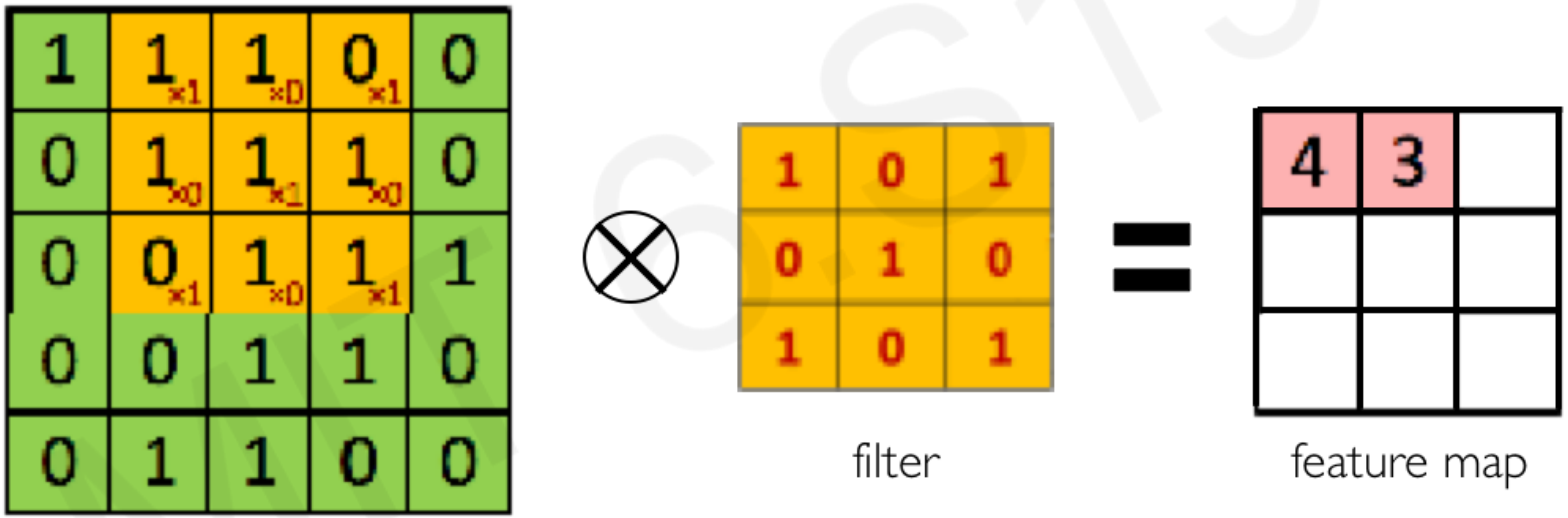
The Convolution Operation

We slide the 3x3 filter over the input image, element-wise multiply, and add the outputs:



The Convolution Operation

We slide the 3x3 filter over the input image, element-wise multiply, and add the outputs:



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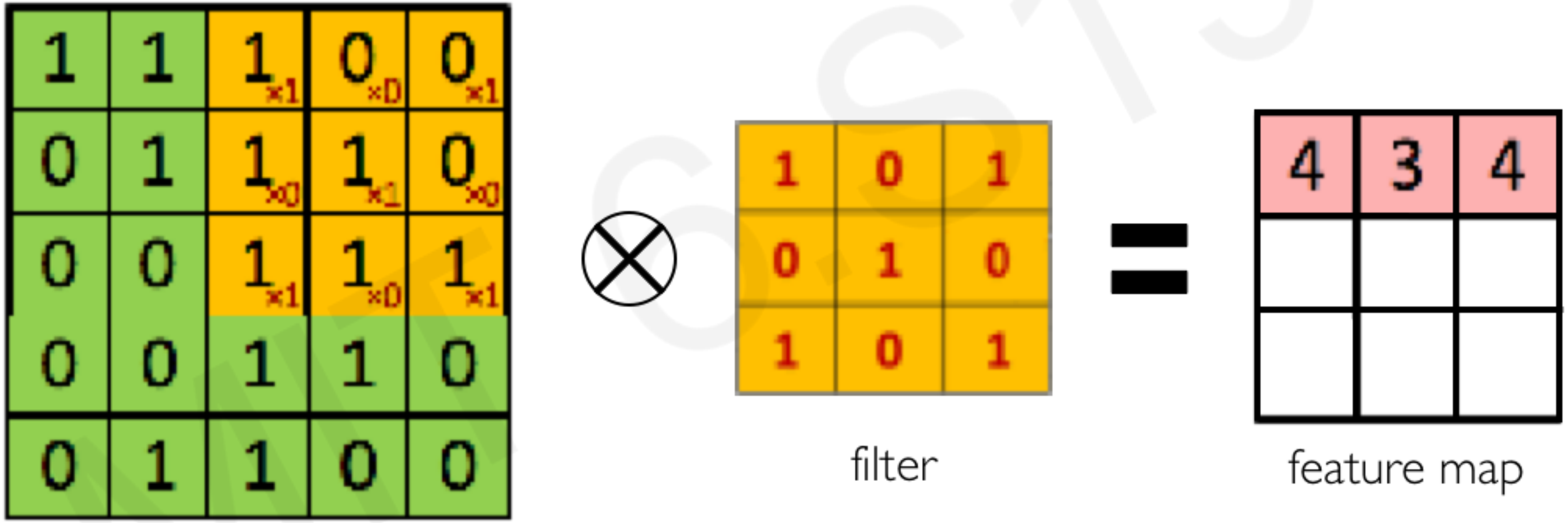

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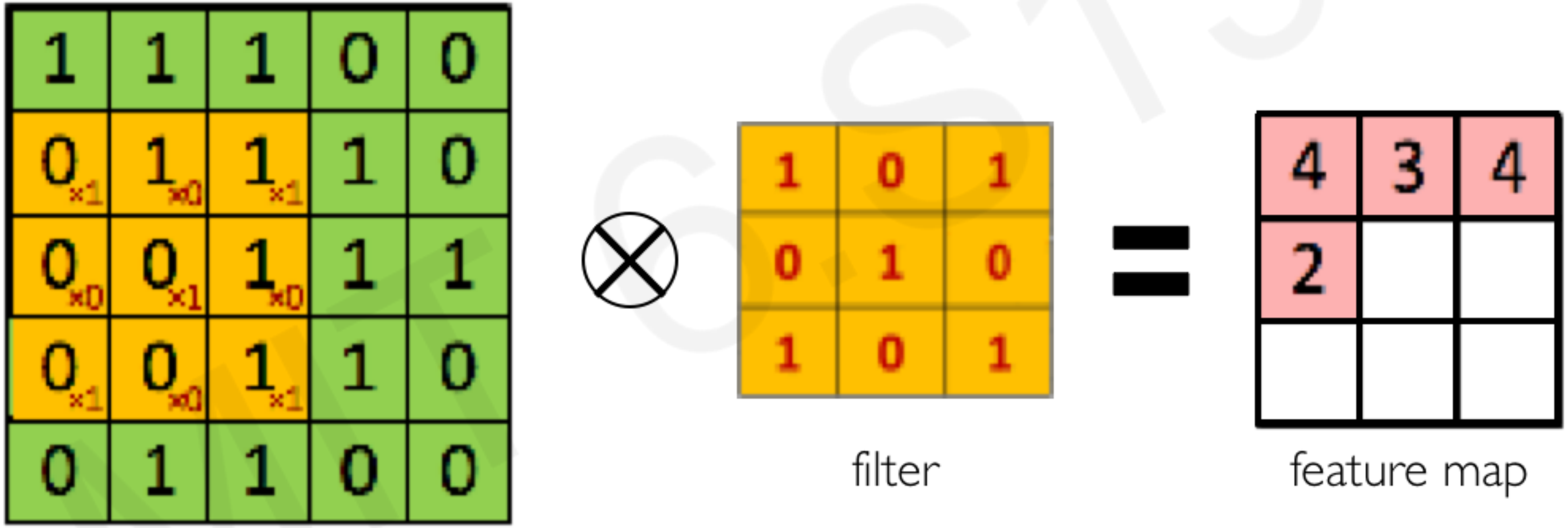

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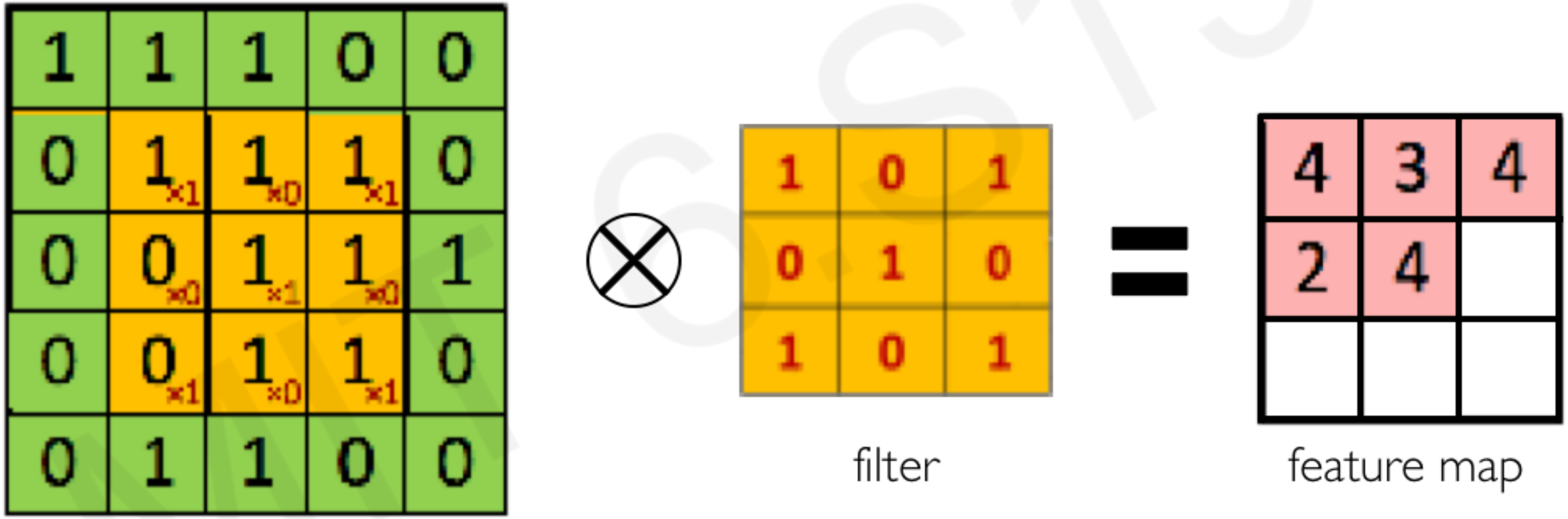

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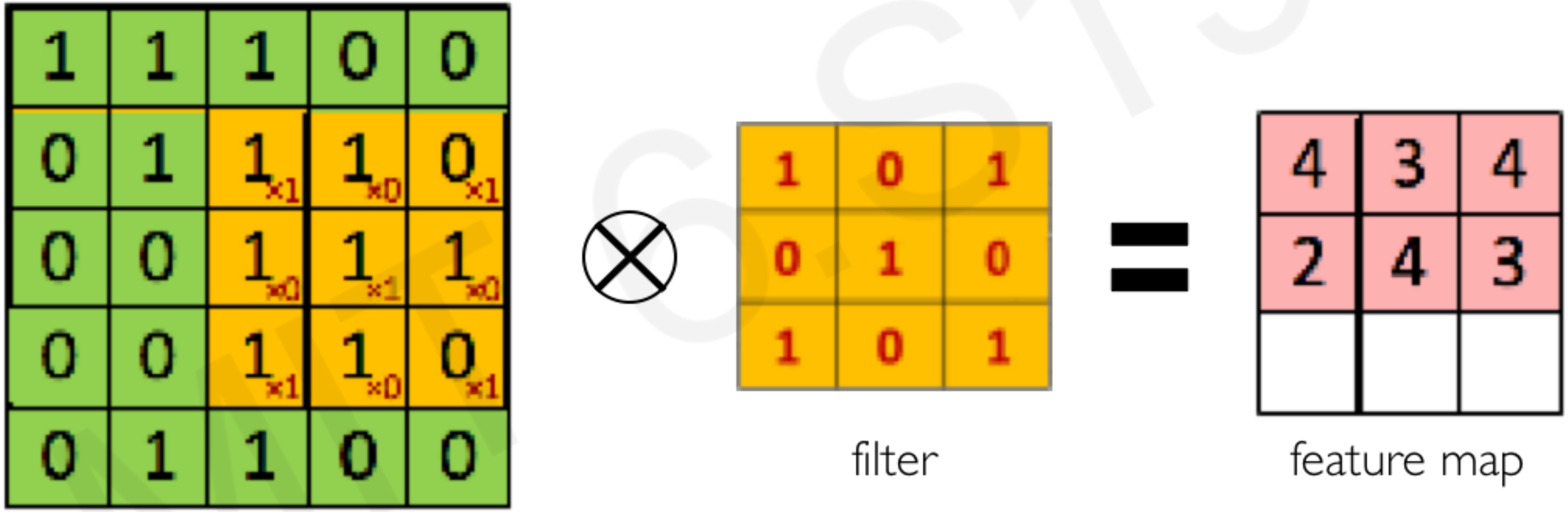

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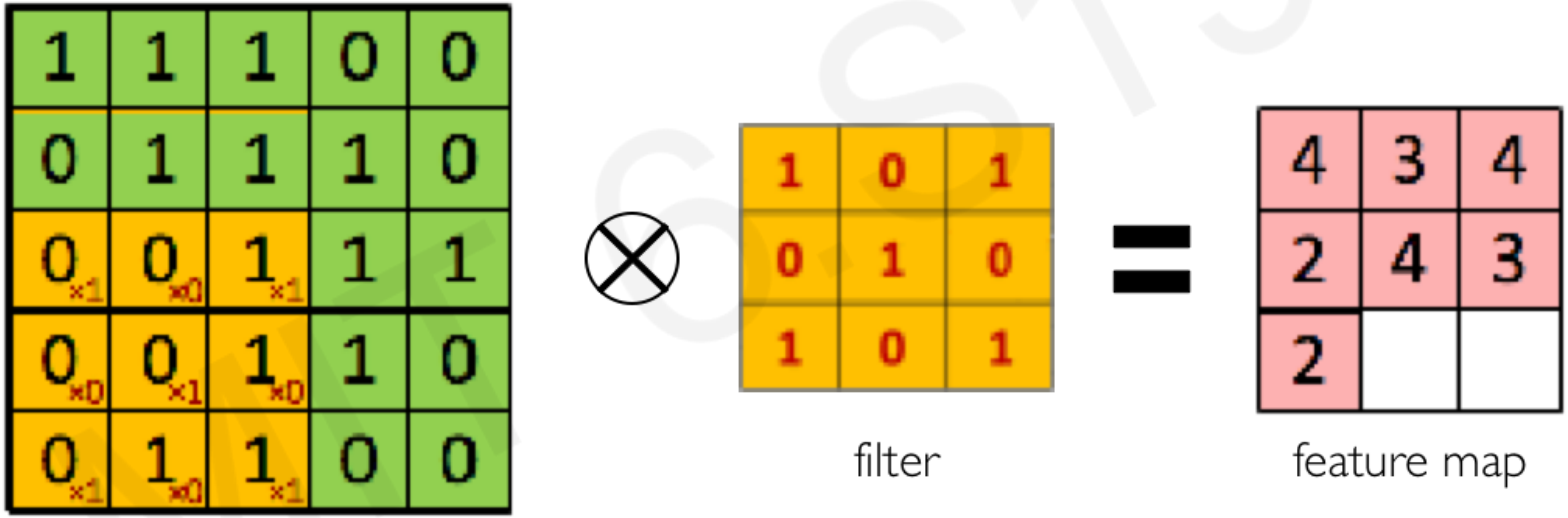

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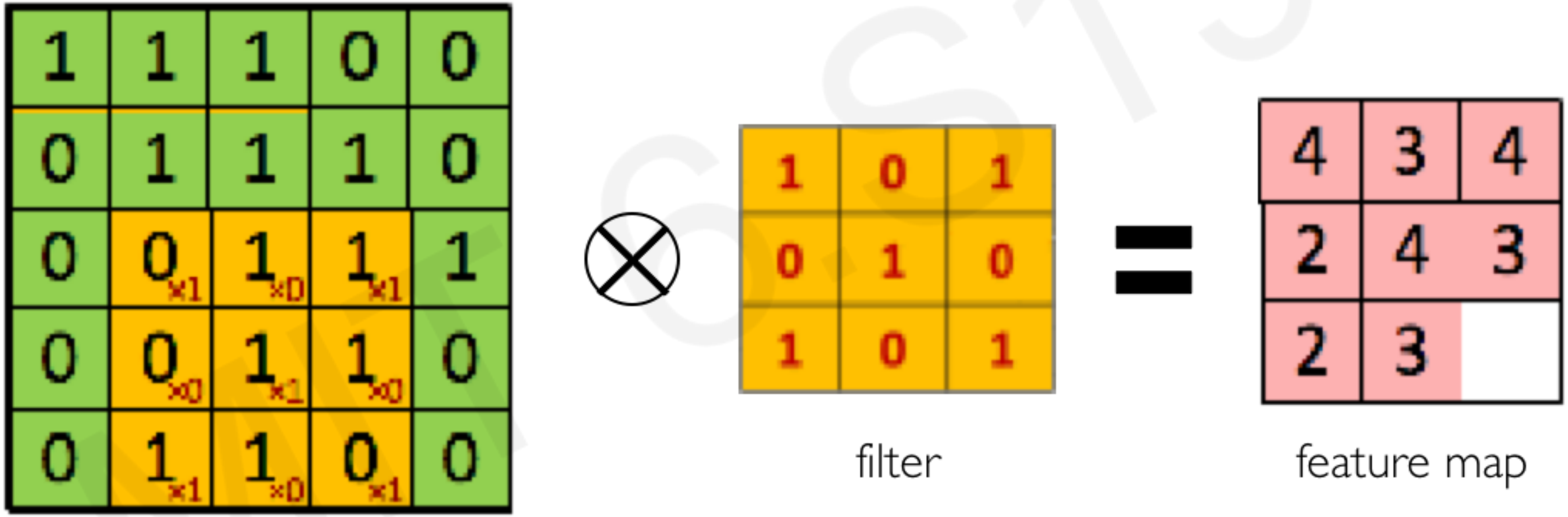
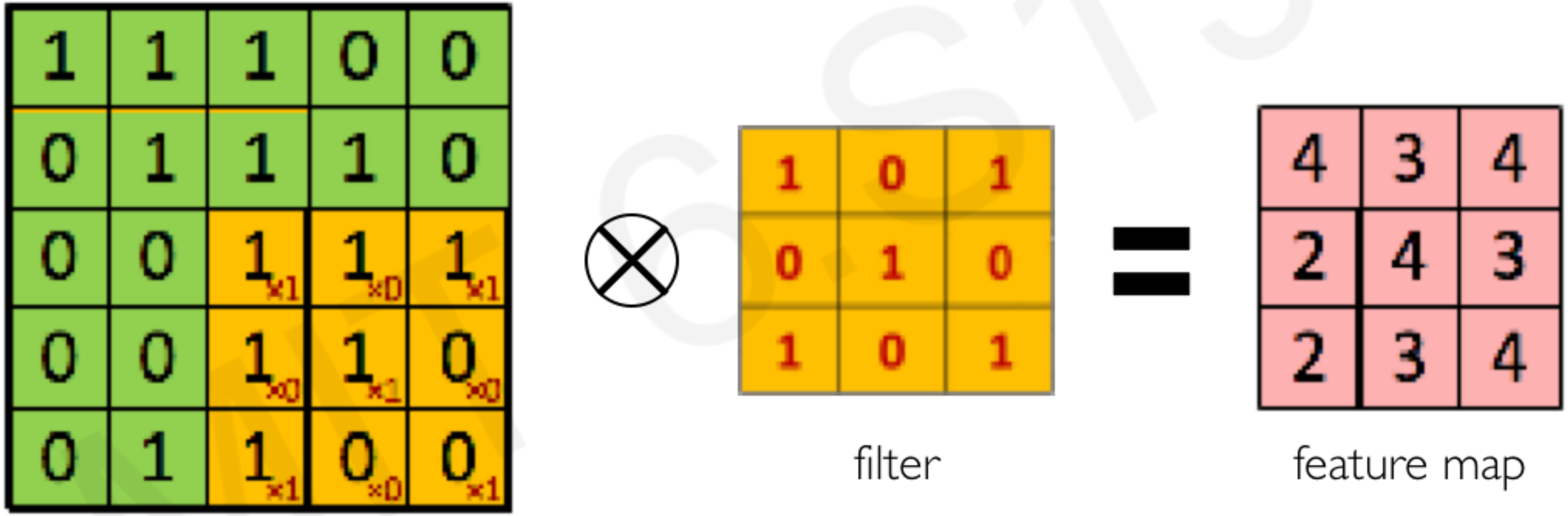


filter

feature map

The Convolution Operation

We slide the 3x3 filter over the input image, element-wise multiply, and add the outputs:



Producing Feature Maps

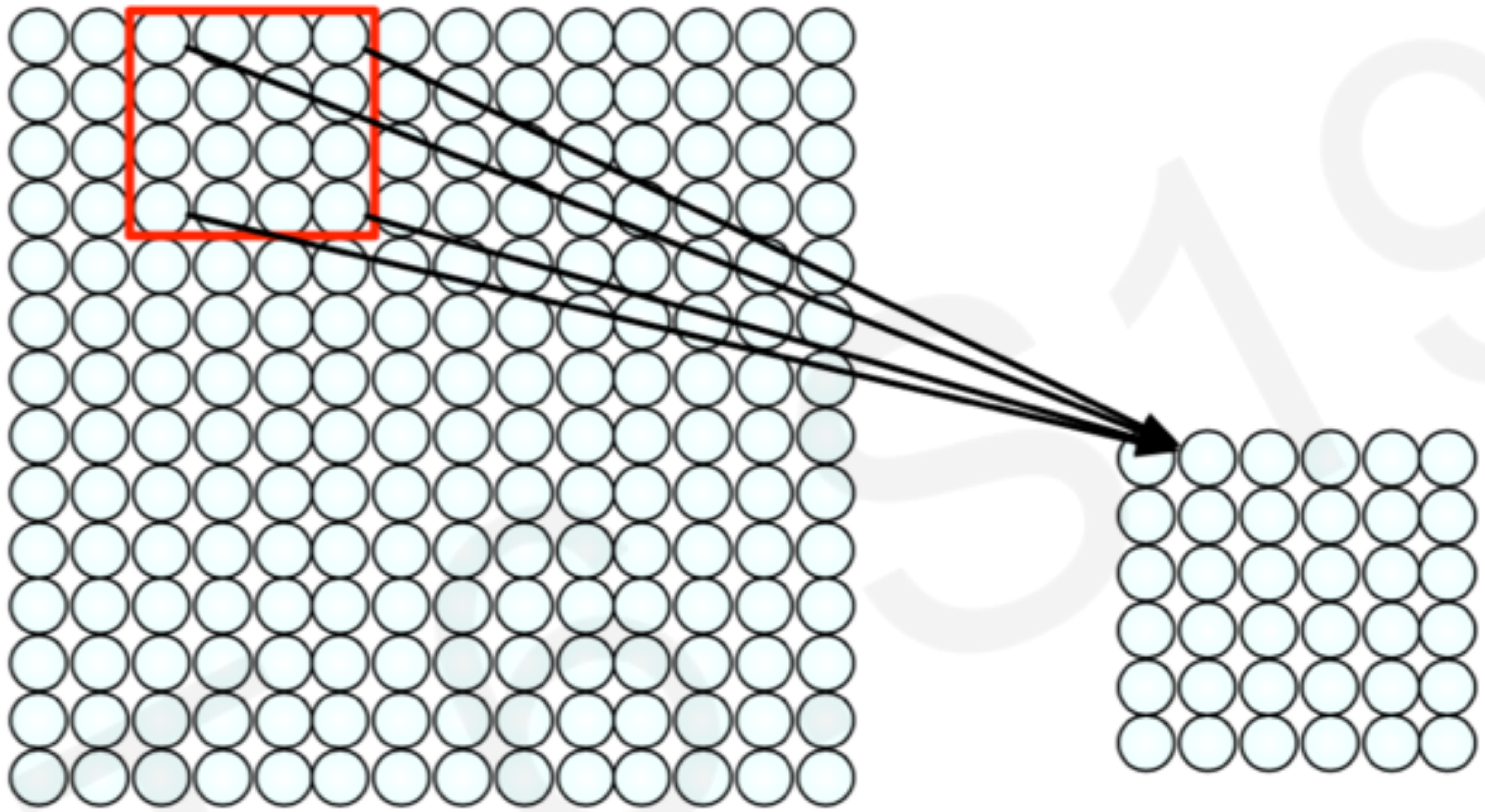
Original

Sharpen

Edge Detect

"Strong" Edge Detect

Feature Extraction with Convolution



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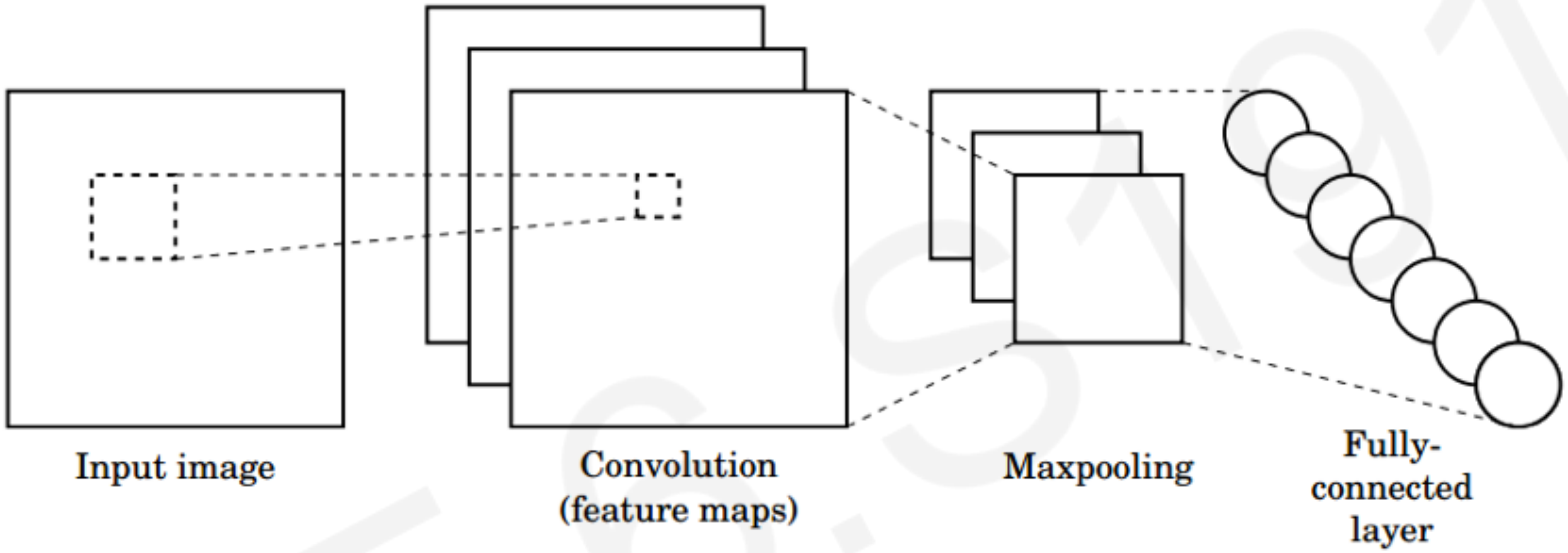
2) Use **multiple filters** to extract different features

3) **Spatially share** parameters of each filter

Convolutional Neural Networks (CNNs)

CNNs for Classification

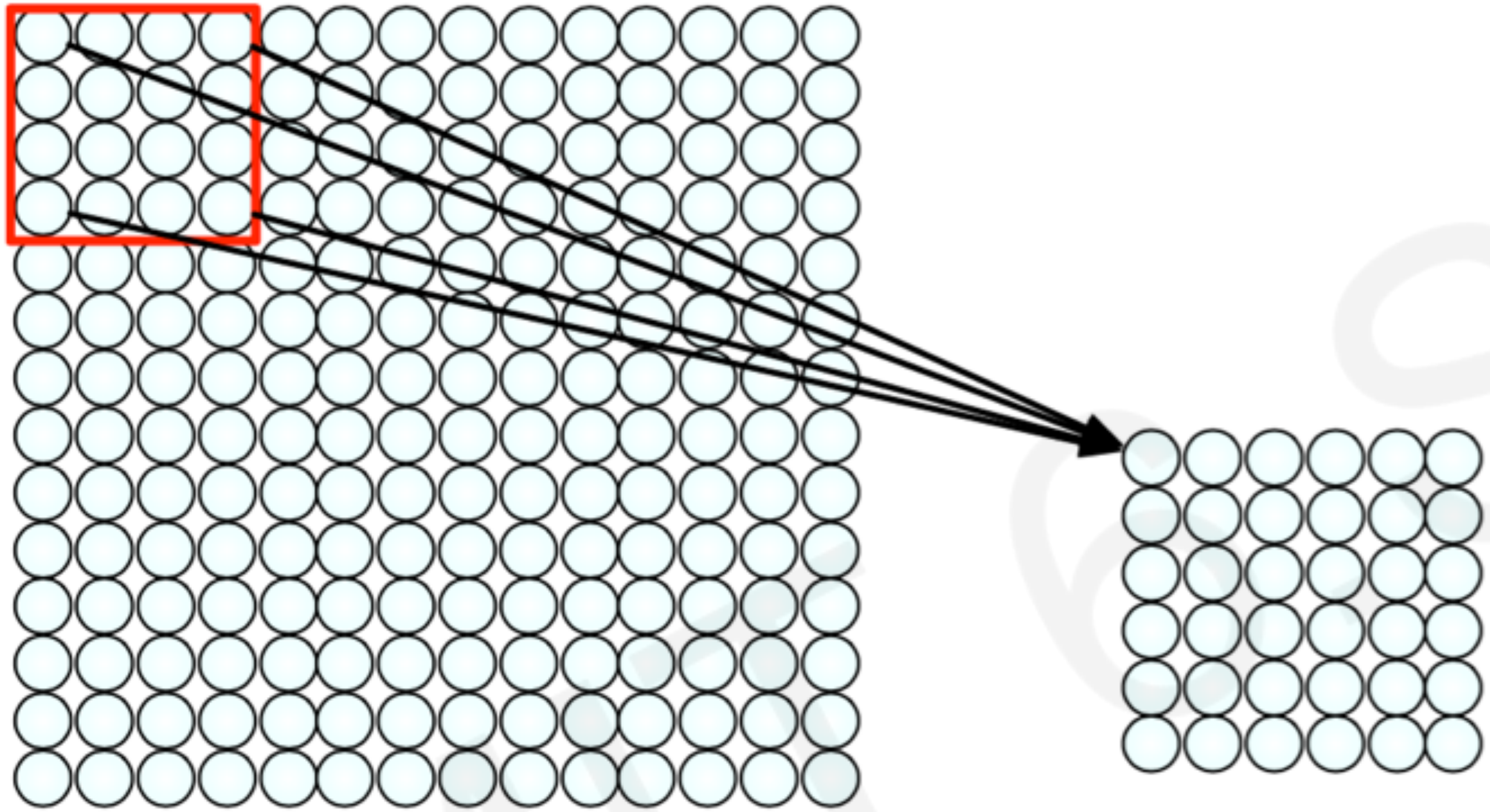


1. **Convolution**: Apply filters to generate feature maps.
2. **Non-linearity**: Often ReLU.
3. **Pooling**: Downsampling operation on each feature map.

```
tf.keras.layers.Conv2D
tf.keras.activations.*
tf.keras.layers.MaxPool2D
```

Train model with image data.
Learn weights of filters in convolutional layers.

Convolutional Layers: Local Connectivity

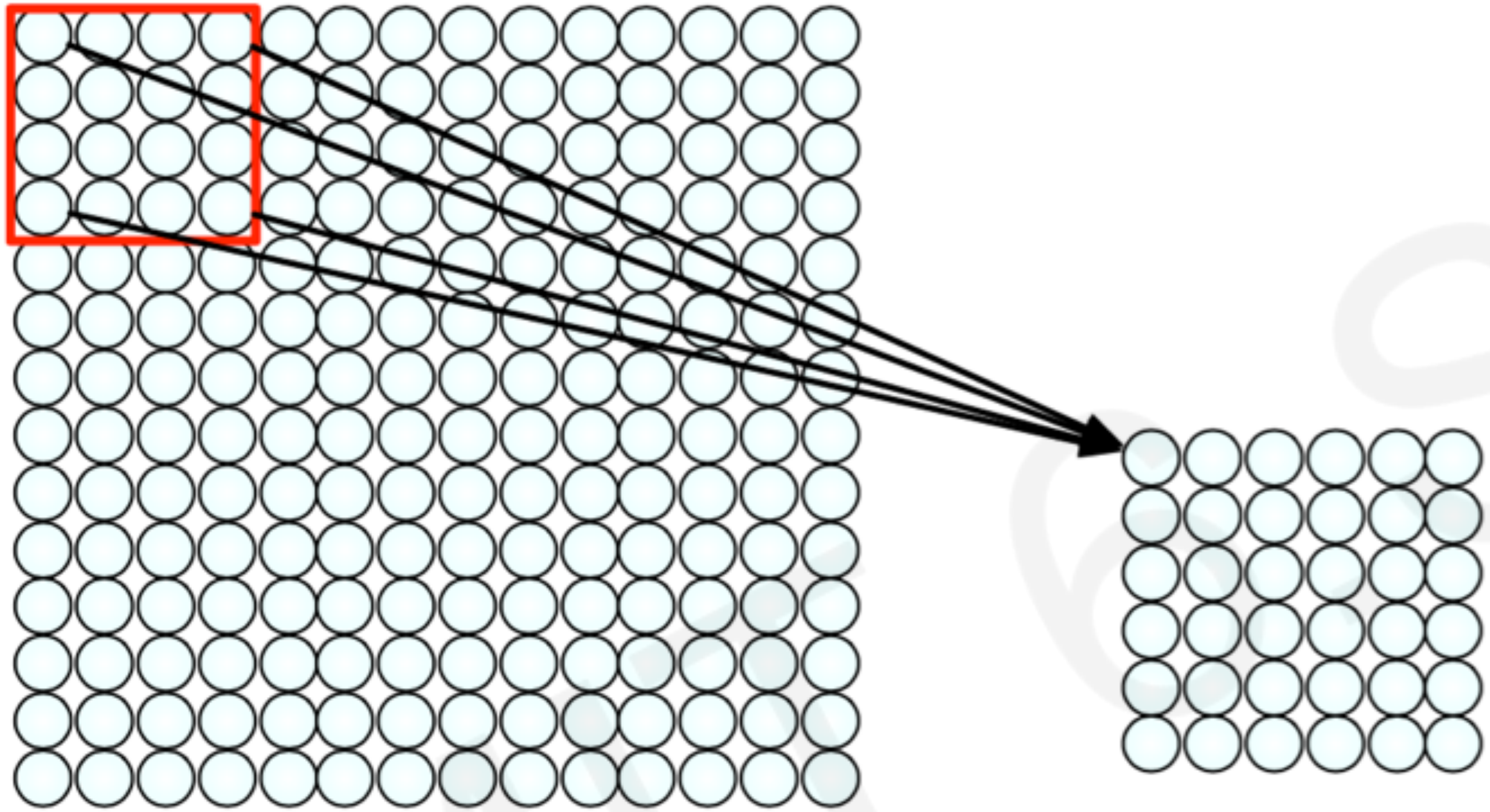


`tf.keras.layers.Conv2D`

For a neuron in hidden layer:

- Take inputs from patch
- Compute weighted sum
- Apply bias

Convolutional Layers: Local Connectivity



`tf.keras.layers.Conv2D`

4x4 filter: matrix of weights w_{ij}

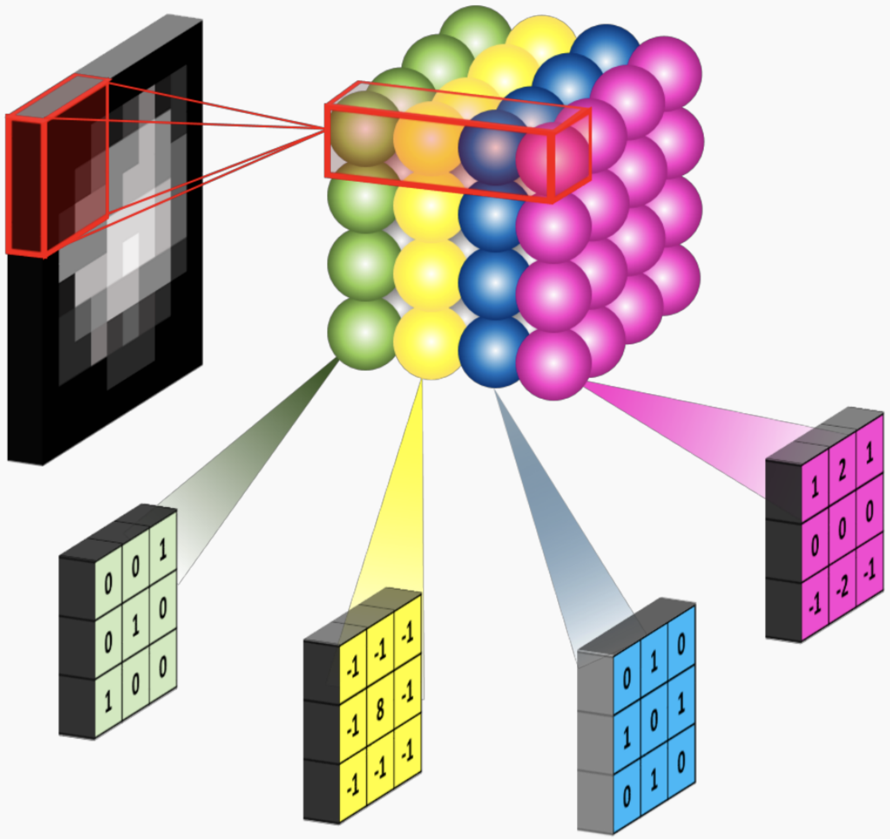
$$\sum_{i=1}^{4} \sum_{j=1}^{4} w_{ij}\, x_{i+p,j+q} + b$$

for neuron (p,q) in hidden layer

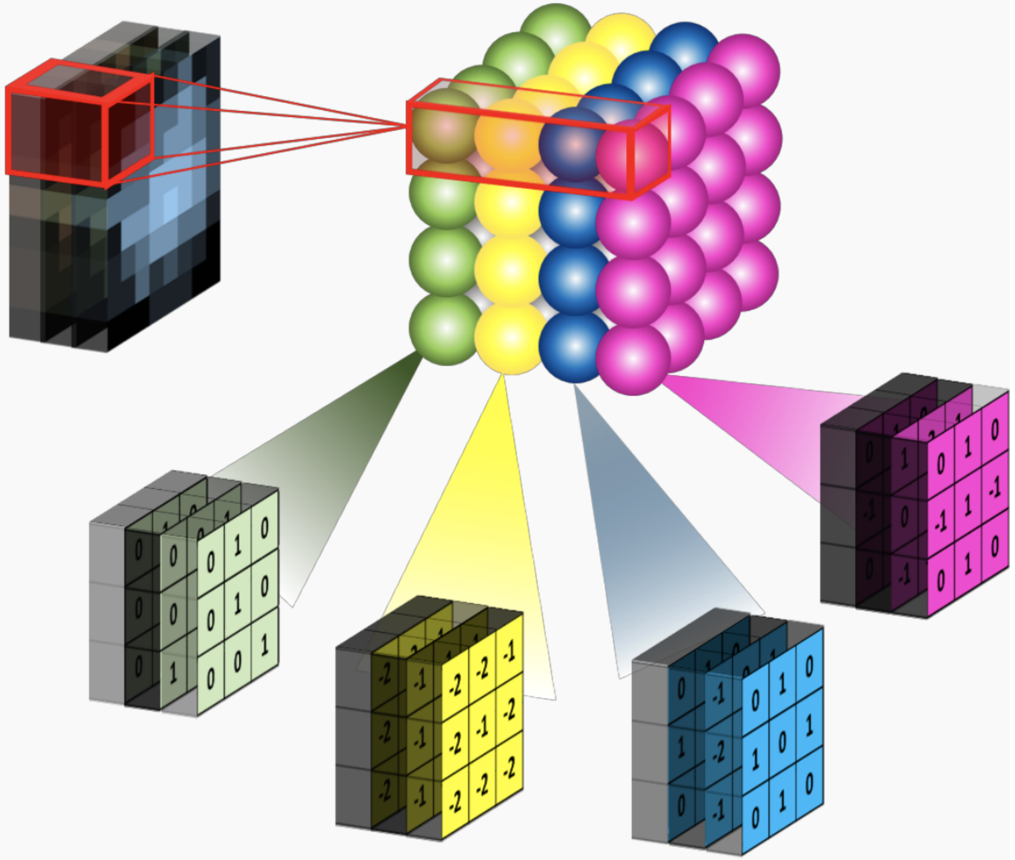
For a neuron in hidden layer:

- Take inputs from patch
- Compute weighted sum
- Apply bias

1) applying a window of weights
2) computing linear combinations
3) activating with non-linear function

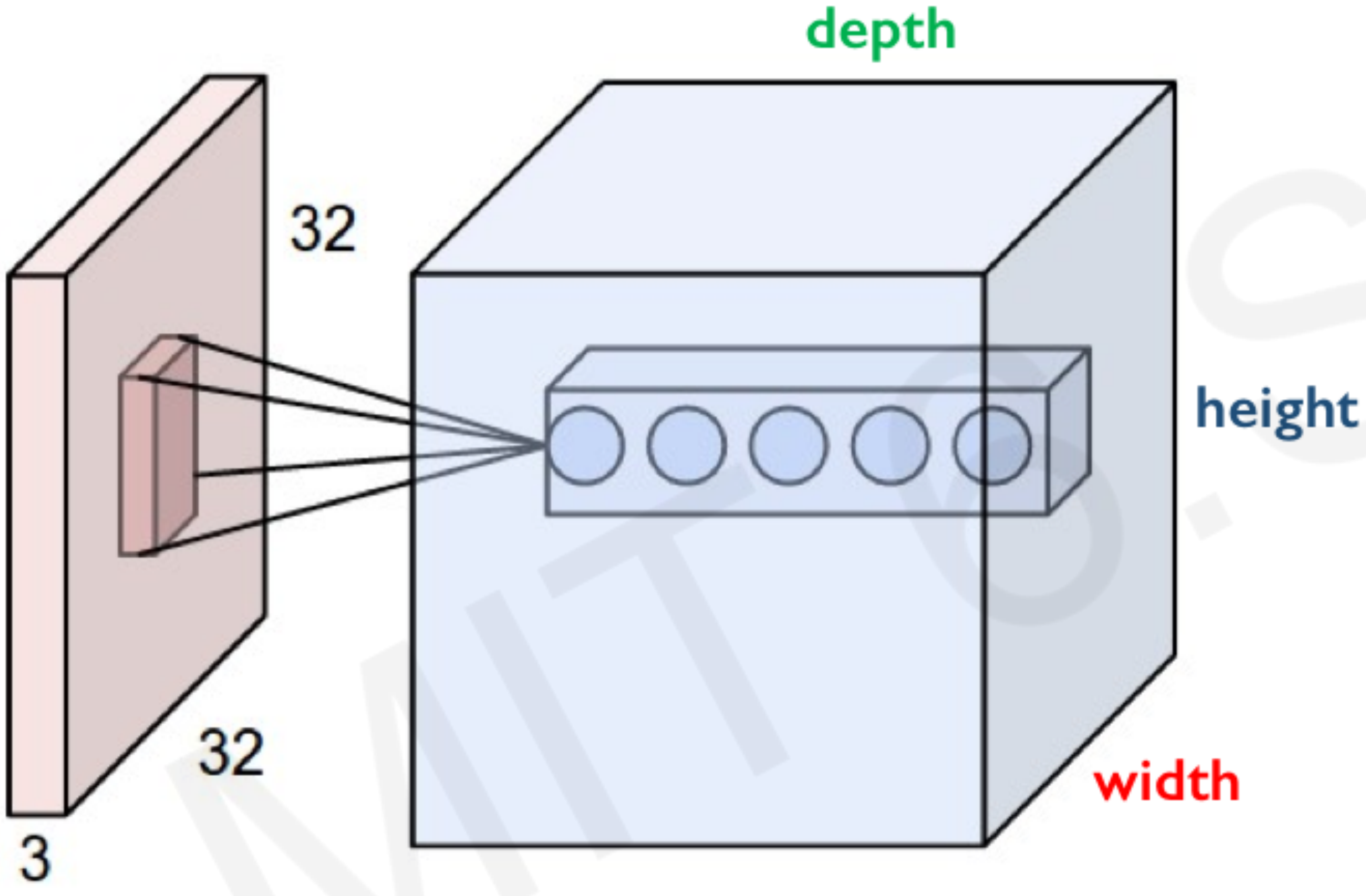


Convolutional layer with four 3x3 filters on a black and white image (just one channel)



Convolutional layer with four 3x3 filters on an RGB image. As you can see, the filters are now cubes, and they are applied on the full depth of the image..

CNNs: Spatial Arrangement of Output Volume



Layer Dimensions:

$h \times w \times d$

where h and w are spatial dimensions
d (depth) = number of filters

Stride:

Filter step size

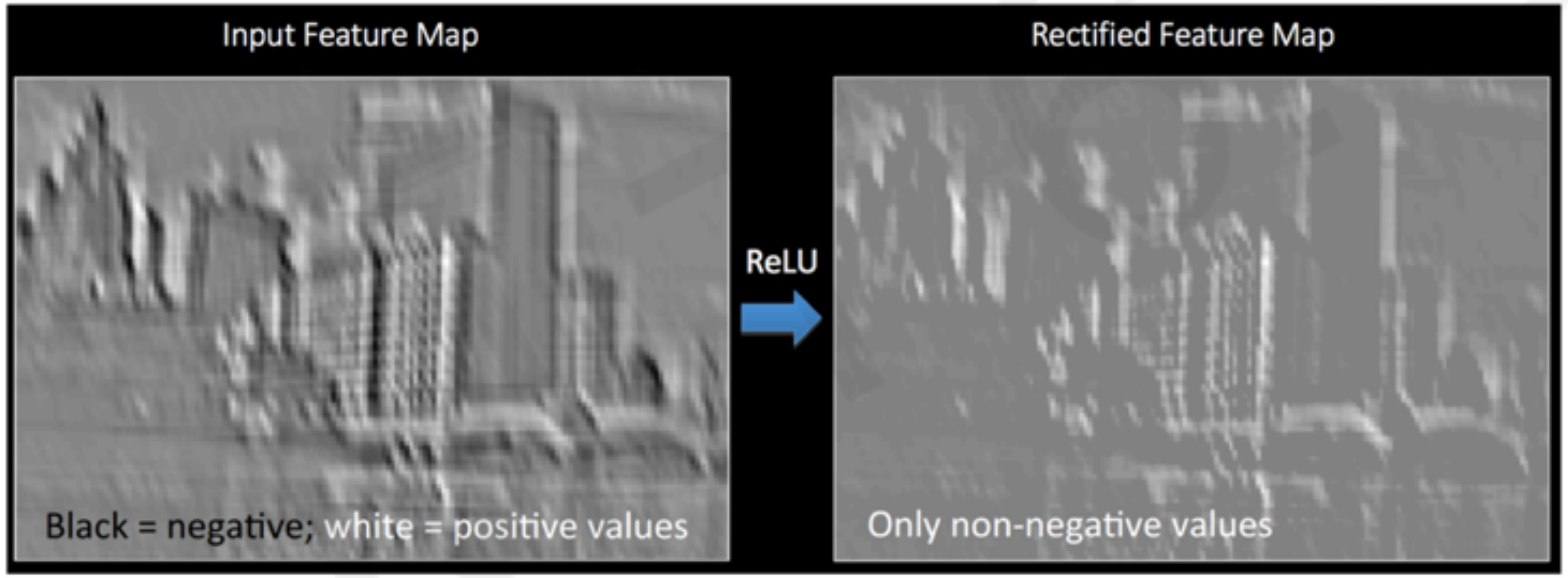
Receptive Field:

Locations in input image that a node is path connected to

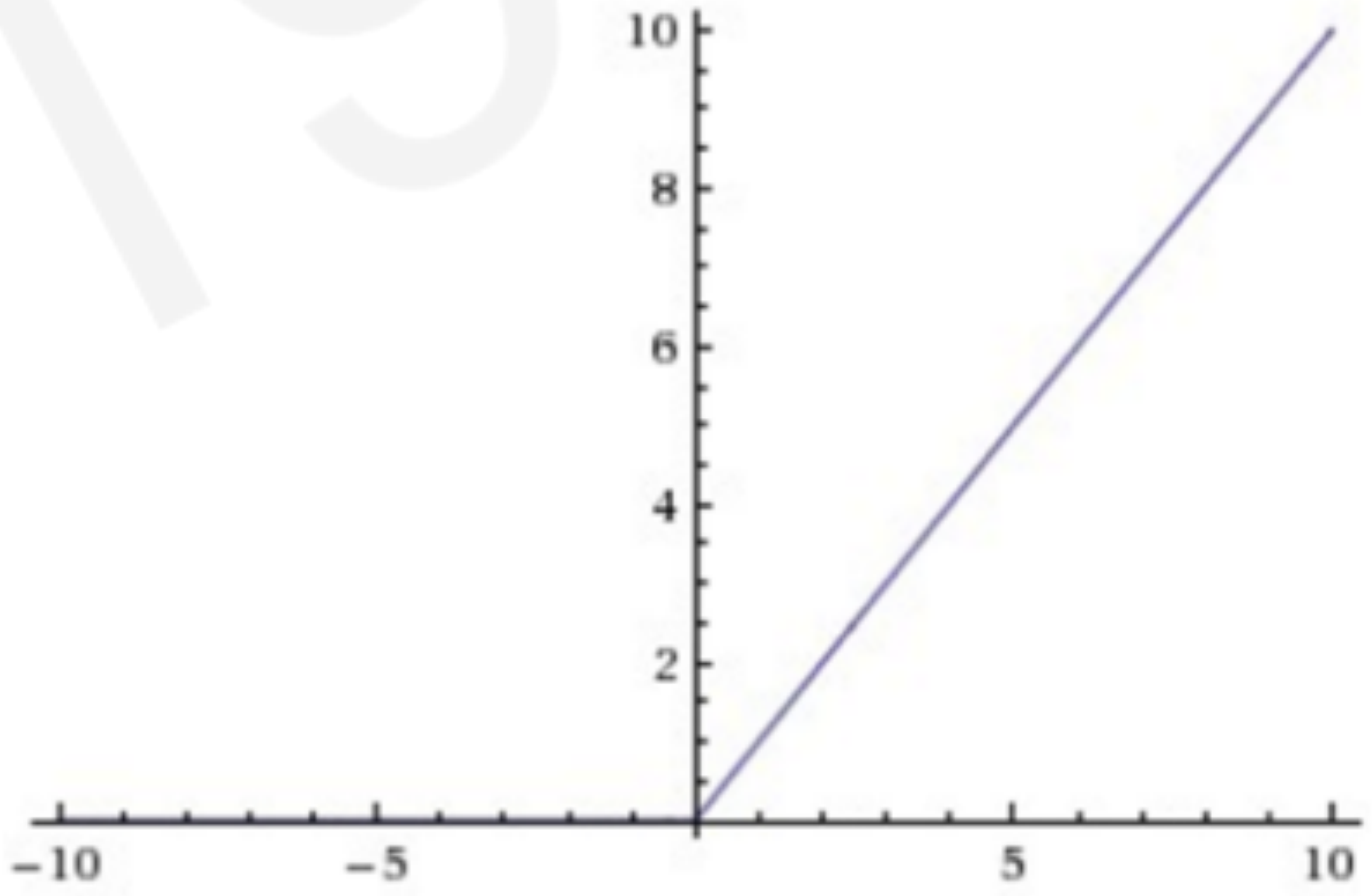
```
tf.keras.layers.Conv2D( filters=d, kernel_size=(h,w), strides=s )
```

Introducing Non-Linearity

- Apply after every convolution operation (i.e., after convolutional layers)
- ReLU: pixel-by-pixel operation that replaces all negative values by zero. **Non-linear operation!**



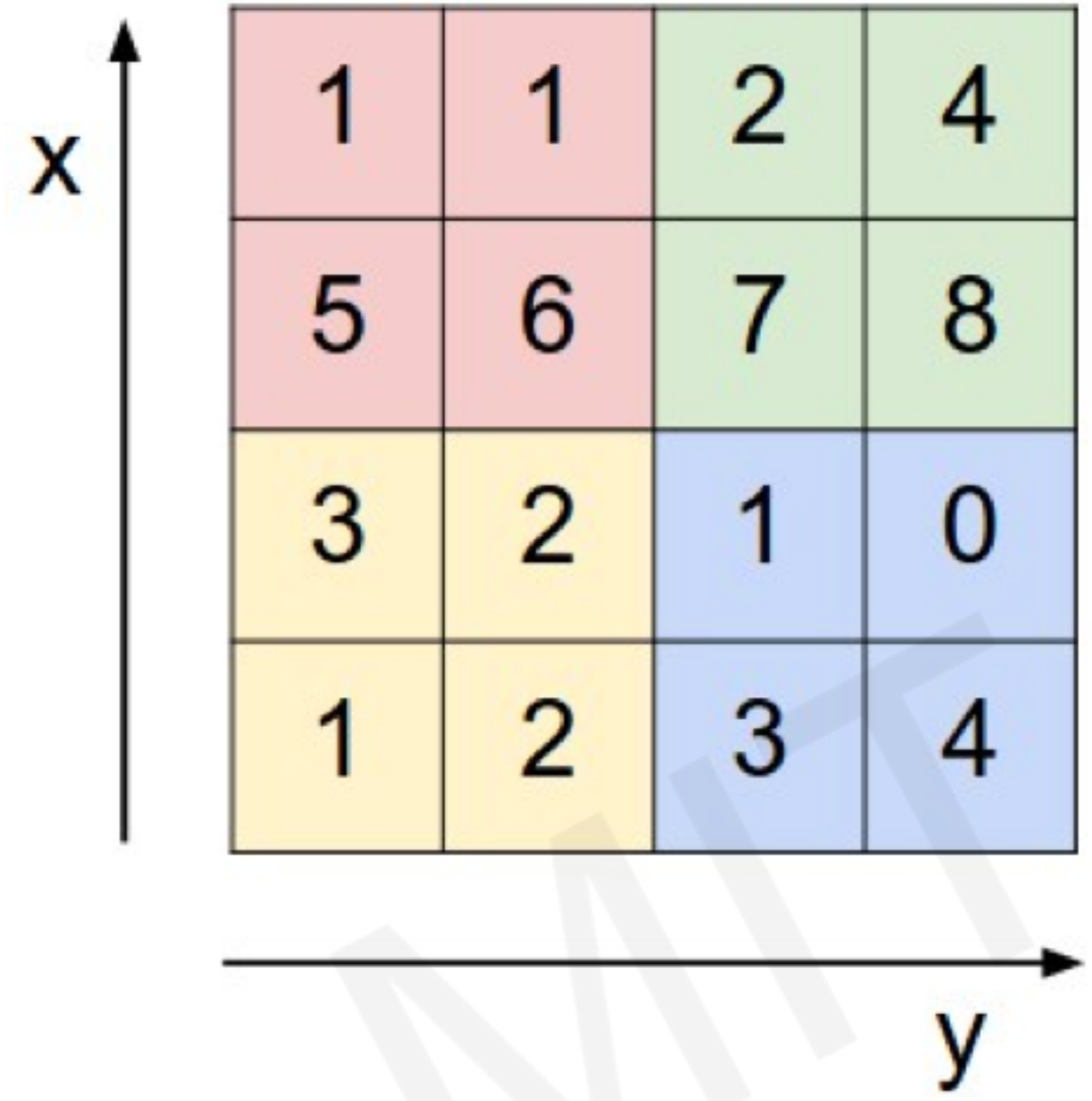
Rectified Linear Unit (ReLU)



$$g(z) = \max(0, z)$$

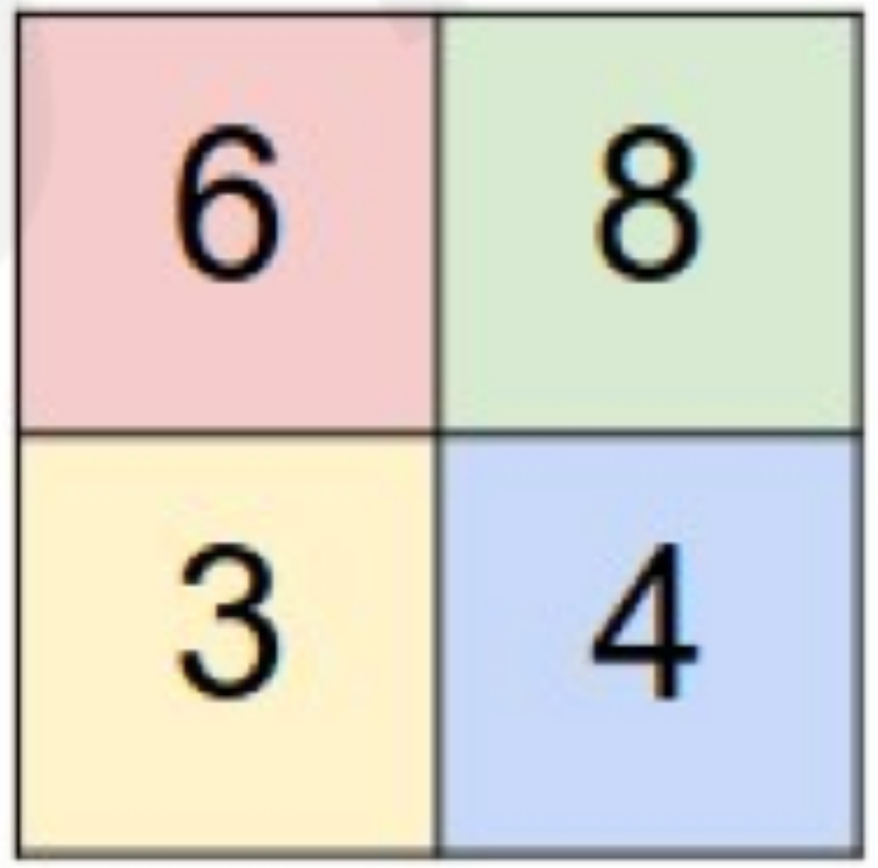
```
tf.keras.layers.ReLU
```

Pooling



max pool with 2x2 filters
and stride 2

```
tf.keras.layers.MaxPool2D(
    pool_size=(2,2),
    strides=2
)
```

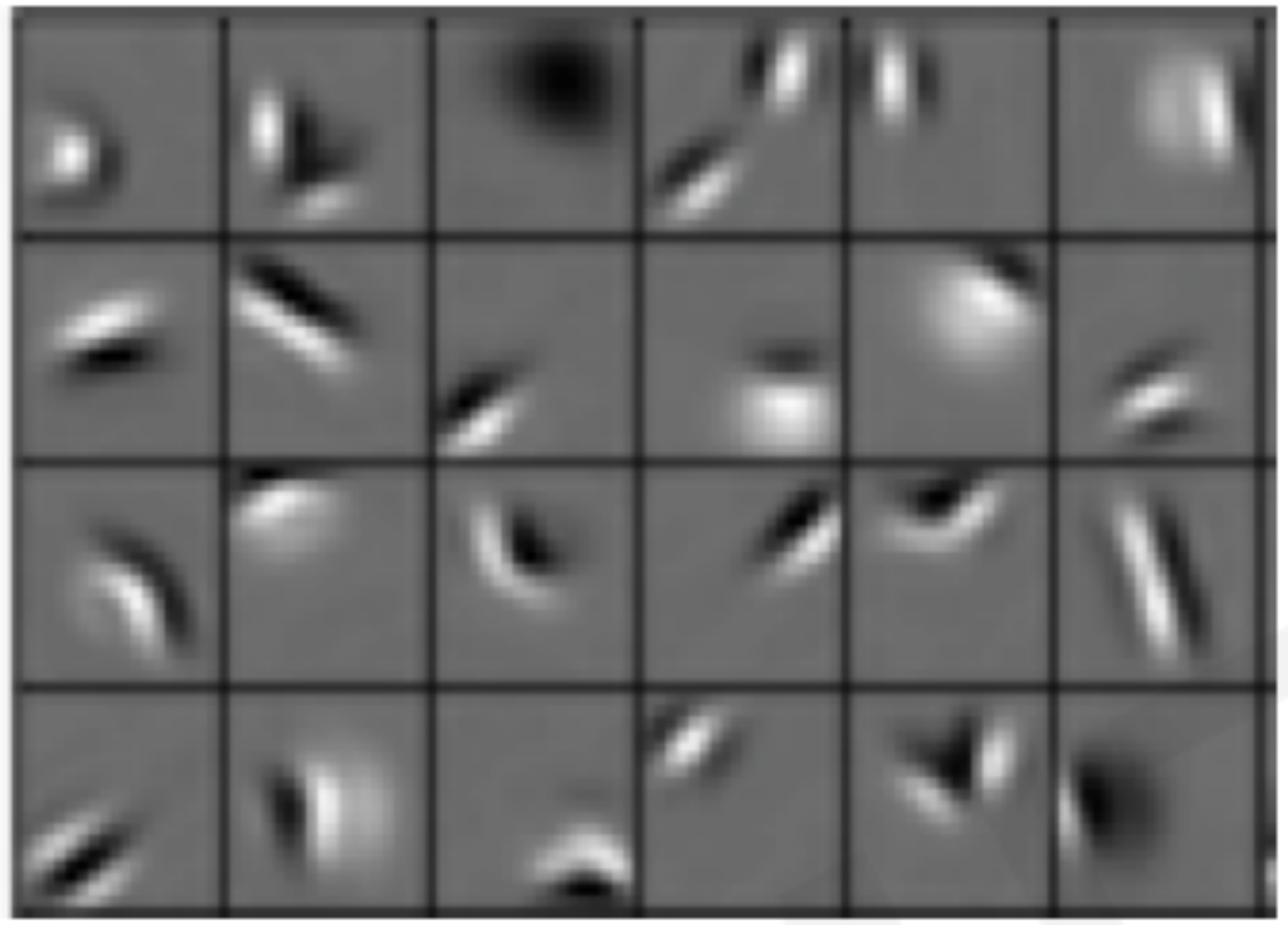


1) Reduced dimensionality
2) Spatial invariance

How else can we downsample and preserve spatial invariance?

Representation Learning in Deep CNNs

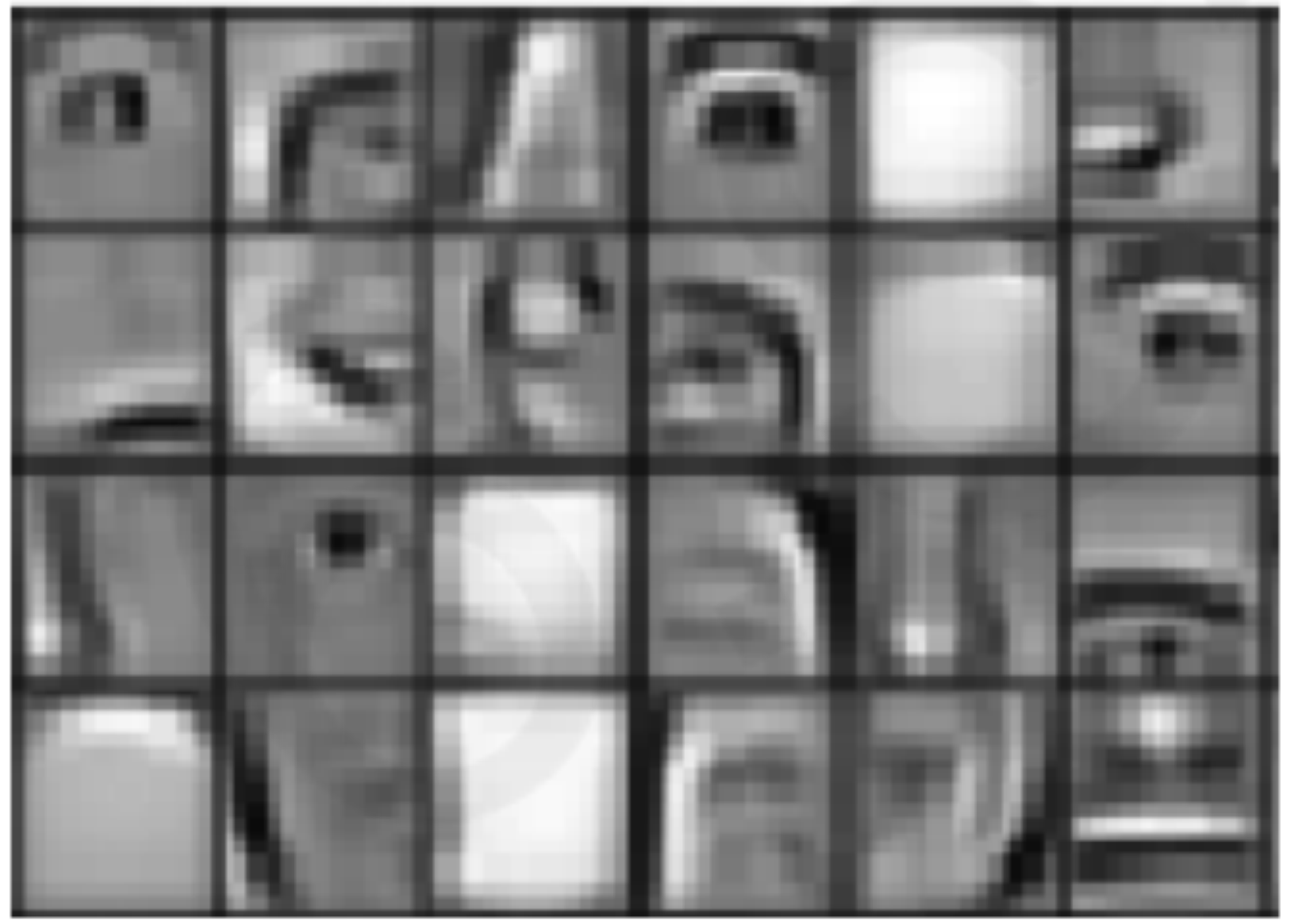
Low level features



Edges, dark spots

Conv Layer 1

Mid level features



Eyes, ears, nose

Conv Layer 2

High level features

Facial structure

Conv Layer 3

CNNs for Classification: Feature Learning

1. Learn features in input image through **convolution**
2. Introduce **non-linearity** through activation function (real-world data is non-linear!)
3. Reduce dimensionality and preserve spatial invariance with **pooling**

CNNs for Classification: Class Probabilities

- CONV and POOL layers output high-level features of input
- Fully connected layer uses these features for classifying input image
- Express output as **probability** of image belonging to a particular class

$$\mathrm{softmax}(y_i) = \frac{e^{y_i}}{\sum_j e^{y_j}}$$

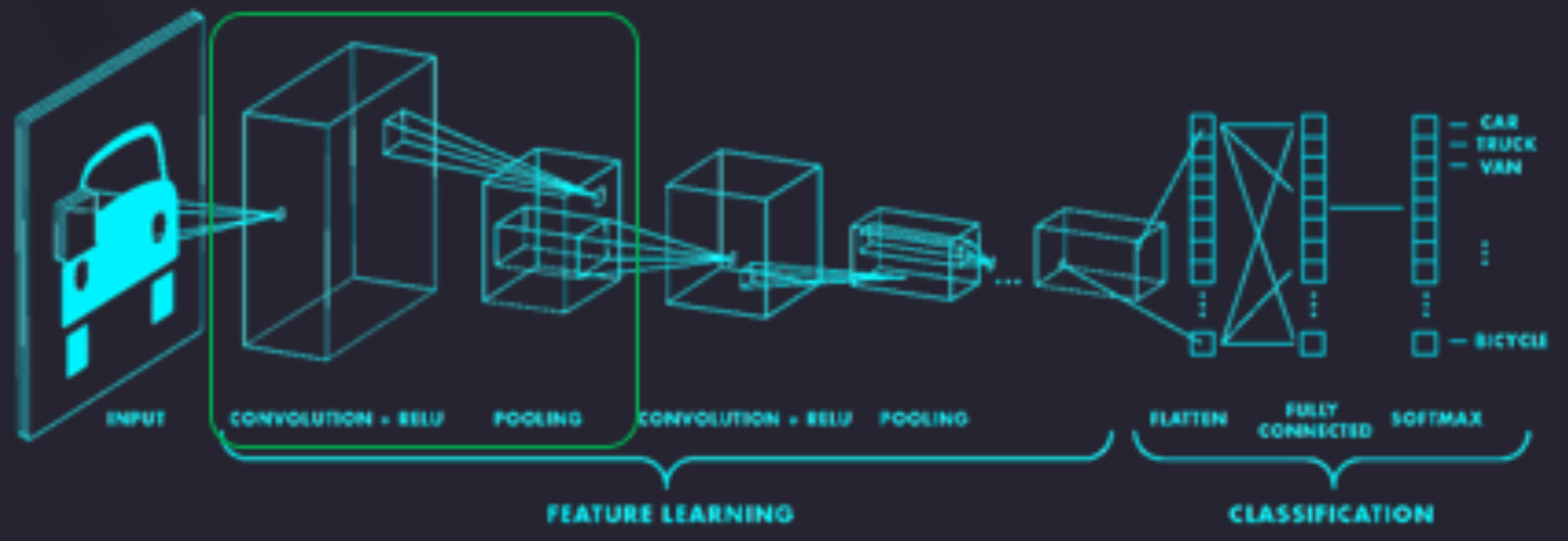
Putting it all together

```
import tensorflow as tf

def generate_model():
    model = tf.keras.Sequential([
      # first convolutional layer
      tf.keras.layers.Conv2D(32, filter_size=3, activation='relu'),
      tf.keras.layers.MaxPool2D(pool_size=2, strides=2),

      # second convolutional layer
      tf.keras.layers.Conv2D(64, filter_size=3, activation='relu'),
      tf.keras.layers.MaxPool2D(pool_size=2, strides=2),

      # fully connected classifier
      tf.keras.layers.Flatten(),
      tf.keras.layers.Dense(1024, activation='relu'),
      tf.keras.layers.Dense(10, activation='softmax')  # 10 outputs
    ])
    return model
```



CNNs for Classification: ImageNet

ImageNet Dataset

Dataset of over 14 million images across 21,841 categories

"Elongated crescent-shaped yellow fruit with soft sweet flesh"

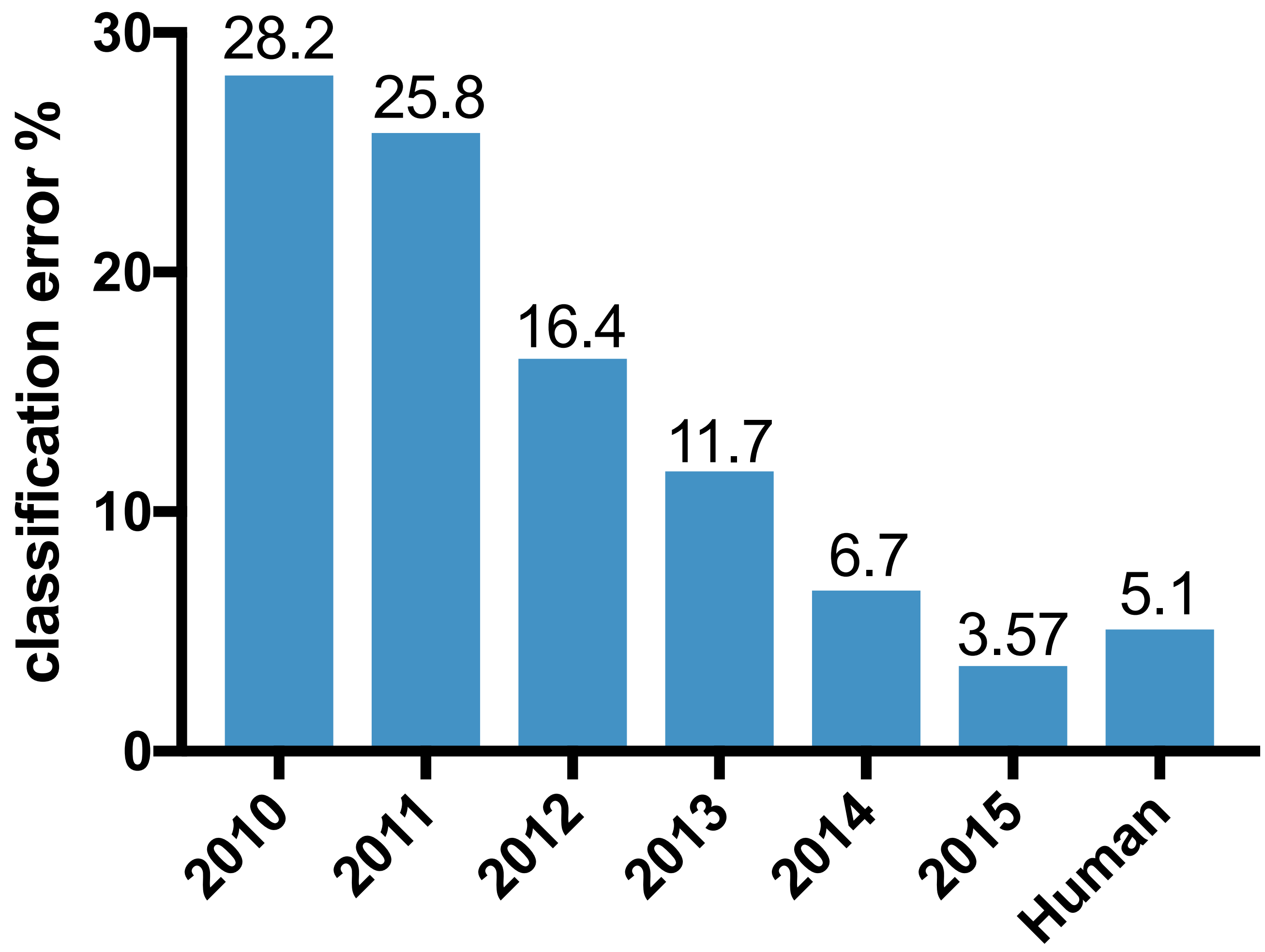
1409 pictures of bananas.

ImageNet Challenge

Classification task: produce a list of object categories present in image. 1000 categories.
"Top 5 error": rate at which the model does not output correct label in top 5 predictions

Other tasks include:
single-object localization, object detection from video/image, scene classification, scene parsing

ImageNet Challenge: Classification Task



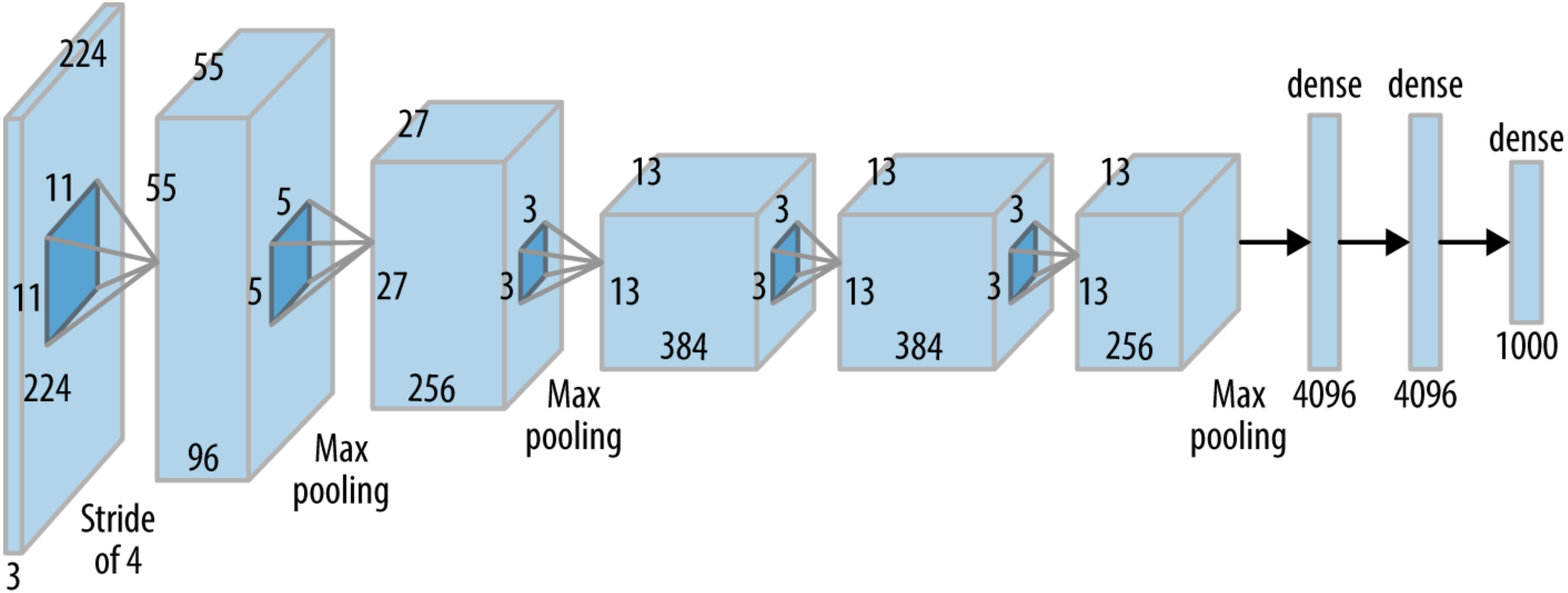
2012: AlexNet. First CNN to win.
- 8 layers, 61 million parameters

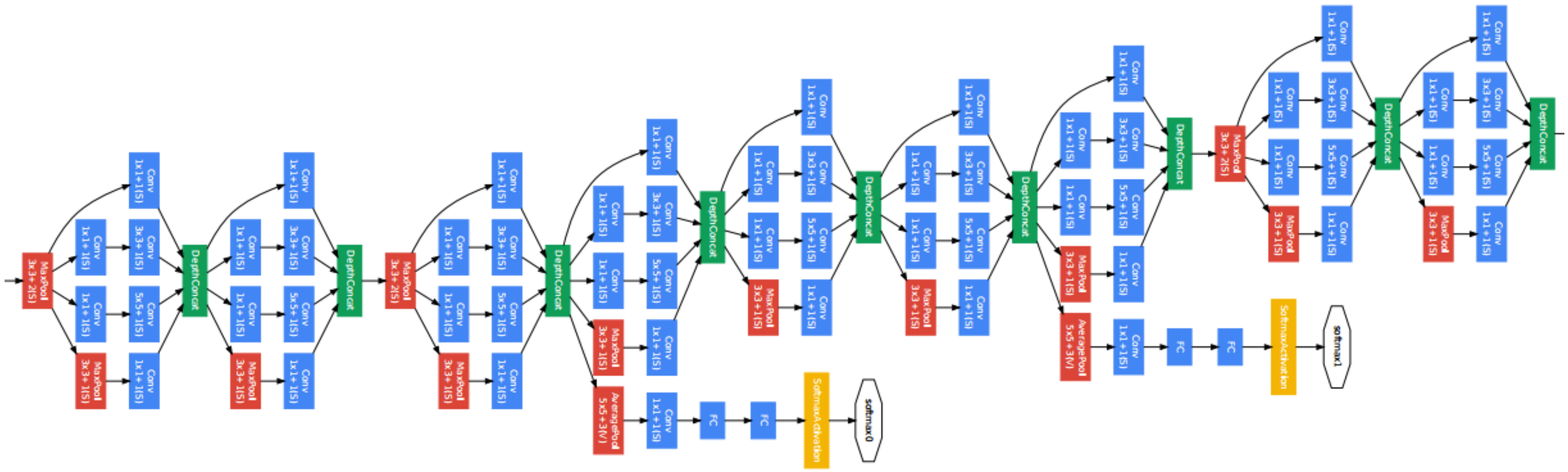
2013: ZFNet
- 8 layers, more filters

2014: VGG
- 19 layers

2014: GoogLeNet
- "Inception" modules
- 22 layers, 5million parameters

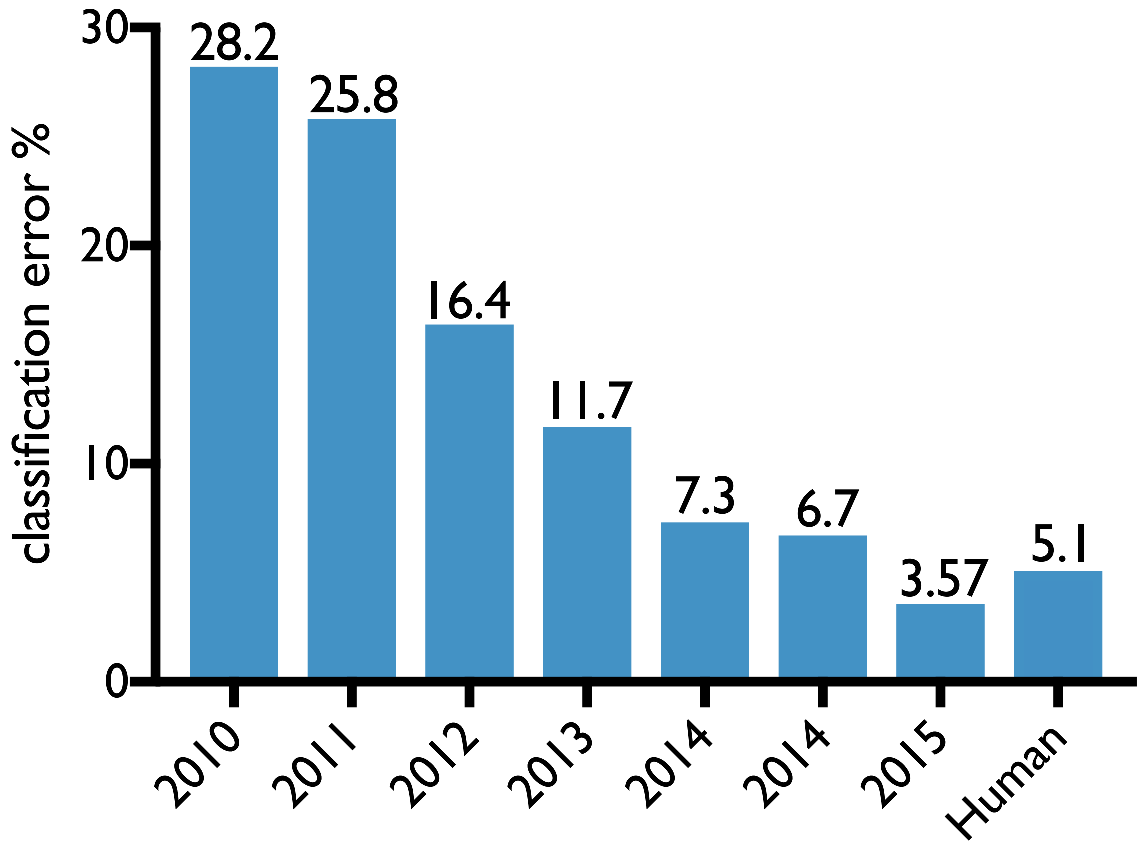
2015: ResNet
- 152 layers

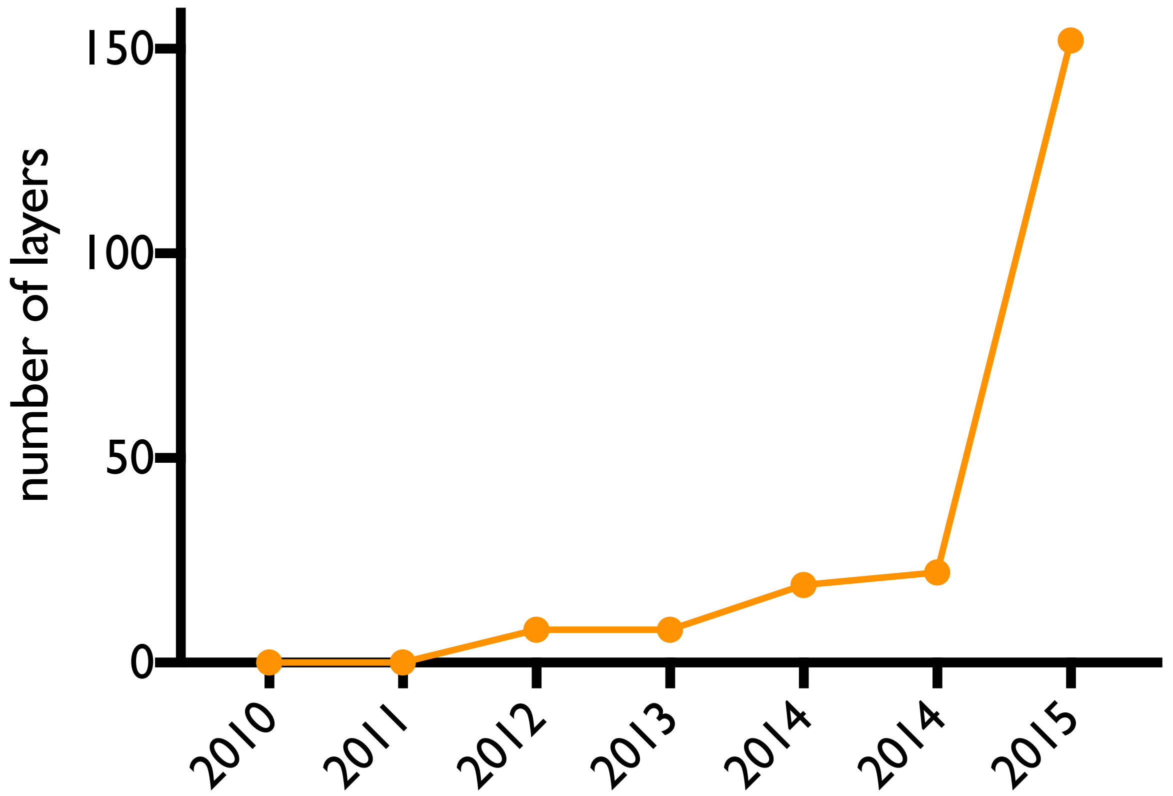

224
224
11
11
3
Stride
of 4
55
55
96
5
5
Max
pooling
27
27
256
3
3
Max
pooling
13
13
384
3
3
13
13
384
3
3
13
13
256
Max
pooling
dense
4096
dense
4096
dense
1000



MaxPool 3x3+2(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
MaxPool 3x3+1(S)
Conv 3x3+1(S)
Conv 5x5+1(S)
Conv 1x1+1(S)
DepthConcat
Conv 1x1+1(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
MaxPool 3x3+1(S)
Conv 3x3+1(S)
Conv 5x5+1(S)
Conv 1x1+1(S)
DepthConcat
MaxPool 3x3+2(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
MaxPool 3x3+1(S)
Conv 3x3+1(S)
Conv 5x5+1(S)
Conv 1x1+1(S)
DepthConcat
AveragePool 5x5+3(V)
Conv 1x1+1(S)
FC
FC
SoftmaxActivation
softmax0
Conv 1x1+1(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
MaxPool 3x3+1(S)
Conv 3x3+1(S)
Conv 5x5+1(S)
Conv 1x1+1(S)
DepthConcat
Conv 1x1+1(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
MaxPool 3x3+1(S)
Conv 3x3+1(S)
Conv 5x5+1(S)
Conv 1x1+1(S)
DepthConcat
Conv 1x1+1(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
MaxPool 3x3+1(S)
Conv 3x3+1(S)
Conv 5x5+1(S)
Conv 1x1+1(S)
DepthConcat
AveragePool 5x5+3(V)
Conv 1x1+1(S)
FC
FC
SoftmaxActivation
softmax1
Conv 1x1+1(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
MaxPool 3x3+1(S)
Conv 3x3+1(S)
Conv 5x5+1(S)
Conv 1x1+1(S)
DepthConcat
MaxPool 3x3+2(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
MaxPool 3x3+1(S)
Conv 3x3+1(S)
Conv 5x5+1(S)
Conv 1x1+1(S)
DepthConcat
Conv 1x1+1(S)
Conv 1x1+1(S)
Conv 1x1+1(S)
MaxPool 3x3+1(S)
Conv 3x3+1(S)
Conv 5x5+1(S)
Conv 1x1+1(S)
DepthConcat

ImageNet Challenge: Classification Task





An Architecture for Many Applications

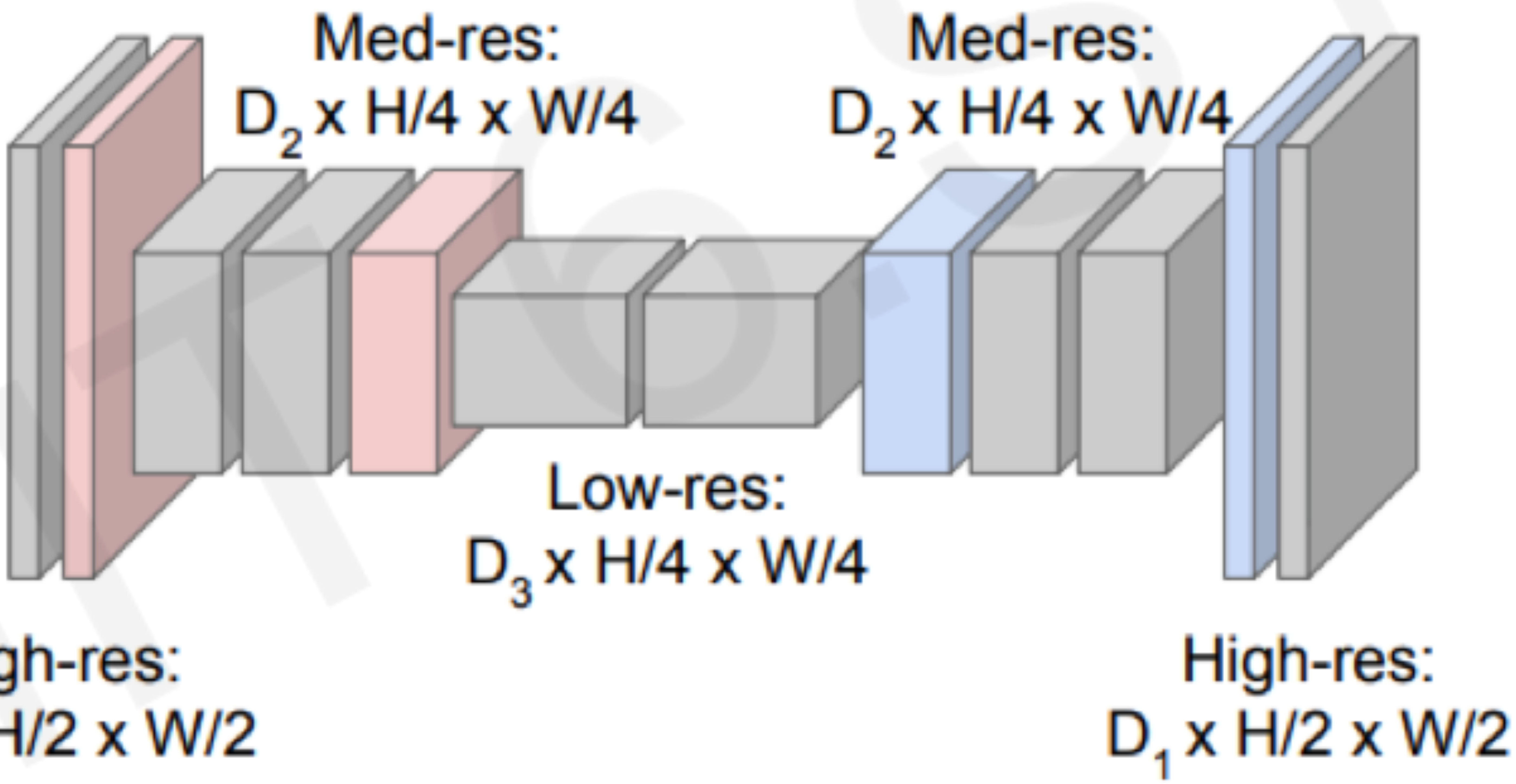
An Architecture for Many Applications

Detection
Semantic segmentation
End-to-end robotic control

Deep Learning for Computer Vision: Impact

Semantic Segmentation: Fully Convolutional Networks

FCN: Fully Convolutional Network.
Network designed with all convolutional layers,
with **downsampling** and **upsampling** operations



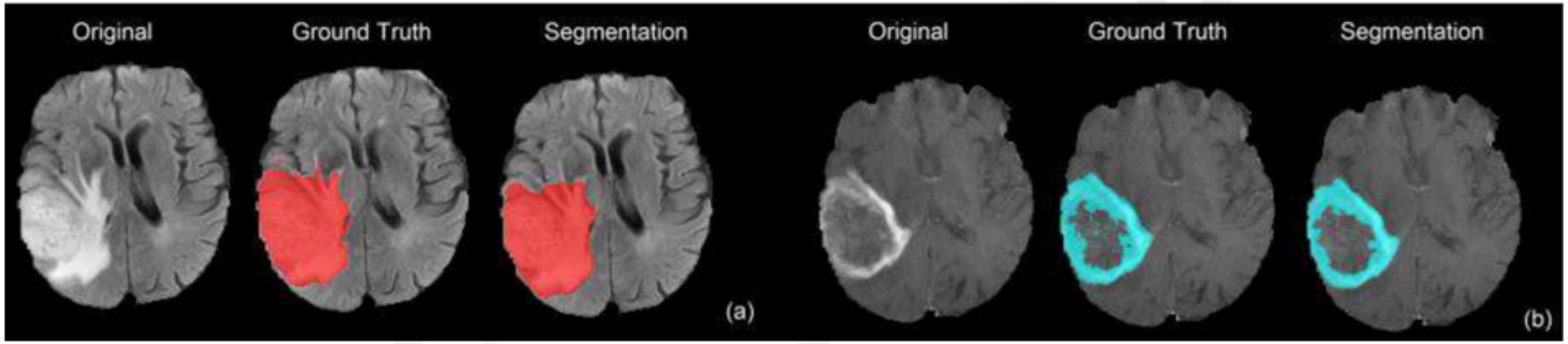
Input:
3 x H x W

Predictions:
H x W

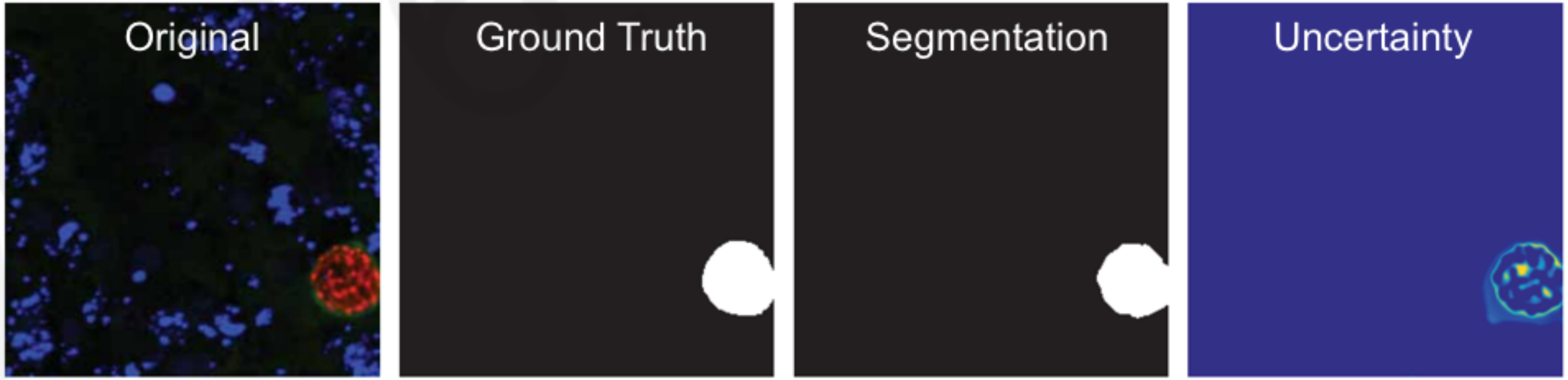
`tf.keras.layers.Conv2DTranspose`

Semantic Segmentation: Biomedical Image Analysis

Brain Tumors
Dong+ *MIUA* 2017.



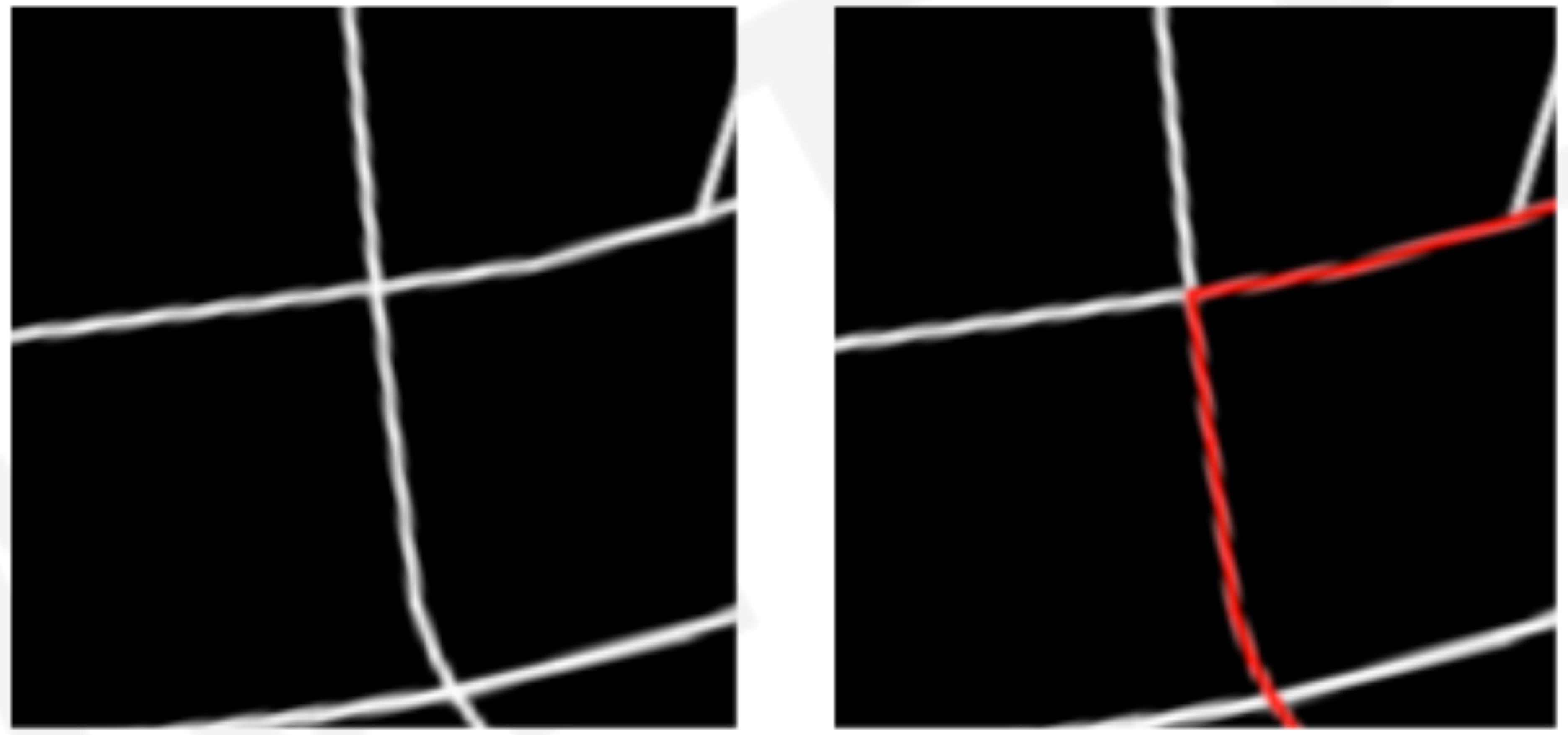
Malaria Infection
Soleimany+ *arXiv* 2019.



Self-Driving Cars: Navigation from Visual Perception

Raw Perception
I
(ex. camera)

Coarse Maps
M
(ex. GPS)



Possible Control Commands

End-to-End Framework for Autonomous Navigation

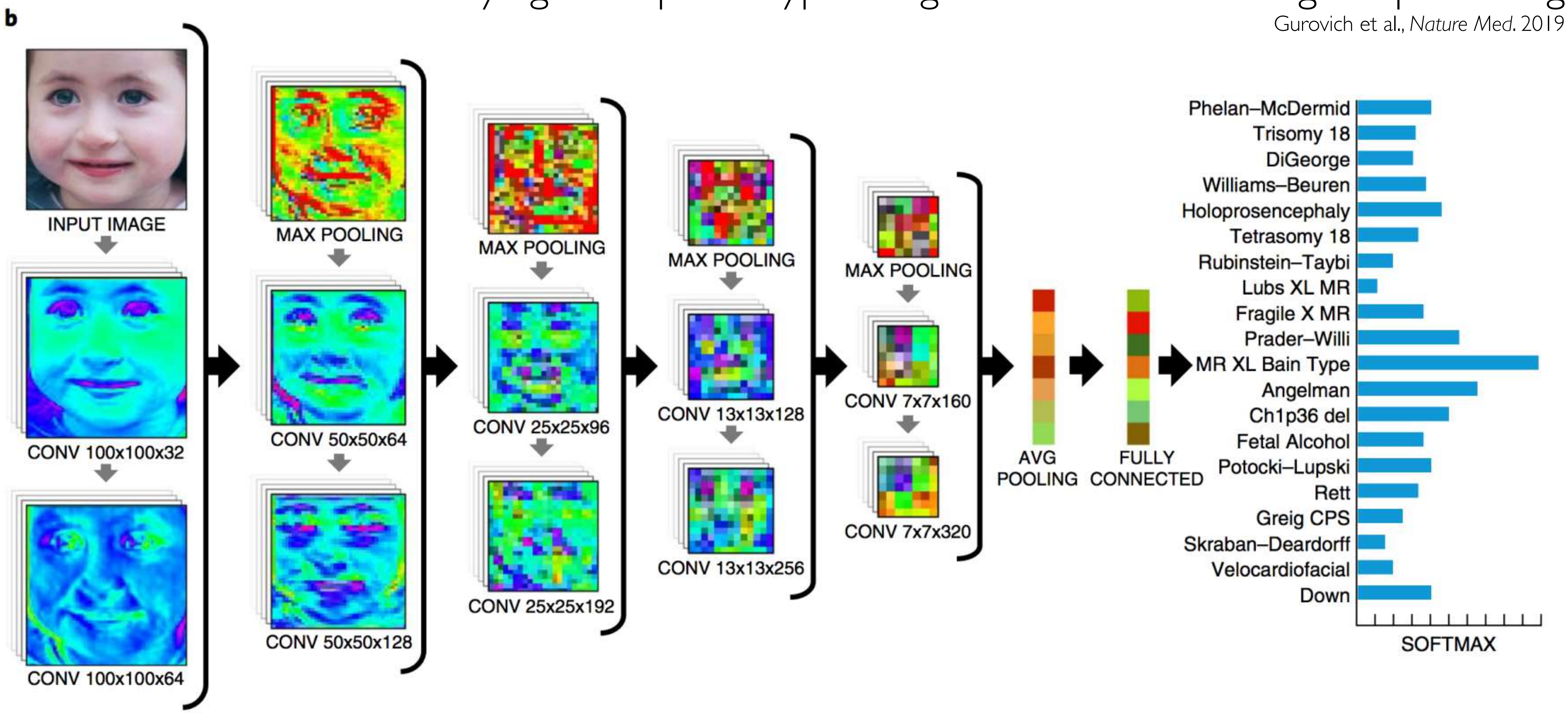
Entire model is trained end-to-end **without any human labelling or annotations**


Auto ON
Navigation and Localization
Amini+ ICRA 2019.

Impact: Healthcare

Identifying facial phenotypes of genetic disorders using deep learning

Gurovich et al., *Nature Med.* 2019



USER & ENTITY BEHAVIOR ANALYTICS (UEBA)

MACHINE LEARNING DRIVEN **BEHAVIOR ANALYTICS** IS A NEW WAY TO **COMBAT ATTACKERS**

1. **Machine driven, not only human driven**
2. **Detect compromised users, not only attackers**
3. **Post-infection detection, not only prevention**

REAL WORLD NEWS WORTHY EXAMPLES

COMPROMISED

40 million credit cards were stolen
from Target's severs

STOLEN CREDENTIALS

Edward Snowden stole more than 1.7 million
classified documents

INTENDED TO LEAK INFORMATION

NEGLIGENT

DDoS attack from 10M+ hacked home
devices took down major websites

ALL USED THE SAME PASSWORD

REAL WORLD ATTACKS CAUGHT

SCANNING ATTACK

scan servers in the data center to find out vulnerable targets

DETECTED WITH
Active Directory (AD) LOGS

DATA DOWNLOAD

download data from internal document repository which is not typical for the host

DETECTED WITH **NETWORK TRAFFIC**

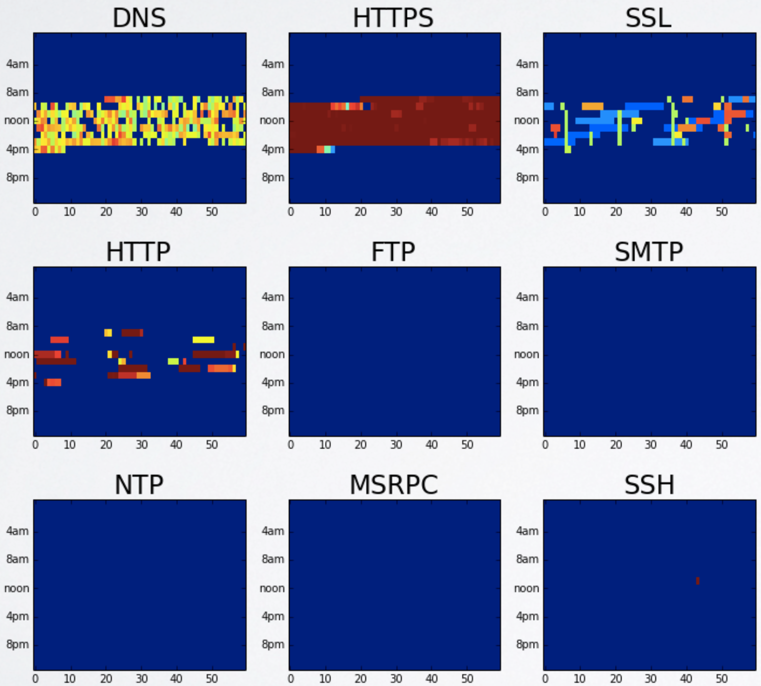
EXFILTRATION OF DATA

upload a large file to cloud server hosted in new country never accessed before

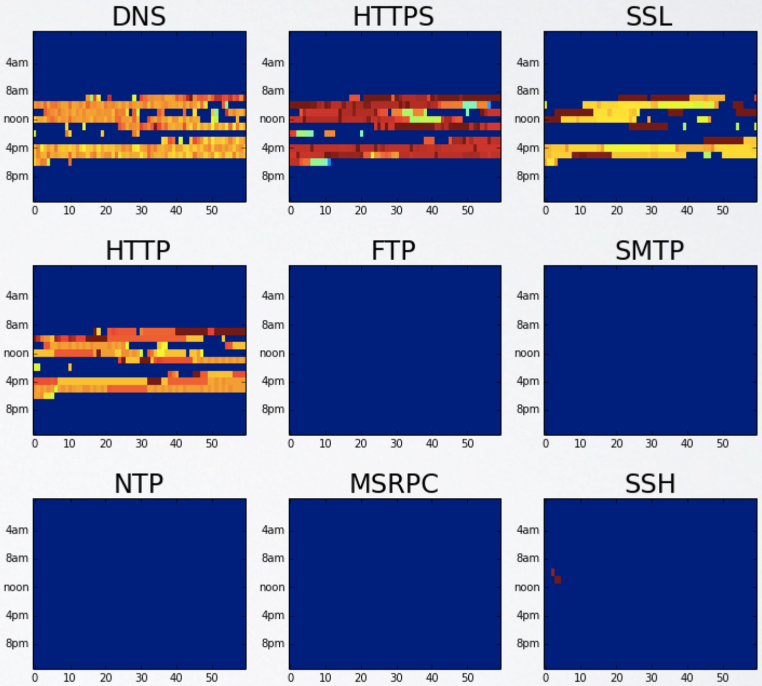
DETECTED WITH **WEB PROXY LOGS**

BEHAVIOR ENCODING USERS

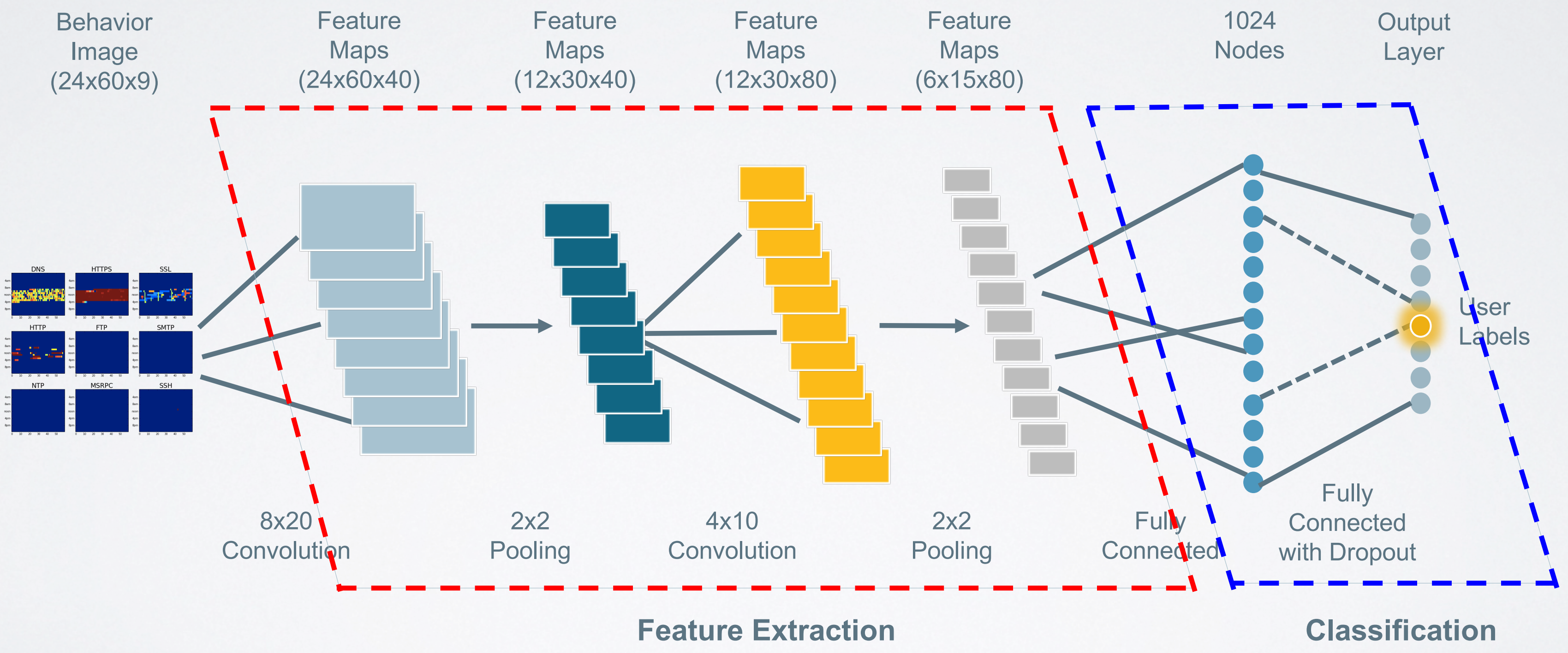
User 1



User 2

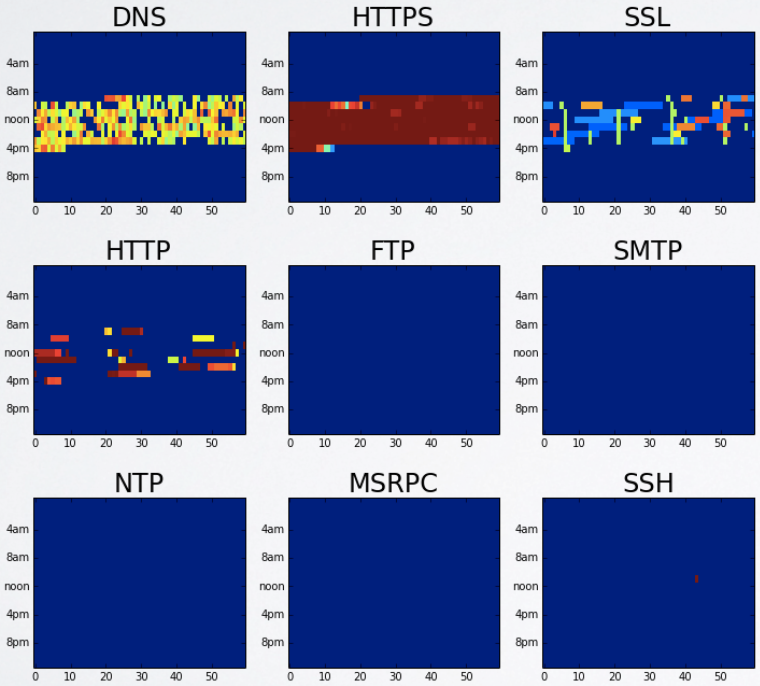


ANOMALY DETECTION CONVOLUTIONAL NEURAL NETWORK (CNN)

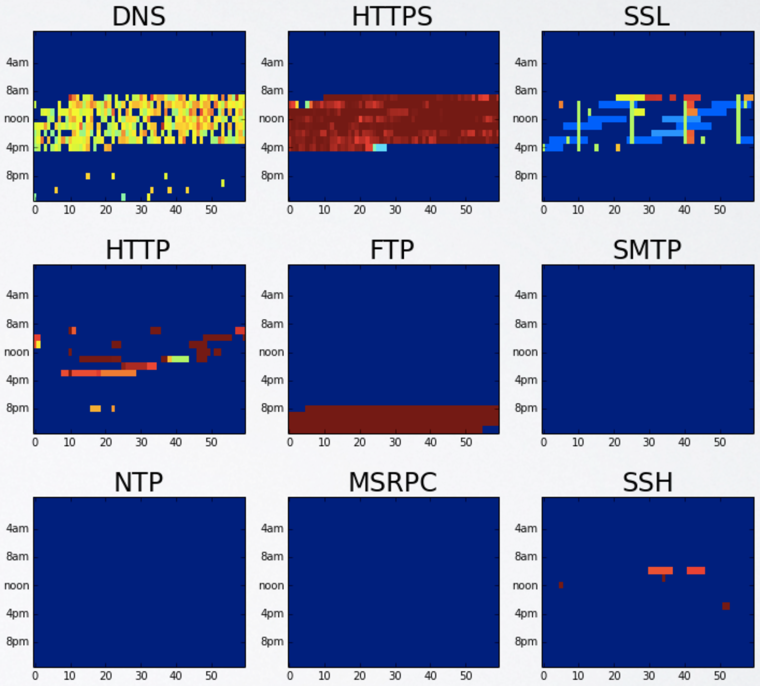


BEHAVIOR ANOMALY USER | EXFILTRATION

User – Before Compromise

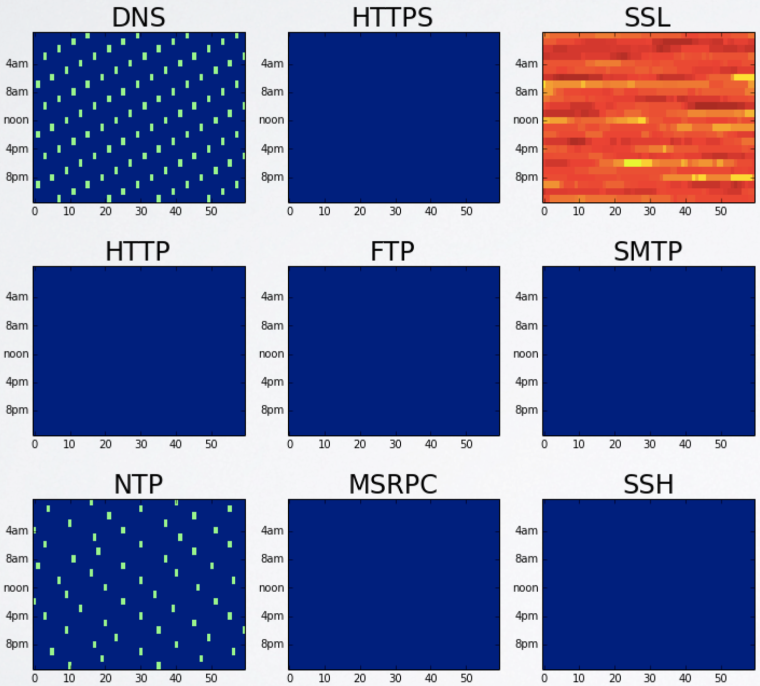


User – Post Compromise

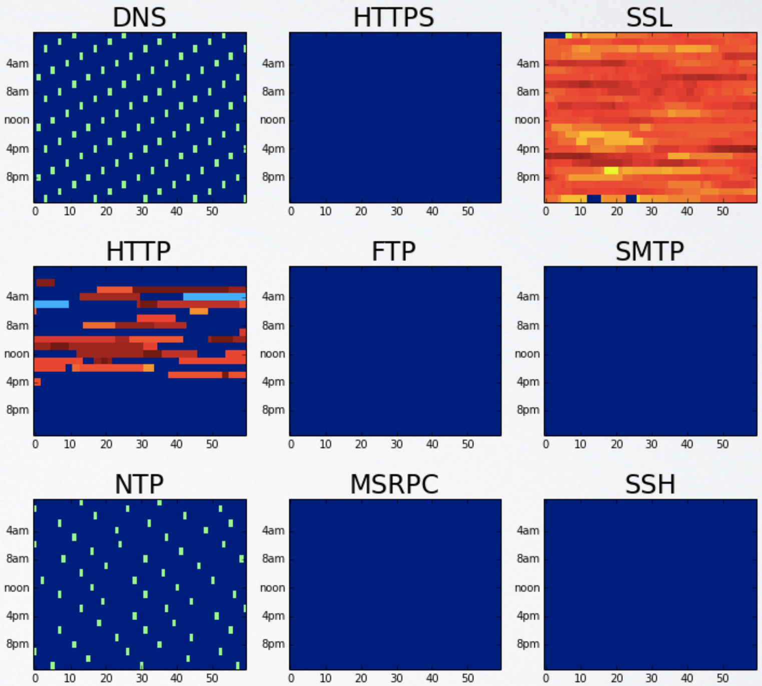


BEHAVIOR ANOMALY IOT DEVICE | DATA DOWNLOAD

Dropcam – Before Compromise



Dropcam – Post Compromise



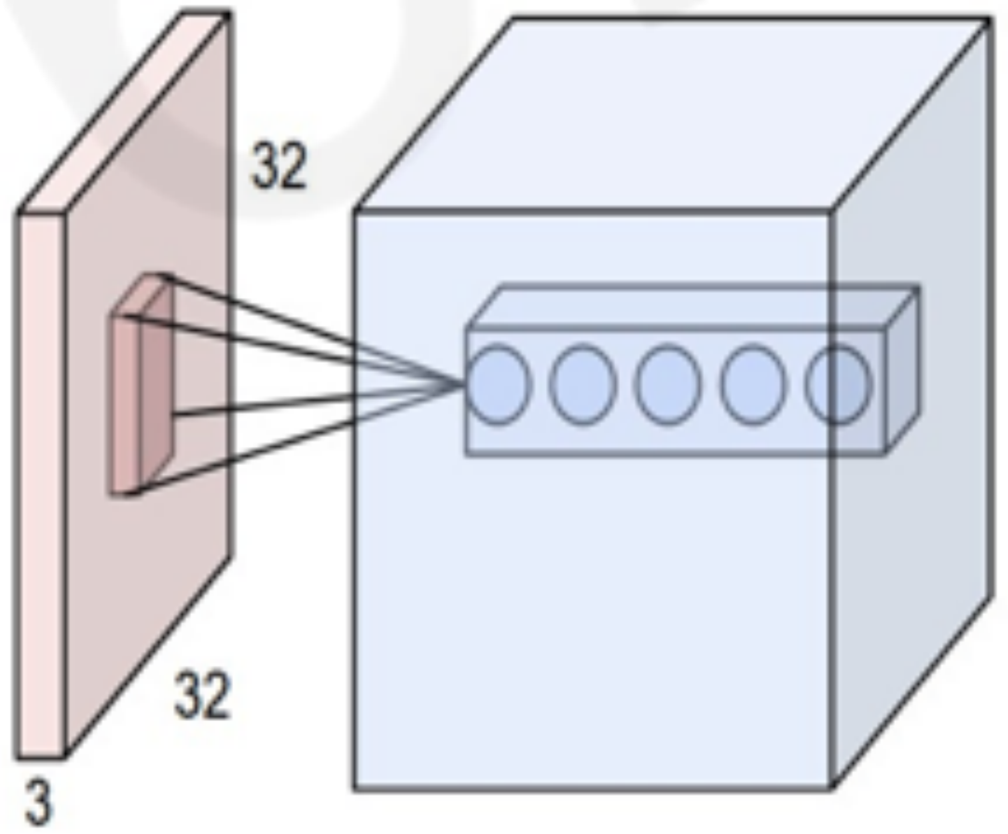
Deep Learning for Computer Vision: Summary

Foundations

- Why computer vision?
- Representing images
- Convolutions for feature extraction

CNNs

- CNN architecture
- Application to classification
- ImageNet



Applications

- Segmentation, image captioning, control
- Security, medicine, robotics